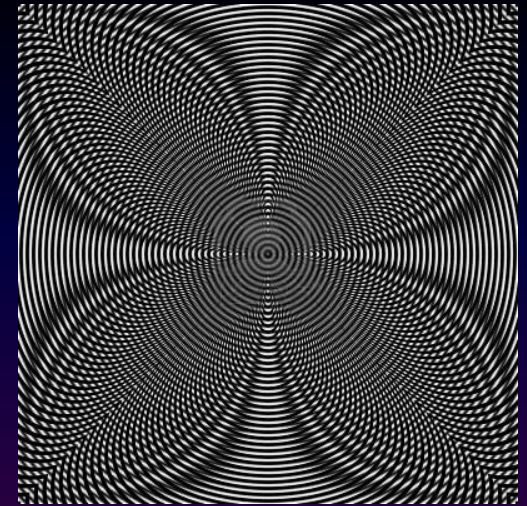




**Ciências  
ULisboa**



# 2D Sampling: characteristics, difficulties and applications

**José Manuel Rebordão**

# Summary

Sampling is a fundamental part of any measurement, one of the "arts" of physics. Within the signal (one-dimensional, 1D, typically time) sampling is a well-controlled process. At two spatial dimensions (images, 2D) and at three dimensions (volumes, 3D), one is often confronted with unknown objects or symmetry-shaped objects that become evident as spatial resolution increases, and it is possible to obtain results of the measurement that can either describe reality or can be artifacts generated by the measurement process.

On the other hand, we are increasingly dealing with information presented to us through displays of various technologies, or generated through dynamic scanning processes. Due to their periodic or quasi-periodic nature, such mathematical objects do not always make possible the natural application of Shannon's theorem, confronting us with the need to perform other forms of analysis.

The aim of this seminar is to draw attention - without major formal elaborations - to a wide range of artifacts that typically arise in image manipulation, and from which various applications derive, using either their stability or their unique nature and instability.

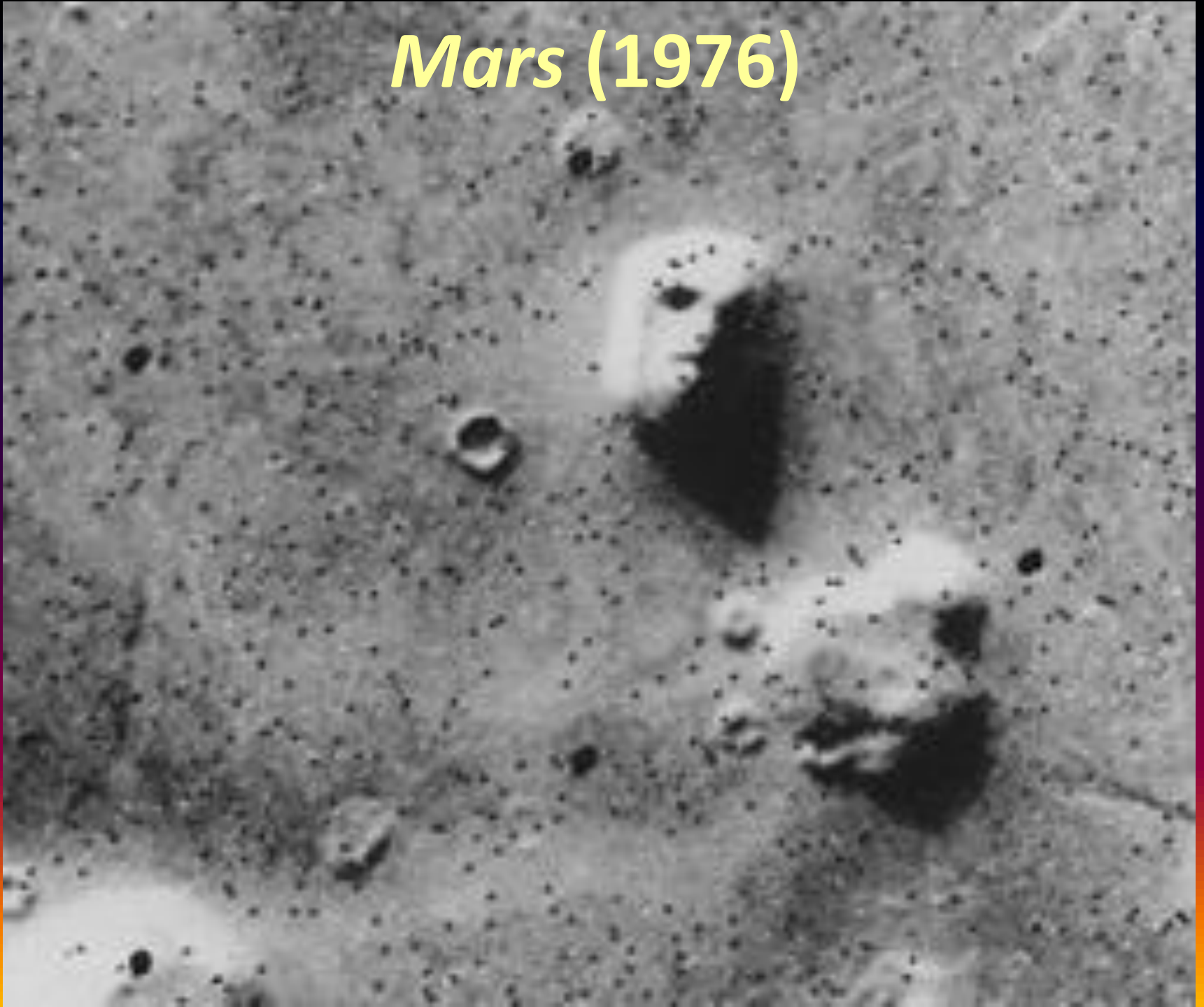
# Sumário

As estratégias de amostragem constituem uma parte fundamental de qualquer processo de medição, uma das "artes" da Física. No âmbito do sinal (unidimensional, 1D, tipicamente o tempo), a amostragem é um processo bem controlado. A duas dimensões espaciais (imagens, 2D) e a 3 dimensões (volumes, 3D), é-se muitas vezes confrontado com objectos desconhecidos ou possuidores de formas de simetria que se põem em evidência à medida que a resolução espacial aumenta, e não é difícil obterem-se resultados do processo de medida que tanto podem descrever a realidade como podem perfeitamente ser artefactos gerados pelo processo de medida.

Por outro lado, cada vez mais lidamos com informação que nos é apresentada através de "displays" de diversas tecnologias, ou gerada através de processos dinâmicos de varrimento. Pela sua natureza periódica ou quase-periódica, tais objectos matemáticos nem sempre viabilizam a aplicação natural do teorema de Shannon, confrontando-nos com a necessidade de recorrer a outras formas de análise.

Este seminário tem assim como objectivo chamar a atenção - sem grandes elaborações formais - para uma gama variada de artefactos que tipicamente surgem na manipulação de imagens, e das quais decorrem aplicações diversas que beneficiam quer da sua estabilidade, quer da sua natureza singular e instabilidade.

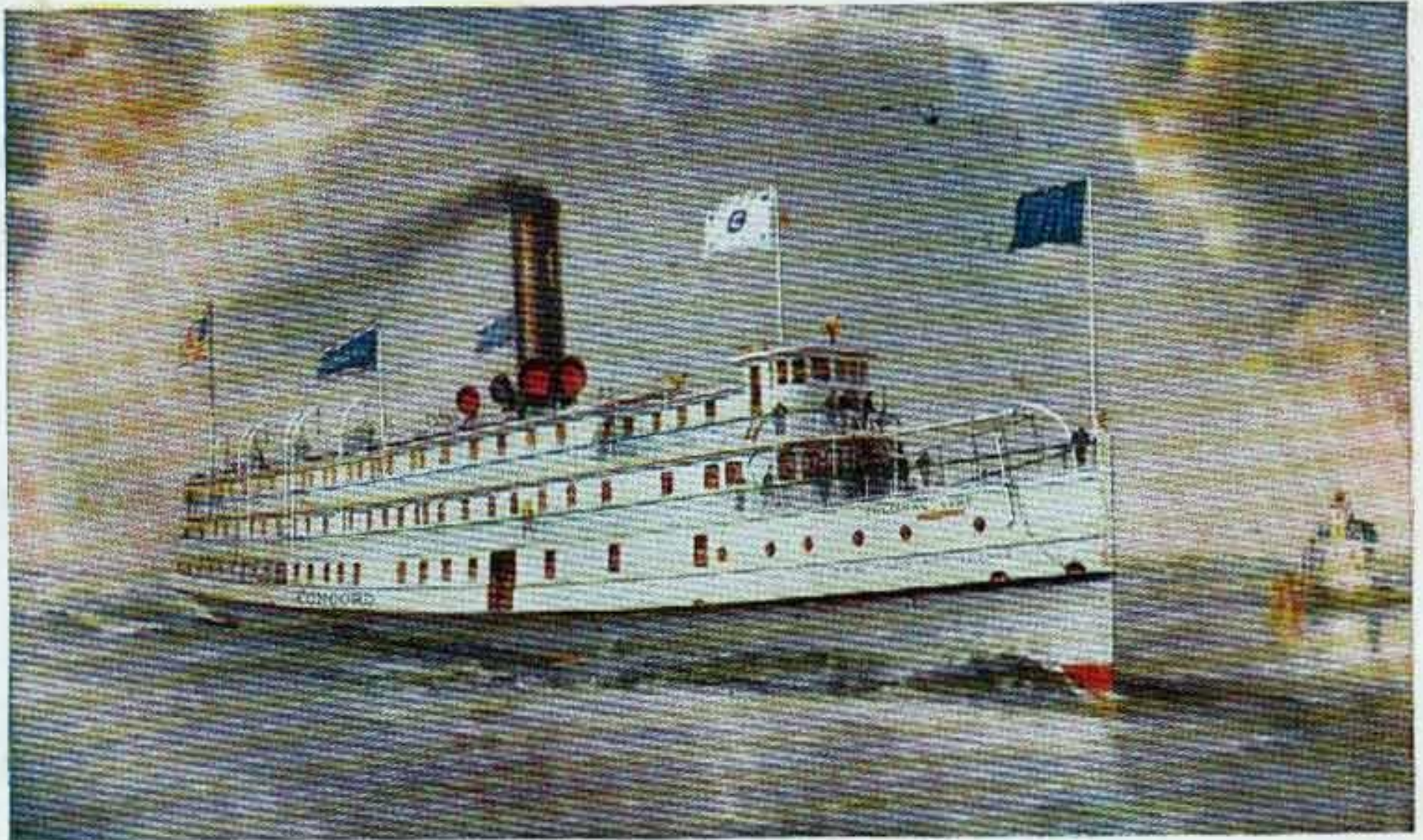
# *Mars (1976)*





# Common points among ...

COLONIAL NAVIGATION COMPANY



BETWEEN NEW YORK AND NEW ENGLAND









# TV





# Yankee stadium in Bronx, New York

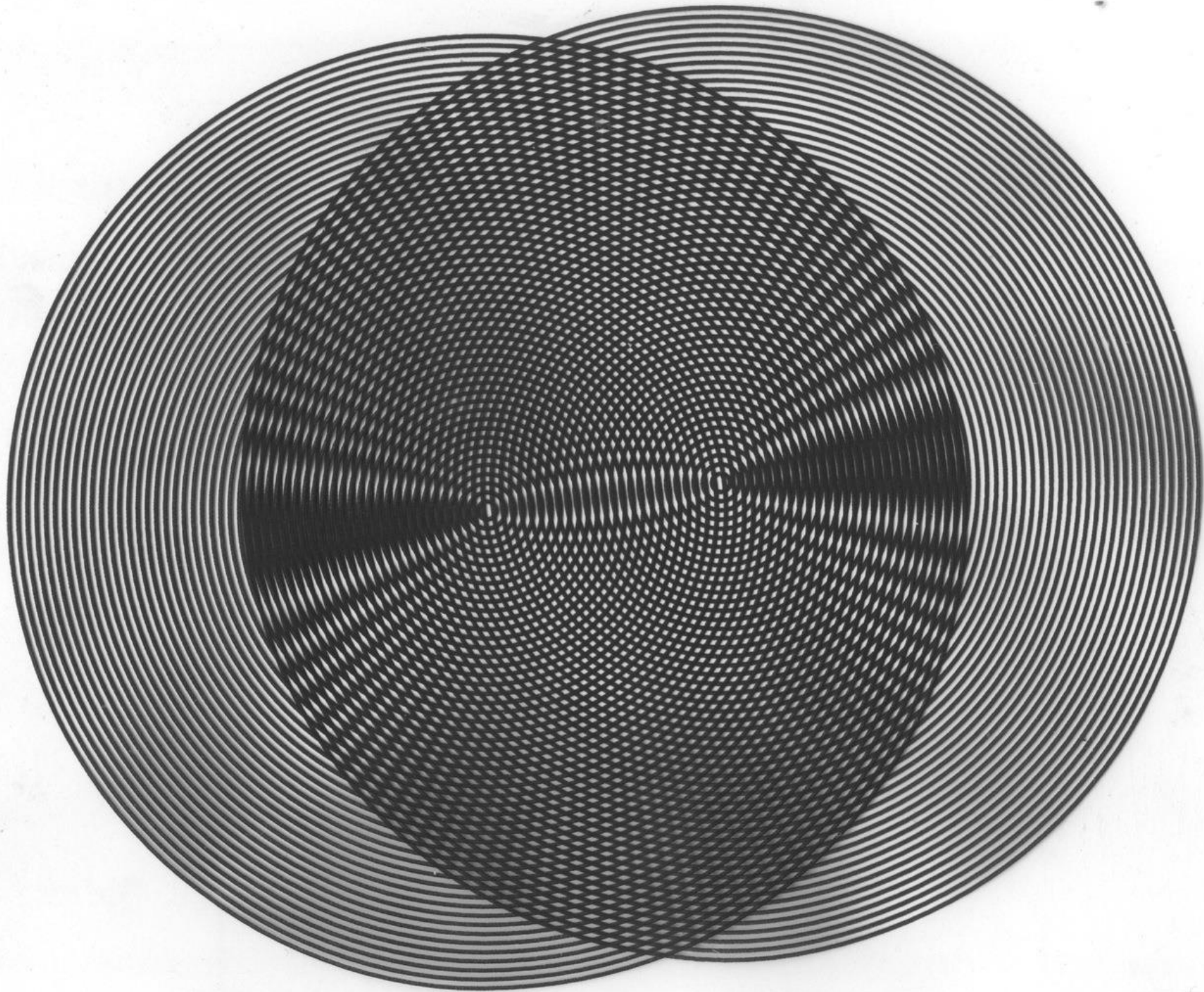


78 m

Image © 2007 Sanborn

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# In common, previously:

- Handling periodic or quasi-periodic patterns
- General sampling theory in 1D, 2D (3D)
- **2D / 3D sampling**
  - Representation / Interpolation
- **Metrology and measurement**
  - Matrix sensors
  - Matricial scanning
  - Measurement: a filtered “reality”
  - New measurement measurement (Moiré, ...)
    - All scales, from nano to macro
- ***Displays , scanners & copiers***
  - Artifacts
- **Sistems**
  - Aligment (integrated circuits, offset printing)
- **Security**
  - Protection / Coding / Decoding / Zoom / ...

# 2D models

- A 2D image / pattern (monochromatic) can be represented by:
  - Reflectance function,  $r_i(x,y)$
  - Transmittance function
- Image **superposition** can be modelled:
  - **Multiplicative**
  - Additive

$$r(x,y) = r_1(x,y) \cdot \dots \cdot r_m(x,y)$$



Fourier transform

$$R(u,v) = R_1(u,v) ** \dots ** R_m(u,v)$$




# \*\* → Convolution

- Convolution:

$$f(x, y) ** g(x, y) = \iint_{-\infty}^{+\infty} f(u, v) g(x - u, y - v) du dv$$

- Different from Correlation:

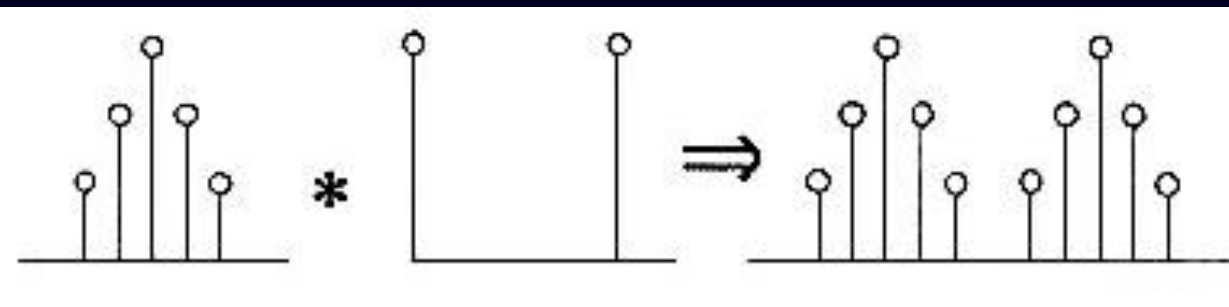
$$f(x, y) \otimes \otimes g(x, y) = \iint_{-\infty}^{+\infty} f(u, v) g(u - x, v - y) du dv$$


- Convolution theorem:

$$h = f ** g \rightarrow \text{TF}(h) = \text{TF}(f) \cdot \text{TF}(g)$$

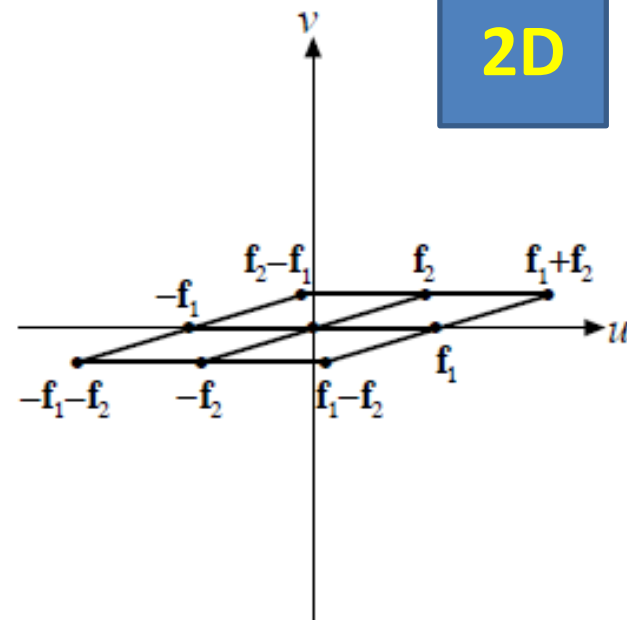
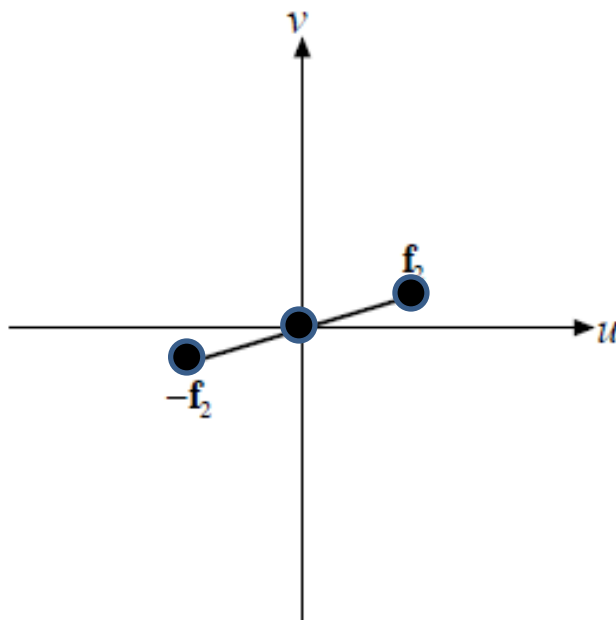
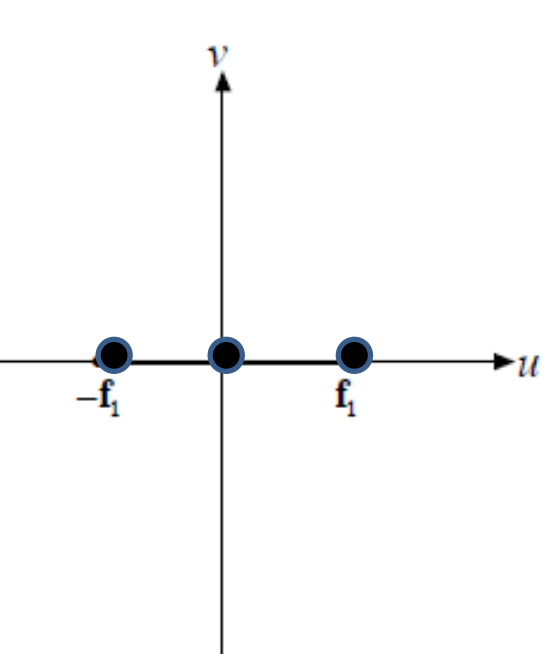
$$h = f \cdot g \rightarrow \text{TF}(h) = \text{TF}(f) ** \text{TF}(g)$$

# \*\* → Convolution

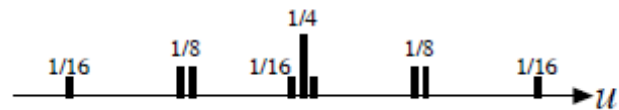
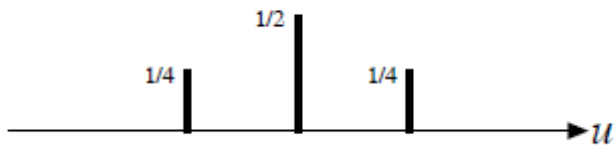
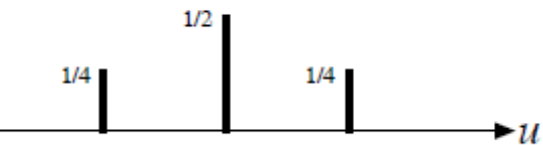


$$f(x, \lambda) ** g(x, \lambda) = \int_{-\infty}^{+\infty} f(\sigma, \lambda) g(x - \sigma, \lambda - \lambda) d\sigma d\lambda$$

1D

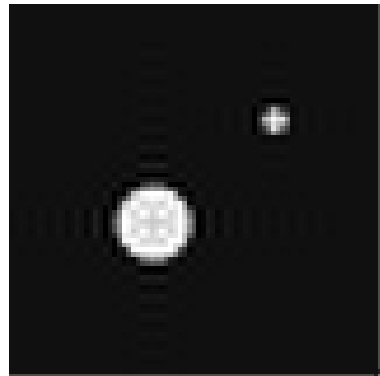


2D



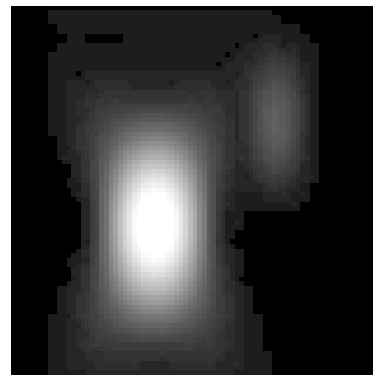
# \*\*\* → Convolution in 2D

$$f(x,y) ** g(x,y) = \iint_{-\infty}^{+\infty} f(u,v)g(x-u,y-v)dudv$$



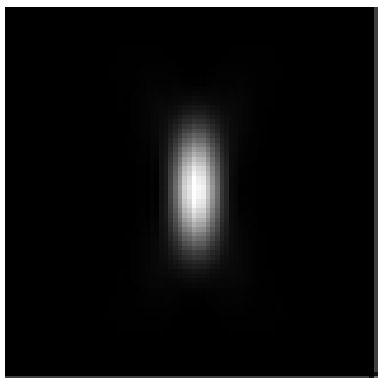
Object

\*\*\*



$$\text{Image} = \text{Object} ** \text{PSF}$$

PSF = Point Spread Function



PSF

2D

\*\*\*

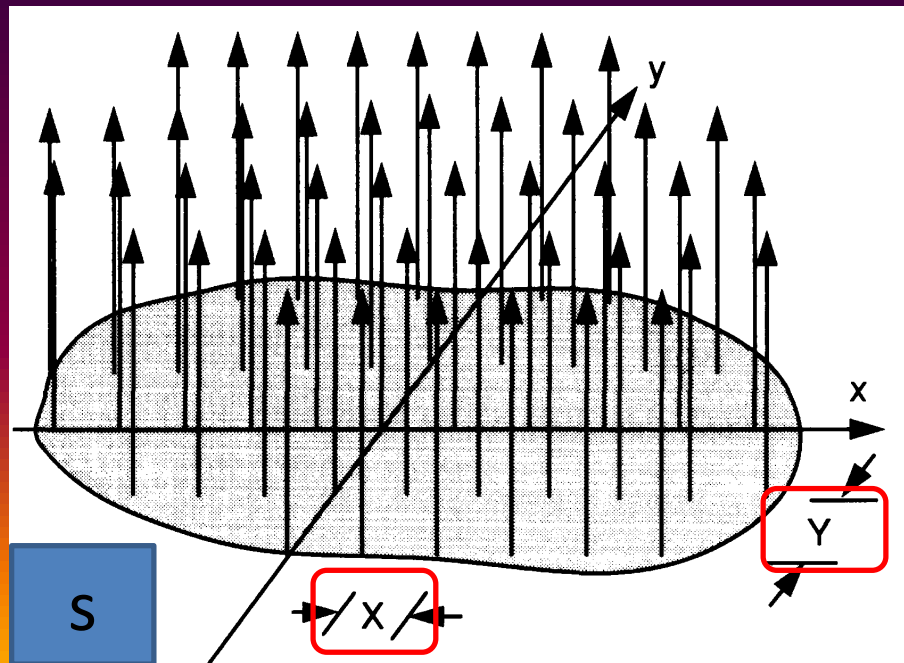
# Sampling

Point sampling is a multiplicative process:

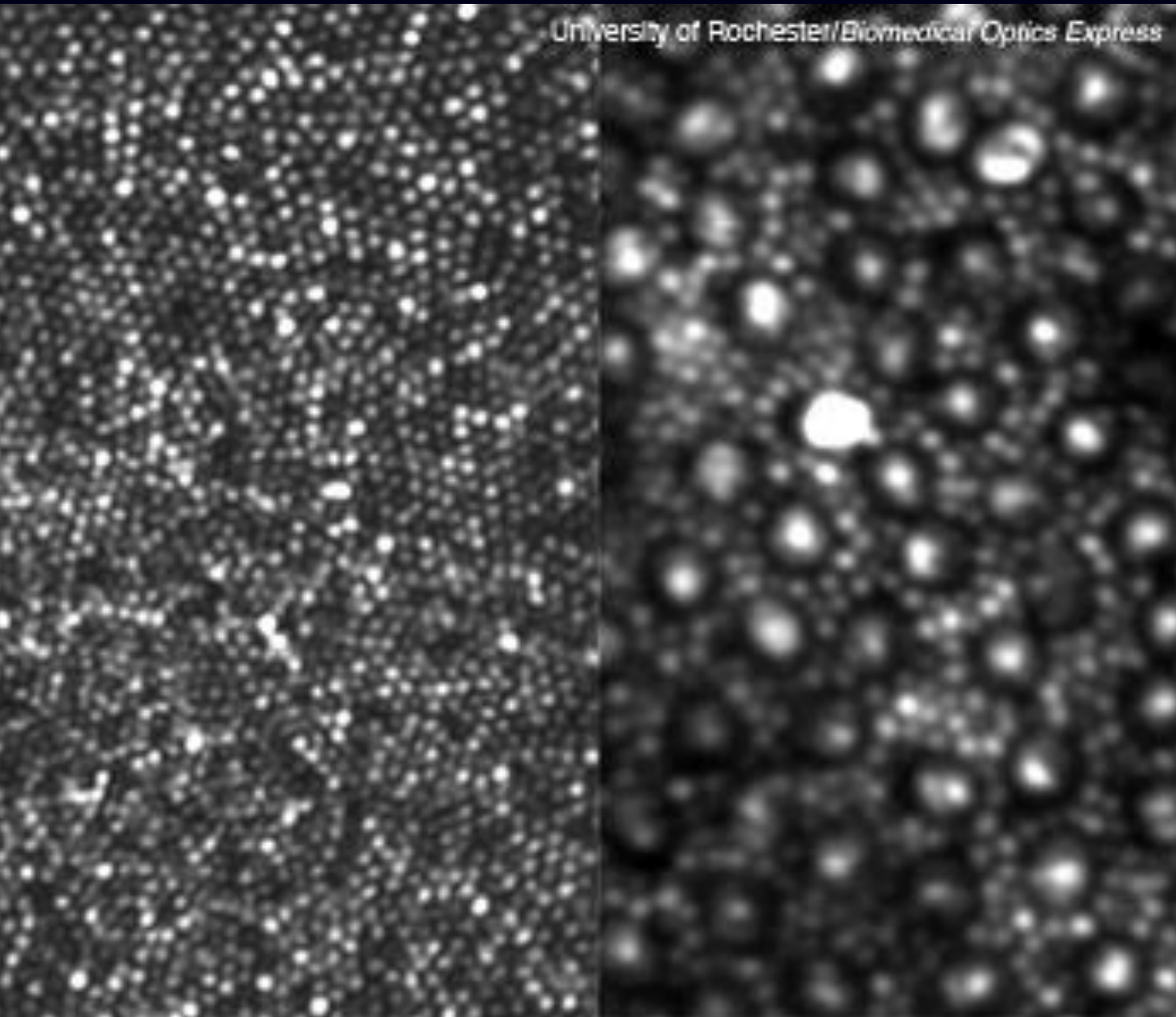
$$g_s(x,y) = g(x,y) \cdot s(x,y)$$

with:

- $g(x,y)$  : continuous description of the signal
- $s(x,y)$  : 2D sampling function (steps  $X, Y$  – not necessarily constant...→)



# Non-uniform sampling - example



**Left**

***Cones*** in the centre of the retina (fovea)

**Right:**

***Cones***, bigger, with dark rings.

***Rods***, large numbers, smaller, around cones.

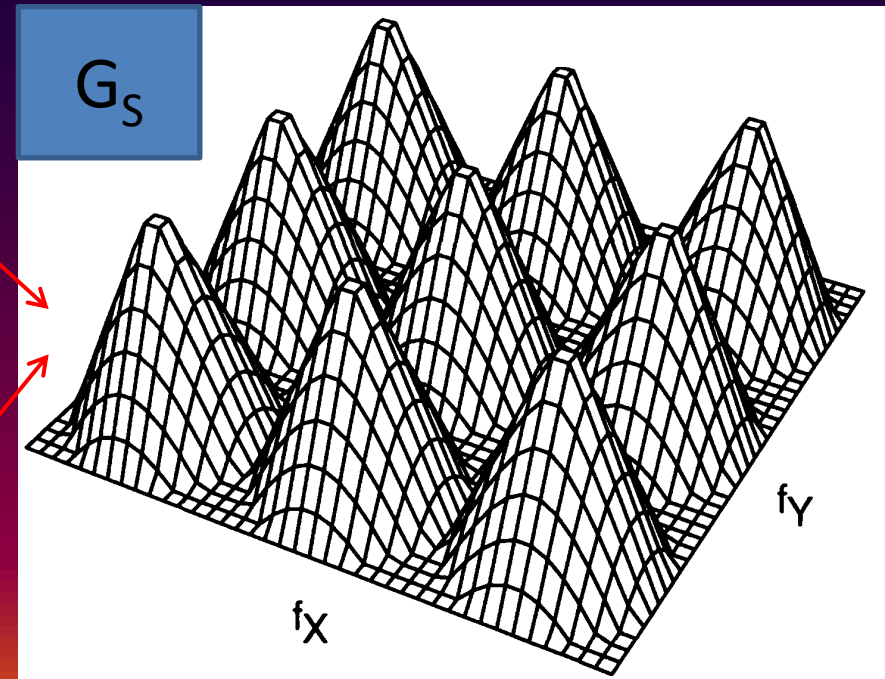
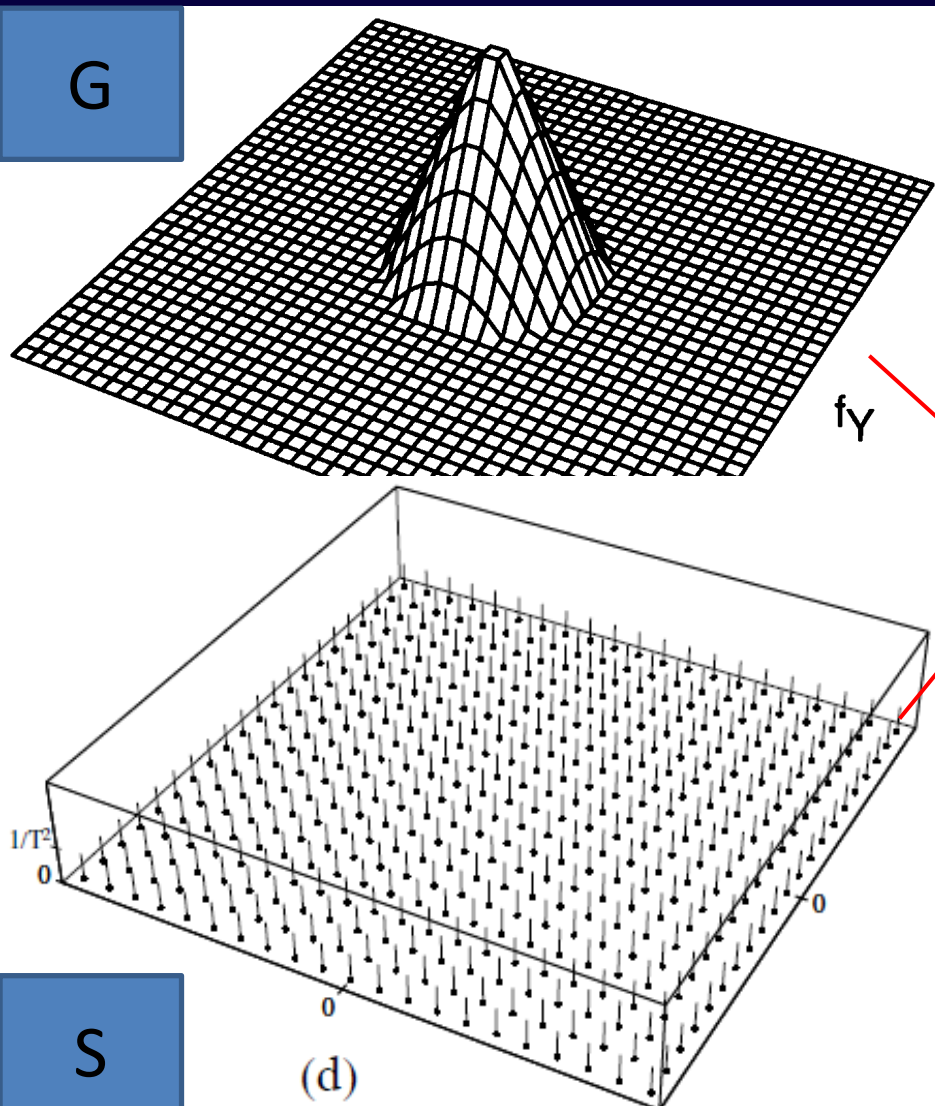
**Scientists Image Rods in the Living Eye**

[Biomed. Opt. Express 2, 1864, 2011;](#)  
[doi:10.1364/BOE.2.001864](#)



# 2D point sampling

$$g_s(x,y) = g(x,y) \cdot s(x,y) \rightarrow G_S(f_x, f_y) = G(f_x, f_y) ** S(f_x, f_y)$$

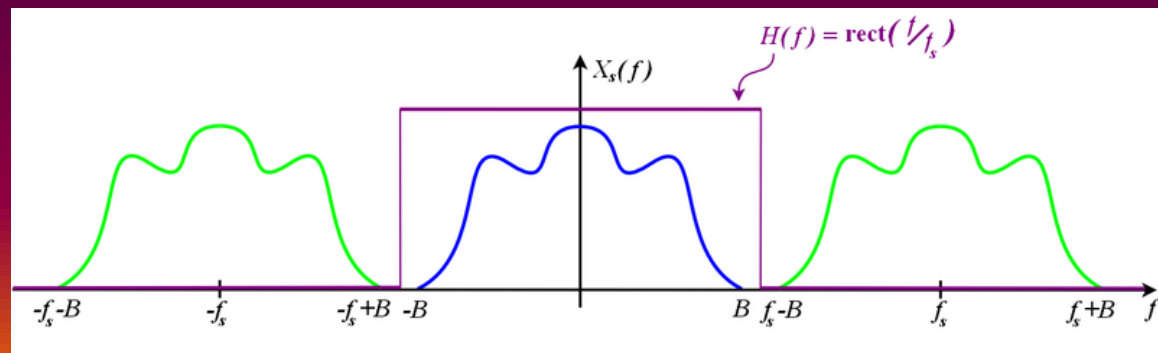
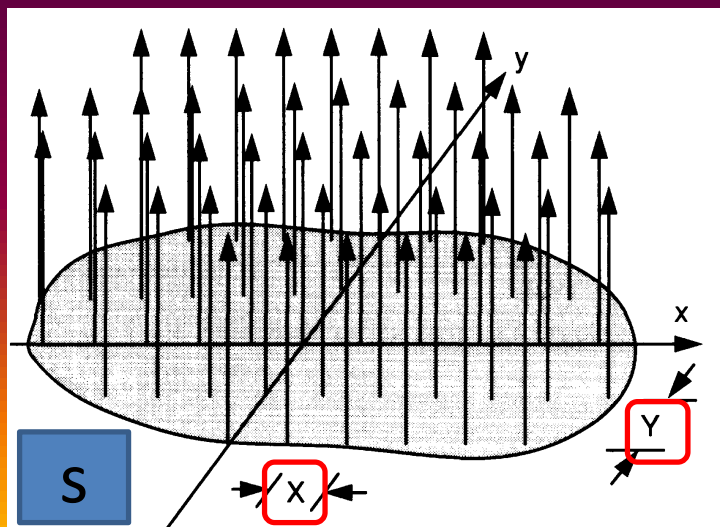


# 2D sampling

If the function is band **LIMITED**  $|f_{x,y}| < B$ , the sampling **step** in  $(X, Y)$  can always be chosen in order to ensure that the repetitions of  $G_S$  do not overlap:

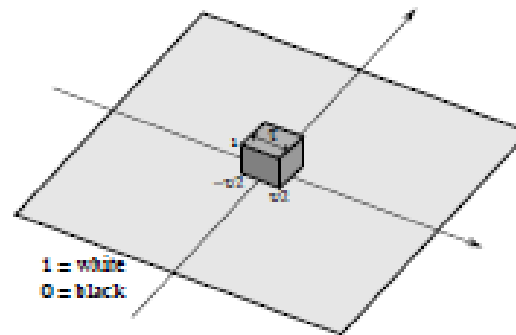
$$X \leq \frac{1}{2B_X} \quad Y \leq \frac{1}{2B_Y}$$

- The **minimum** value of  $2B_{x,y}$  of the sampling frequency is the **Nyquist frequency**

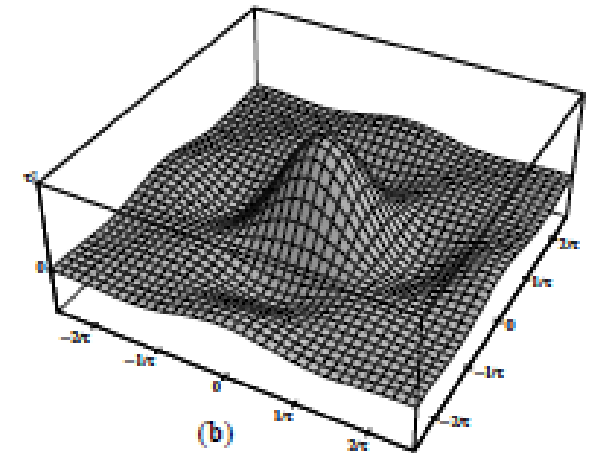


$G_S$

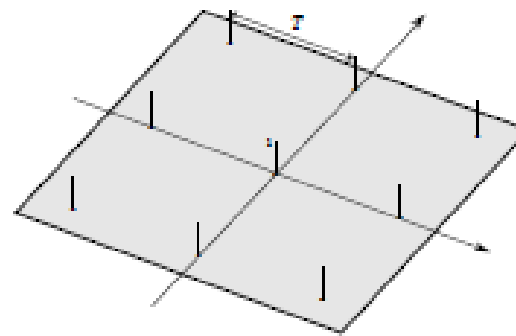
# Dot Screens



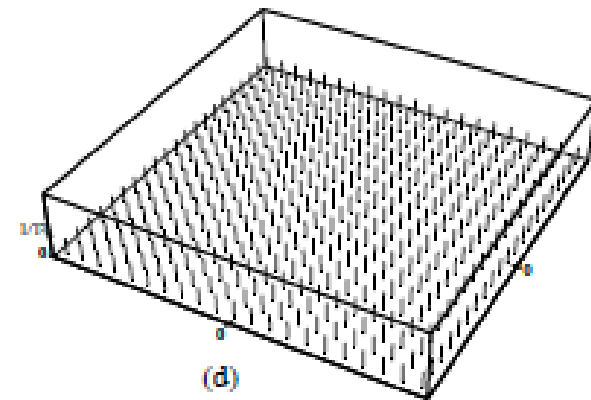
(a)



(b)

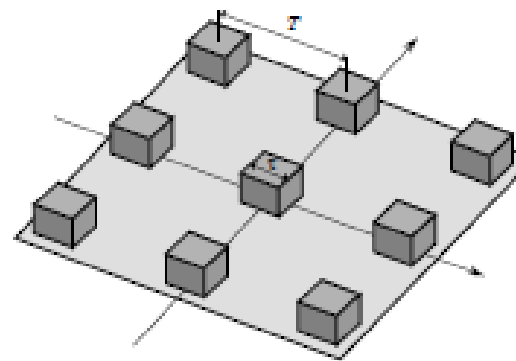


(c)

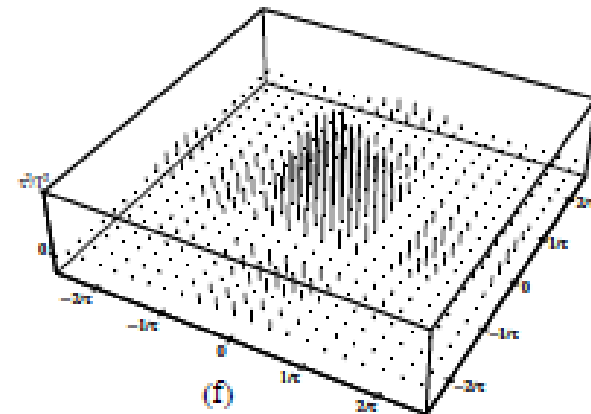


(d)

(a) A square white dot  $d(x,y)$  with side  $\tau$ ; (b) its continuous spectrum  $D(u,v) = \tau^2 \text{sinc}(\tau u) \text{sinc}(\tau v)$ . (c) A nailbed with period  $T$  and amplitude 1; (d) its spectrum is a nailbed with period  $1/T$  and amplitude  $1/T^2$ . (e) A screen of square white dots is the convolution of (a) and (c); (f) the spectrum of this screen is the product of (b) and (d); a nailbed that samples the "envelope" (b) at intervals of  $1/T$ , scaling its amplitude by  $1/T^2$ . Note that the impulses in (f) represent the coefficients of the 2D Fourier series development of (e).



(e)

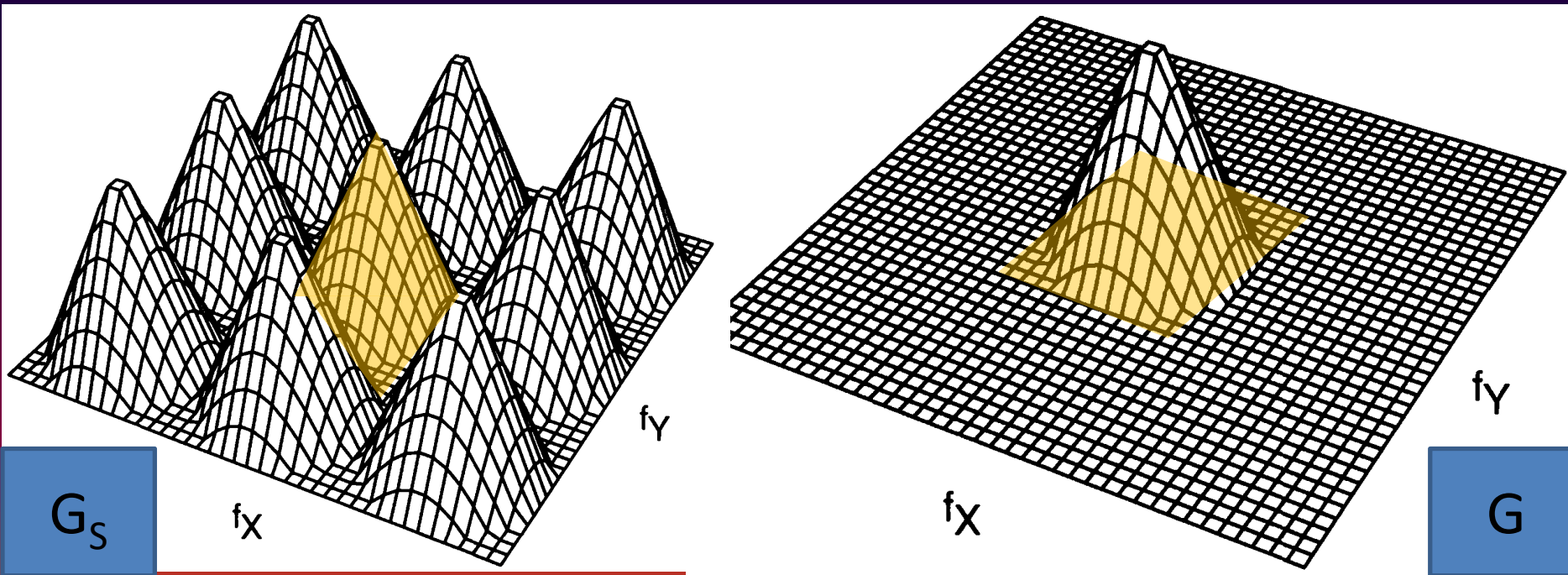


(f)

# 2D sampling: low pass filtering

If the function is band **LIMITED** and  $|f_{x,y}| < B_{x,y}$ , the true spectrum of  $g$ , **G**, can always be extracted from  $G_S$  by filtering:

$$G_S(f_x, f_y) = G(f_x, f_y) ** S(f_x, f_y) \rightarrow \mathbf{G}(f_x, f_y) = \text{rect}(f_x/2B_x, f_y/2B_y) \cdot G_S(f_x, f_y)$$



By inverse FT, we can retrieve  $g(x,y)$  from its samples:

$$g(x,y) = \text{TF}^{-1} G(f_x, f_y)$$

# 2D sampling

If a function  $g(x,y)$  **IS BAND LIMITED**,  $|f_{x,y}| < B_{x,y}$ , below the Nyquist frequency:

$$g_s(x,y) = g(x,y) \cdot s(x,y)$$

$$\text{Point sampling: } p(x,y) = \delta(x,y)$$

$$G_s(f_x, f_y) = G(f_x, f_y) ** S(f_x, f_y)$$

$$G(f_x, f_y) = \text{rect}(f_x/2B_x, f_y/2B_y) \cdot G_s(f_x, f_y)$$

$$g(x,y) = \text{TF}^{-1} G(f_x, f_y)$$

$$g(x, y) = \sum_{n=-\infty}^{\infty} \sum_{m=-\infty}^{\infty} g\left(\frac{n}{2B_x}, \frac{m}{2B_y}\right) \text{sinc}\left[2B_x\left(x - \frac{n}{2B_x}\right)\right] \text{sinc}\left[2B_y\left(y - \frac{m}{2B_y}\right)\right]$$

$$\text{sinc } x = \frac{\sin(\pi x)}{\pi x}$$



# 2D sampling – other factors...

Degrading the signal,  $g$ : aberrations, low-pass anti-aliasing filter, ...

$$g(x,y) \rightarrow g(x,y) * h(x,y)$$

Integrating the signal with a finite aperture sensors,  $p_s$

$$g(x,y) \rightarrow g(x,y) * h(x,y) * p_s(x,y)$$

Sampling the degraded signal

$$g_s(x,y) = [g(x,y) * h(x,y) * p_s(x,y)] \cdot s(x,y)$$

$$G_s(f_x, f_y) = [G(f_x, f_y) \cdot H(f_x, f_y) \cdot P_s(f_x, f_y)] * S(f_x, f_y)$$

Displaying the sampled signal (periodic array of display pixels,  $p_D$ ) ...  $\rightarrow$  ...

$$g_v(x,y) = \{ [g(x,y) * h(x,y) * p_s(x,y)] \cdot s(x,y) \} * p_D(x,y)$$

$$G_v(f_x, f_y) = \{ [G(f_x, f_y) \cdot H(f_x, f_y) \cdot P_s(f_x, f_y)] * S(f_x, f_y) \} \cdot P_D(f_x, f_y)$$

# What if the function is NOT band LIMITED?

Shannon theory is no longer applicable!

Nyquist requirements cannot be satisfied

- The object is unknown or dynamic
- Technical or technological impossibility

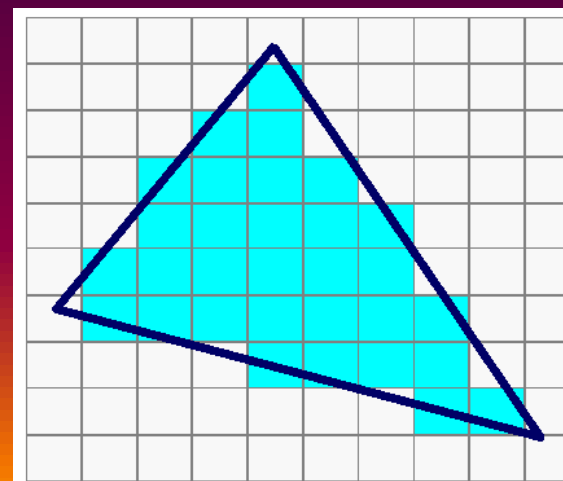
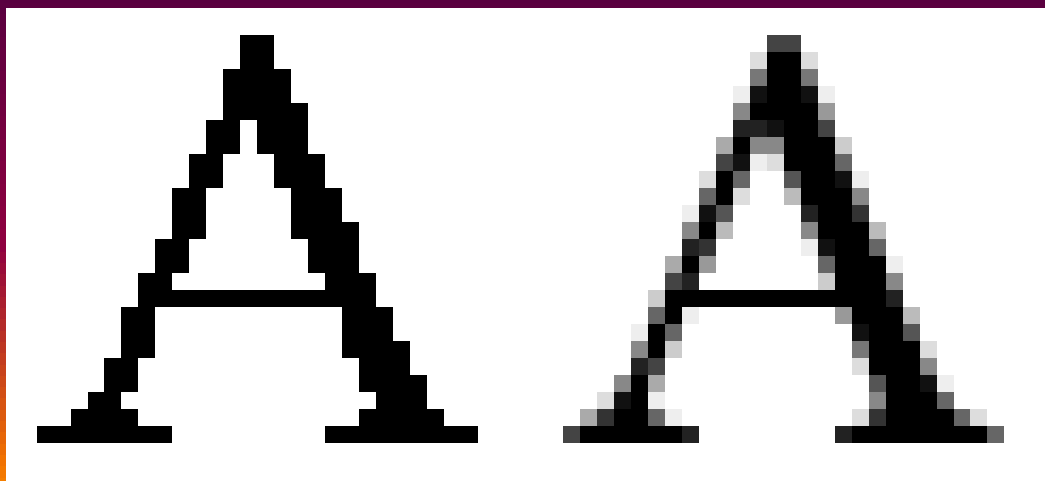
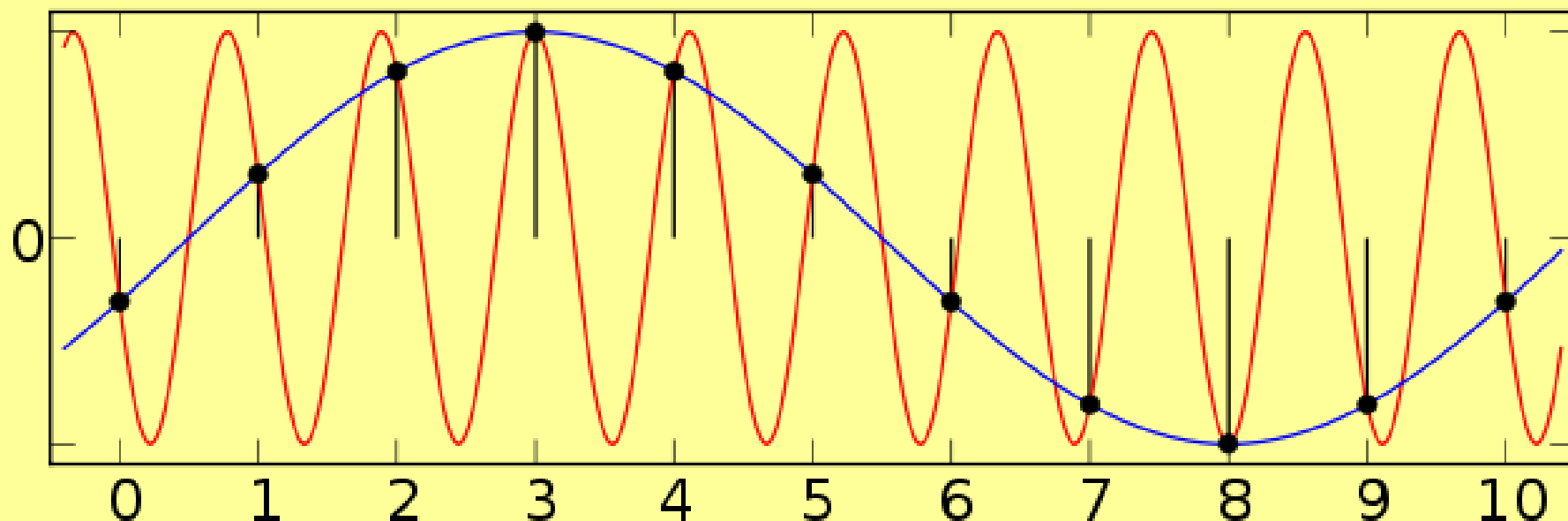
The signal is not band limited / very large bandwidth

- Periodic or quasi-periodic signals  
Printed or digital documents, displays, ...

The multiplicative model is not applicable

- $n$  components multiplicative model (colour)
- Non-multiplicative model

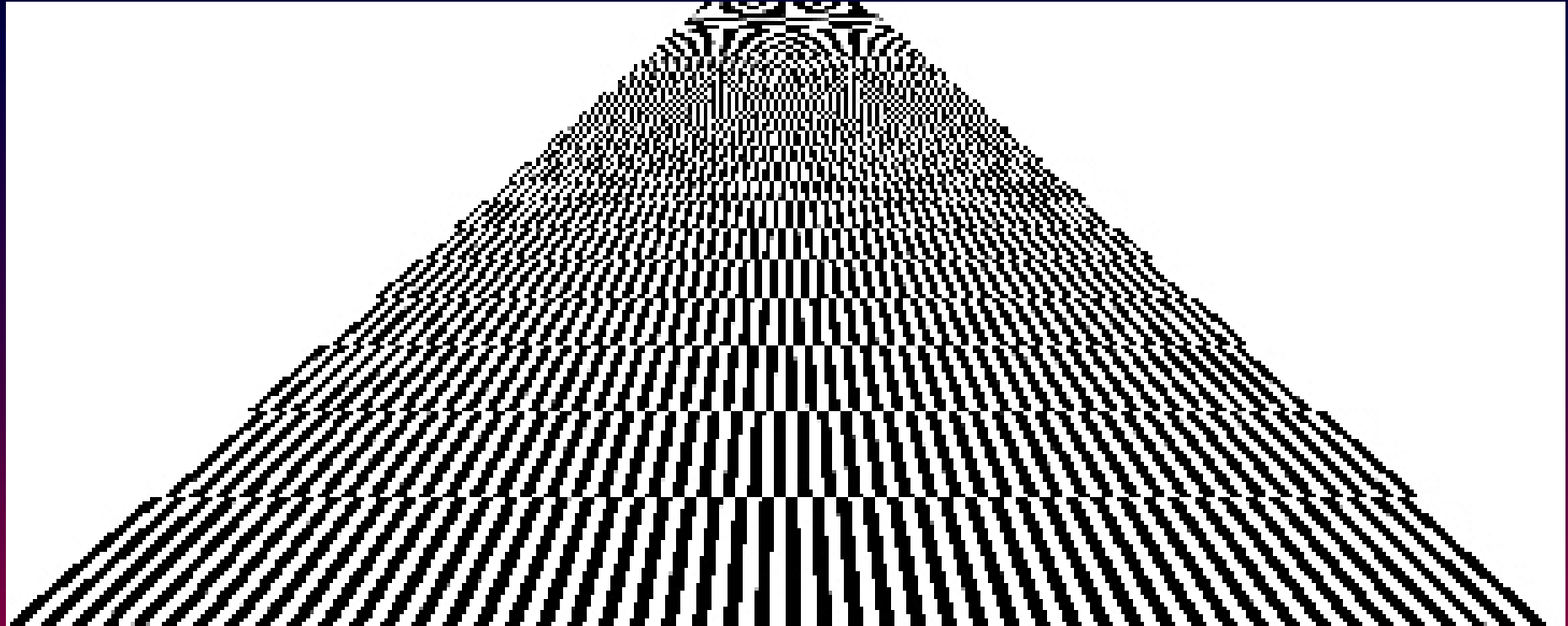
# Artifacts ...



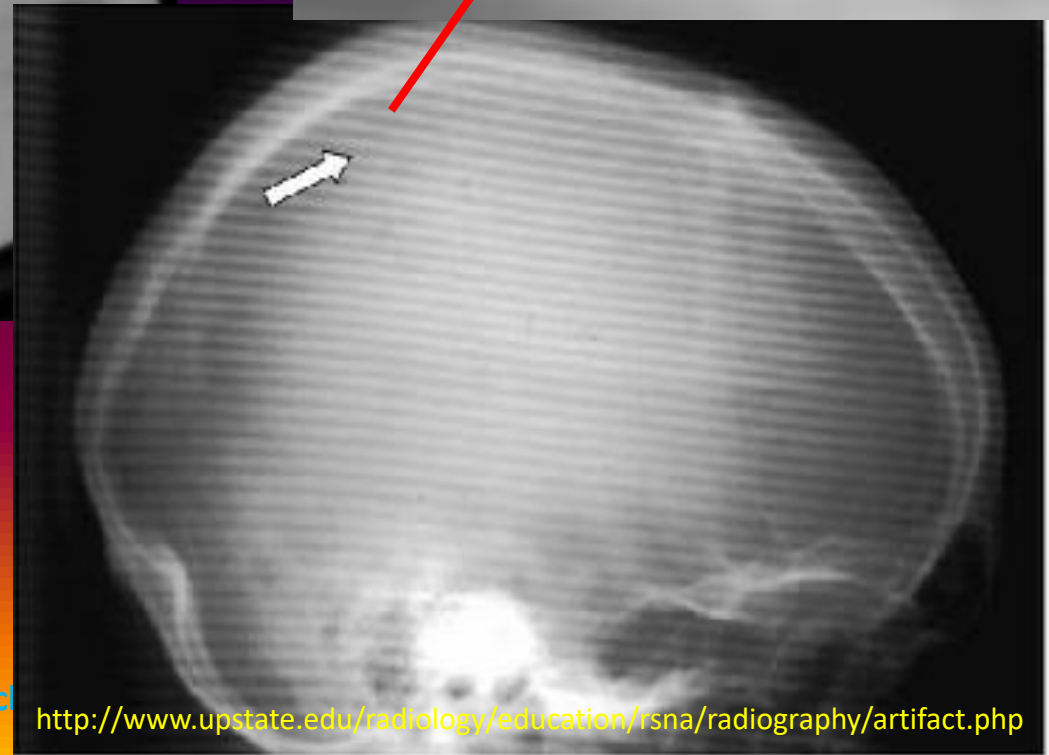
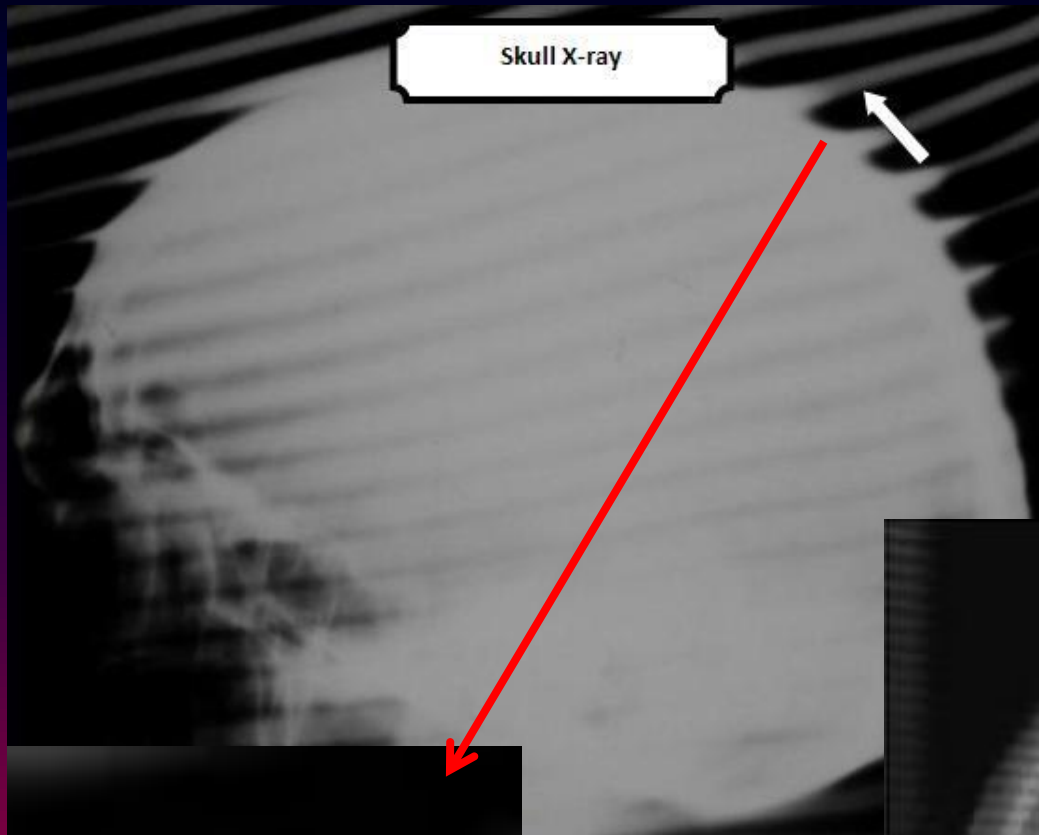
A  
r  
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s



# Artifacts ...



# Artifacts ..... in digital radiography





# Artifacts ...

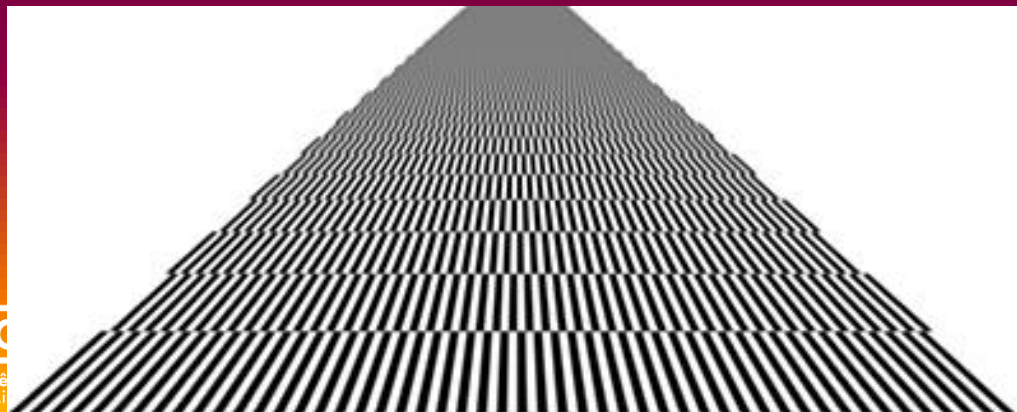
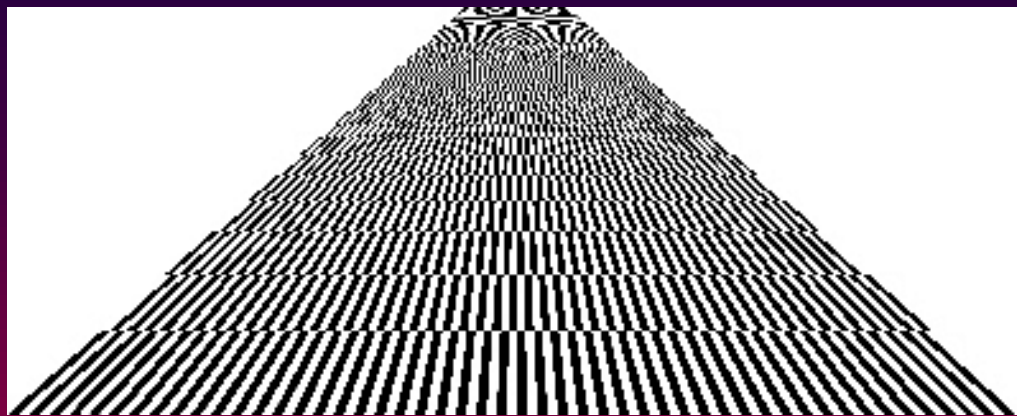
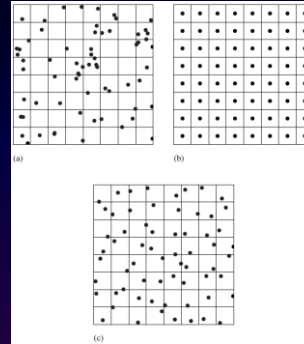




# Aliasing → anti-aliasing

## Sampling

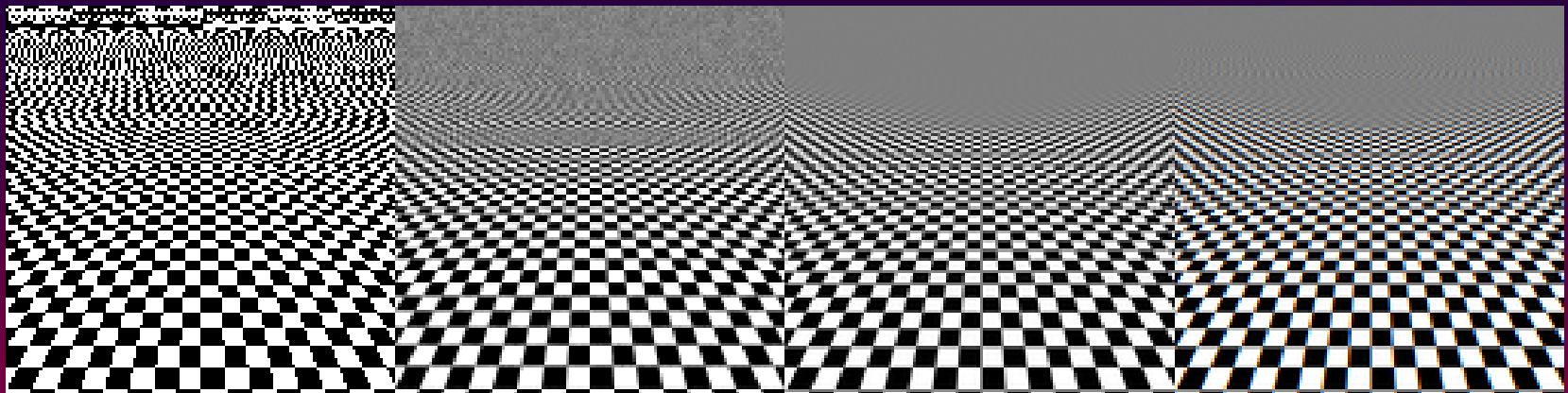
- Non-uniform
  - Stratified
- Adaptive
- Previous / later low-pass filtering



# Aliasing → anti-aliasing

## Sampling

- Non-uniform
  - Stratified
- Adaptive
- Previous / later low-pass filtering



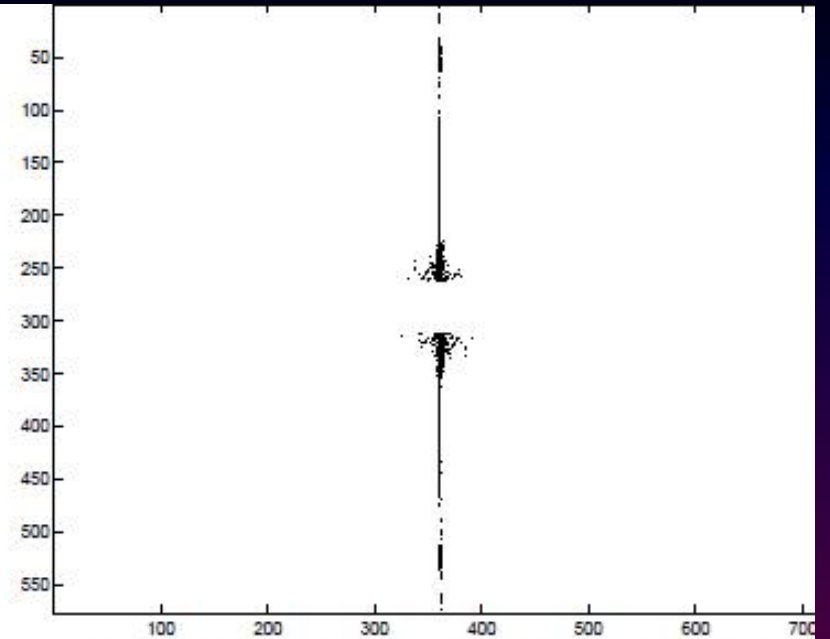
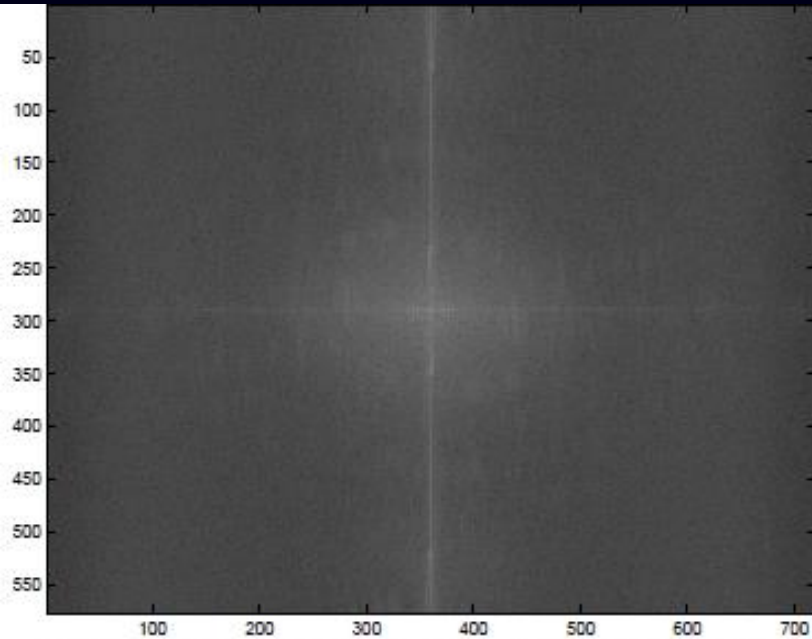
Aliased  
image

Pixel  
Coverage  
Anti-aliasing

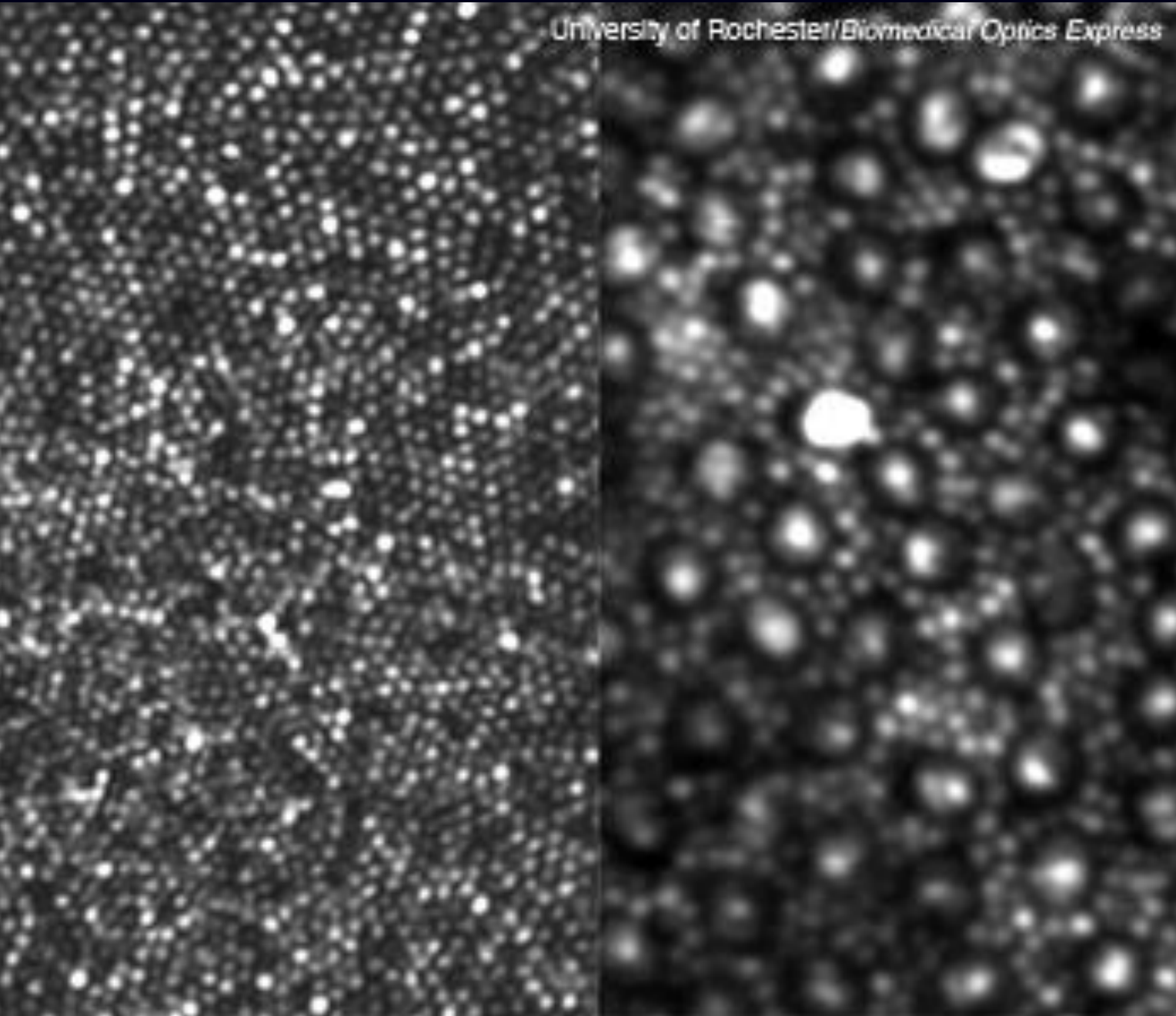
Super  
sampling  
with proper  
filtering

Same with  
subpixel  
rendering

# Low pass filtering – TV transmission



# Retina sensors: non-uniform sensor network



**Left**

***Cones*** in the centre of the retina (fovea)

**Right:**

***Cones***, bigger, with dark rings.

***Rods***, large numbers, smaller, around cones.

**Scientists Image Rods in the Living Eye**

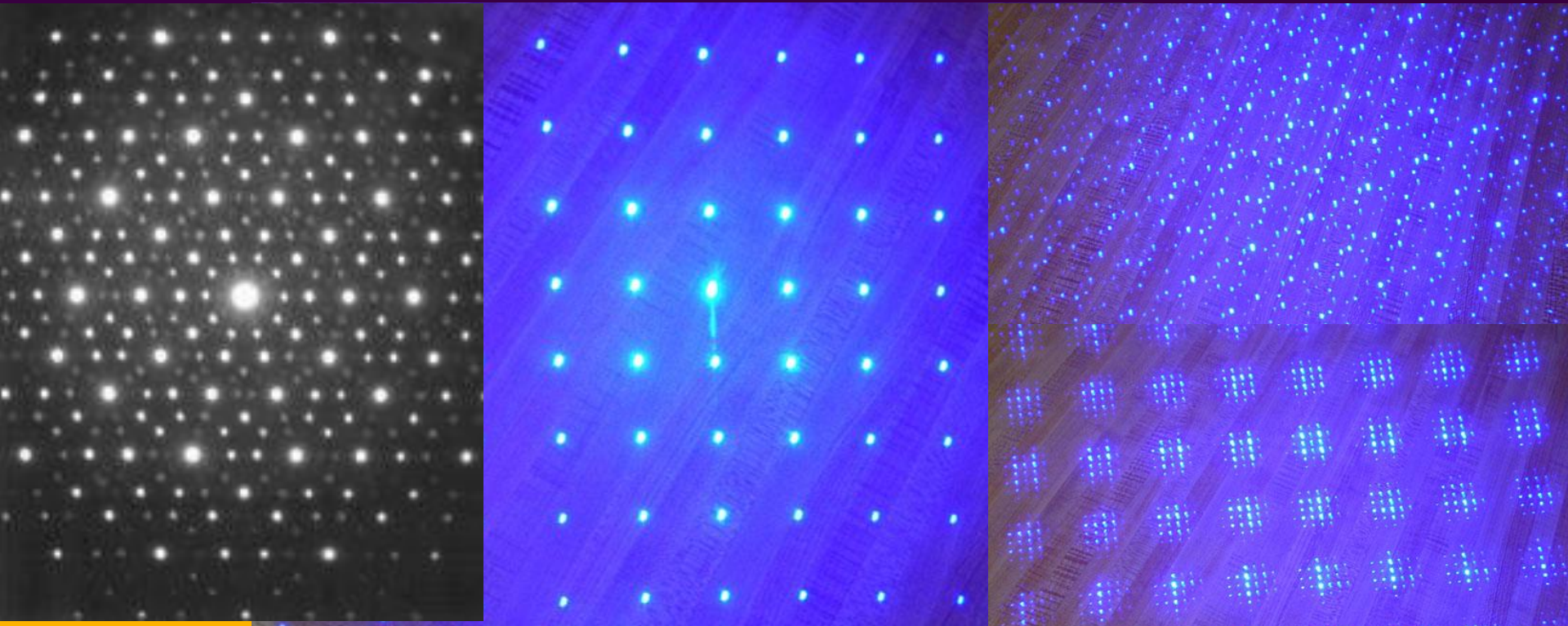
[Biomed. Opt. Express 2, 1864, 2011;](#)  
[doi:10.1364/BOE.2.001864](#)



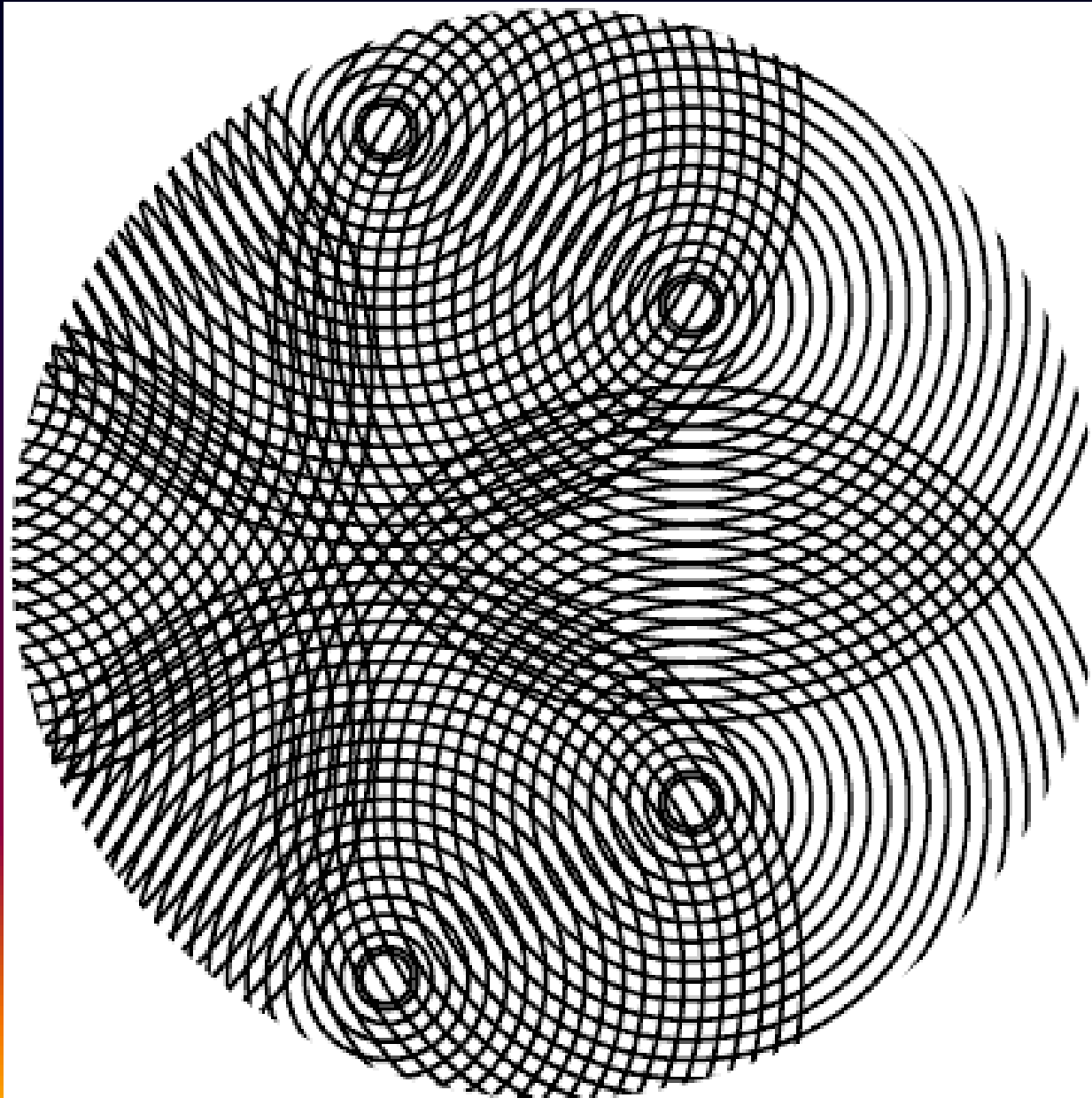
# Artifacts do exist ... What now?

## How to go beyond Shannon theory?

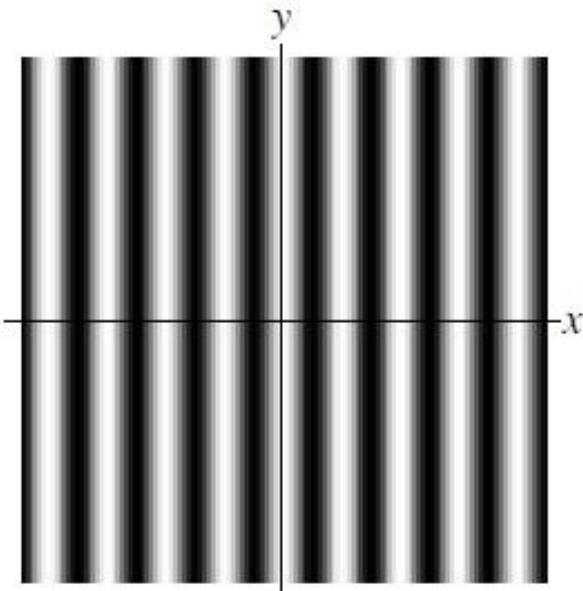
How to handle periodic objects  $\rightarrow$  Large bandwidth  
Fourier spectra, quasi-periodic, with intense pulses in a  
regular pattern, with modulated intensity



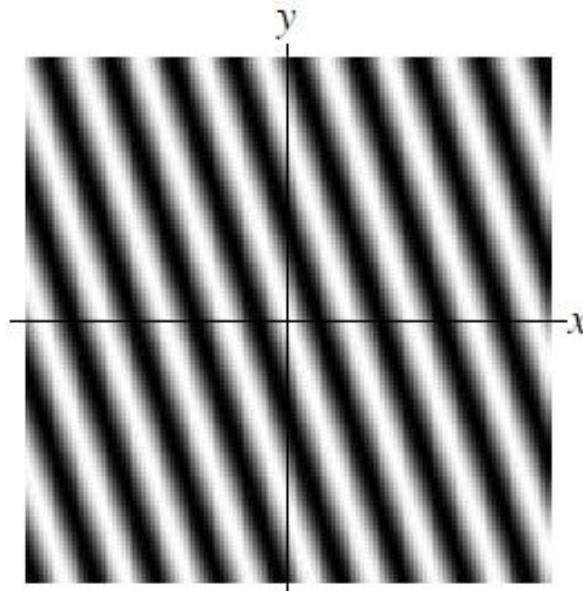
# X Superposition of 5 periodic objects?



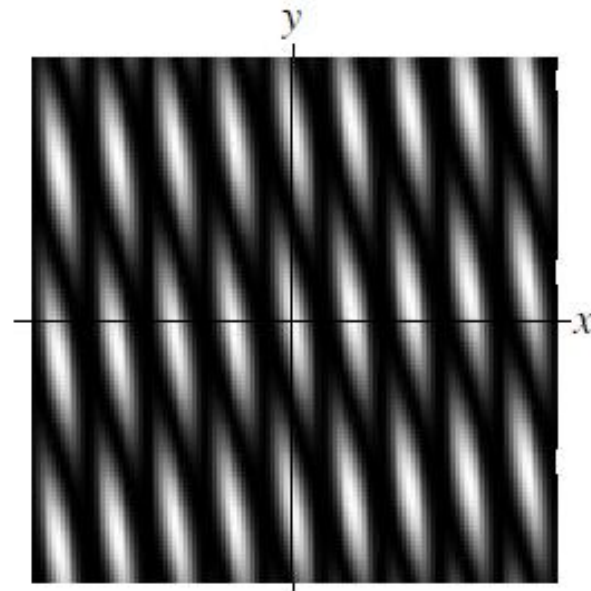
# Example: X Superposition of 2 periodic harmonic objects



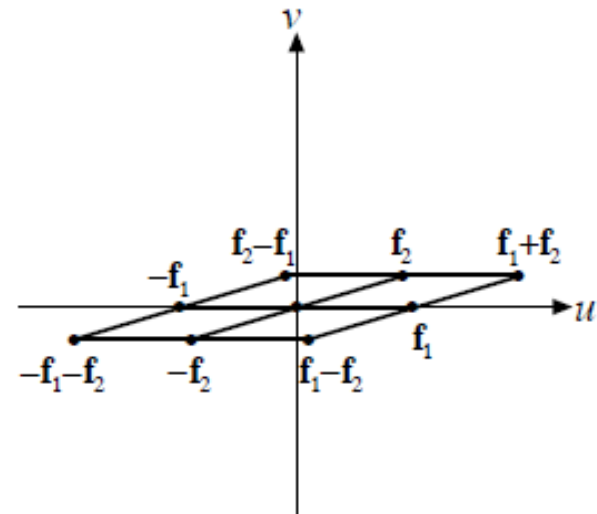
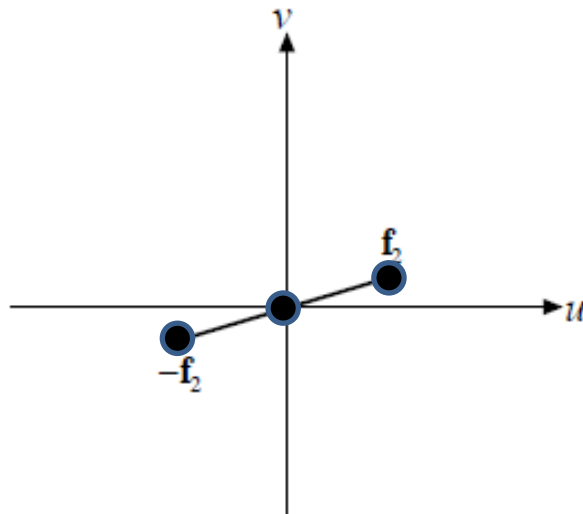
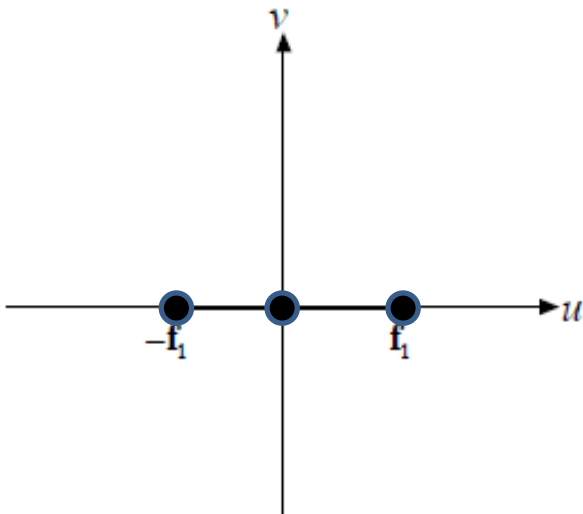
$$r_1(x,y) = \frac{1}{2}\cos(2\pi f_1 x) + \frac{1}{2}$$



$$r_2(x,y) = \frac{1}{2}\cos(2\pi f_2 [x\cos\theta_2 + y\sin\theta_2]) + \frac{1}{2}$$

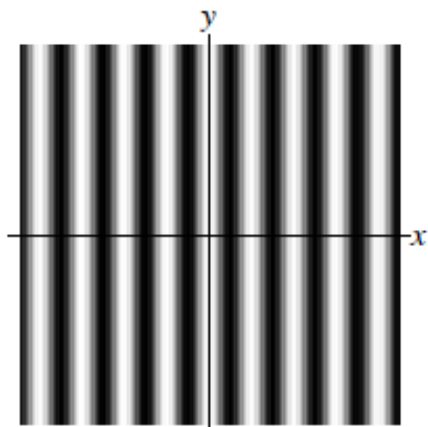


$$r(x,y) = r_1(x,y)r_2(x,y)$$

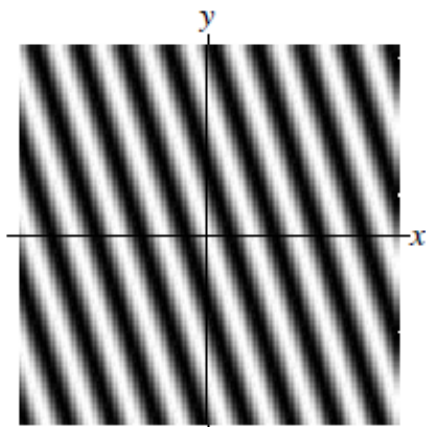




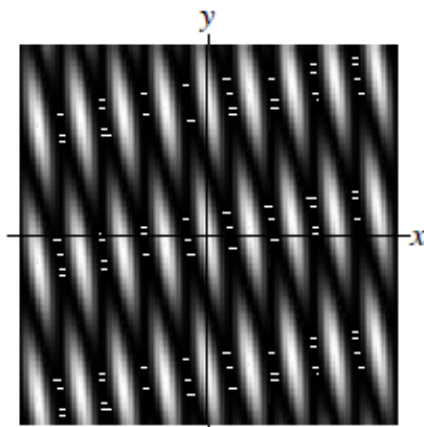
# X Superposition of 2 periodic harmonic objects



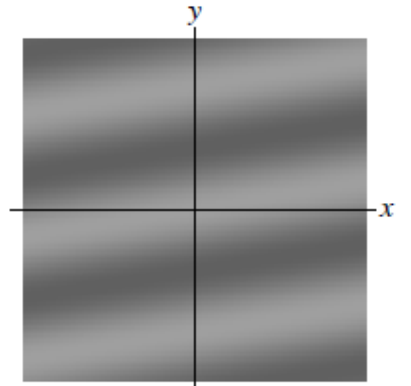
(a)



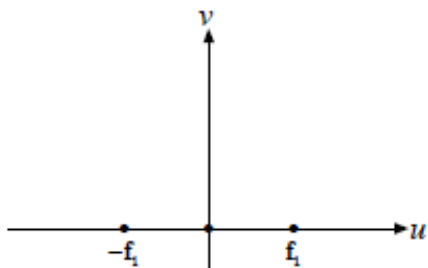
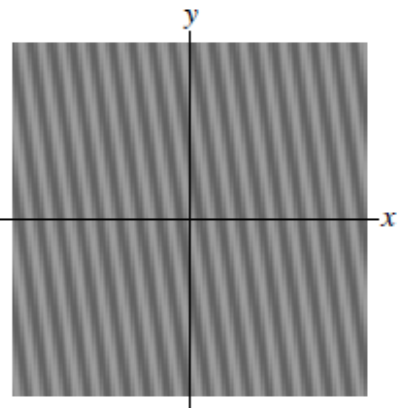
(b)



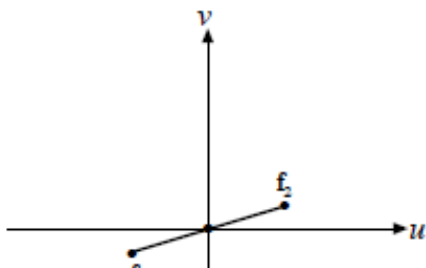
(c)



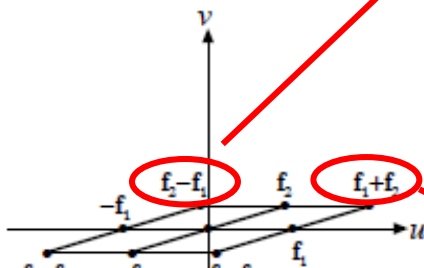
(j)



(d)



(e)

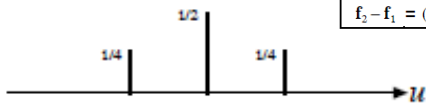


(f)

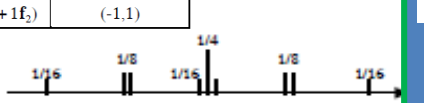
The frequency-vector of the impulse	The $(k_1, k_2)$ -index of the impulse
$0 = (0f_1 + 0f_2)$	$(0,0)$
$f_1 = (1f_1 + 0f_2)$	$(1,0)$
$-f_1 = (-1f_1 + 0f_2)$	$(-1,0)$
$f_2 = (0f_1 + 1f_2)$	$(0,1)$
$-f_2 = (0f_1 - 1f_2)$	$(0,-1)$
$f_1 + f_2 = (1f_1 + 1f_2)$	$(1,1)$
$-f_1 - f_2 = (-1f_1 - 1f_2)$	$(-1,-1)$
$f_1 - f_2 = (1f_1 - 1f_2)$	$(1,-1)$
$f_2 - f_1 = (-1f_1 + 1f_2)$	$(-1,1)$



(g)



(h)



(i)

As frequências  $f_1$  e  $f_2$  só existem na imagem de sobreposição por causa dos termos DC em  $r_1$  e  $r_2$ :

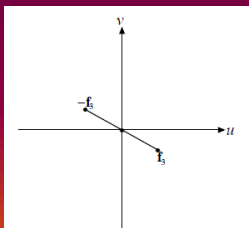
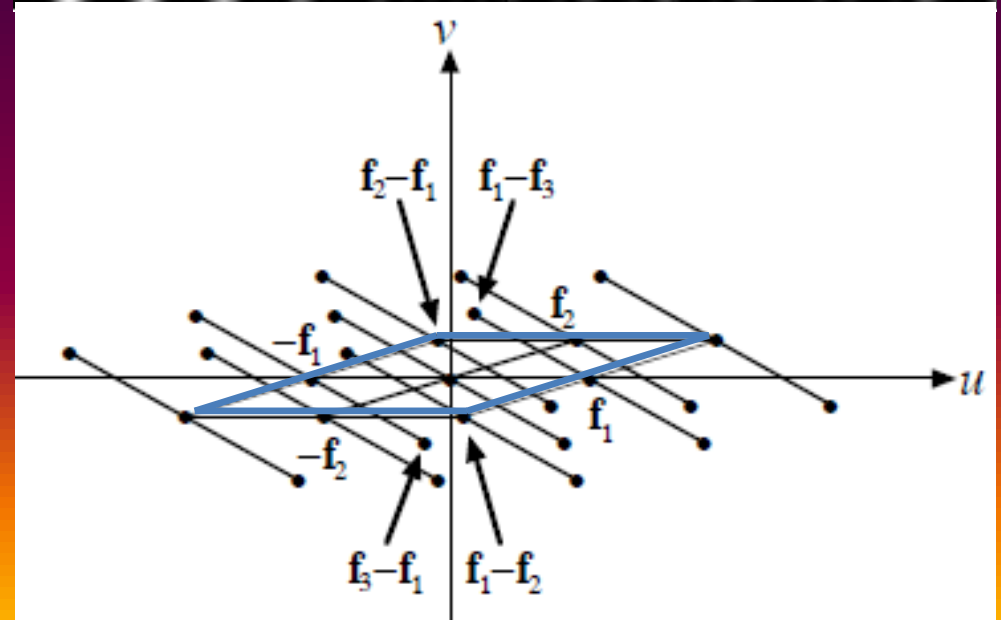
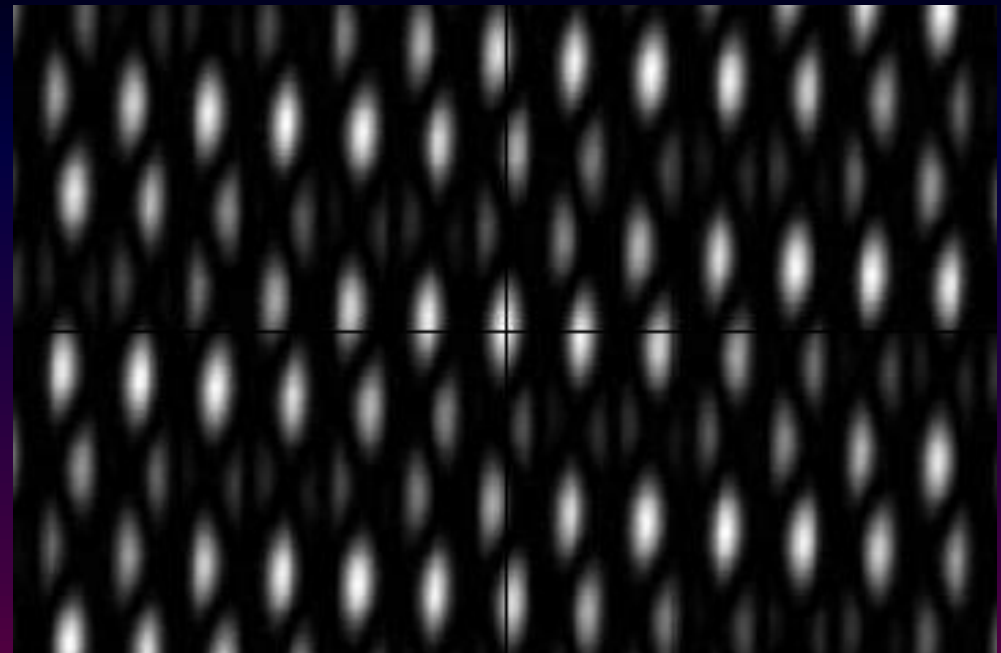
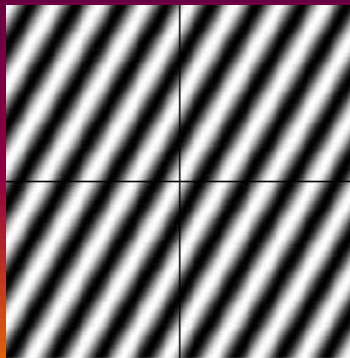
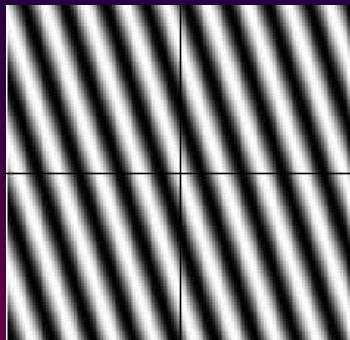
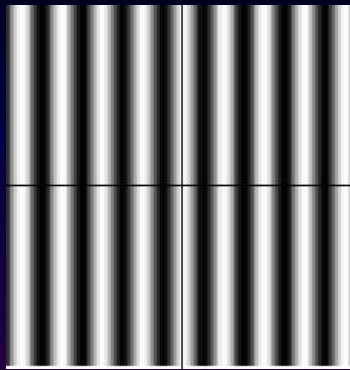
$$\cos \alpha \cos \beta = \frac{1}{2} \cos(\alpha - \beta) + \frac{1}{2} \cos(\alpha + \beta)$$

$$\left(\frac{1}{2} \cos \alpha + \frac{1}{2}\right) \left(\frac{1}{2} \cos \beta + \frac{1}{2}\right) = \frac{1}{4} + \frac{1}{4} \cos \alpha + \frac{1}{4} \cos \beta + \frac{1}{8} \cos(\alpha - \beta) + \frac{1}{8} \cos(\alpha + \beta)$$

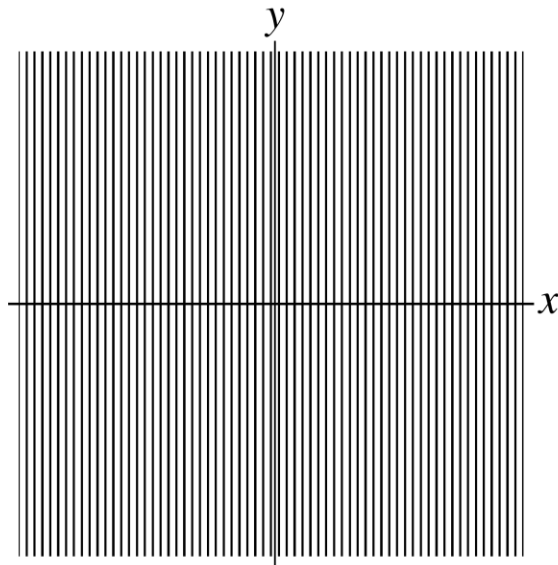
**Notação** (para 2 redes):

$$f = n f_1 + m f_2 \rightarrow (n, m)$$

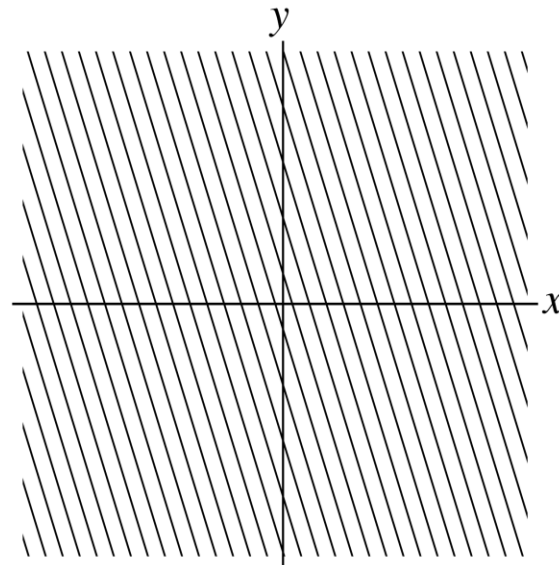
# X Superposition of 3 periodic harmonic objects



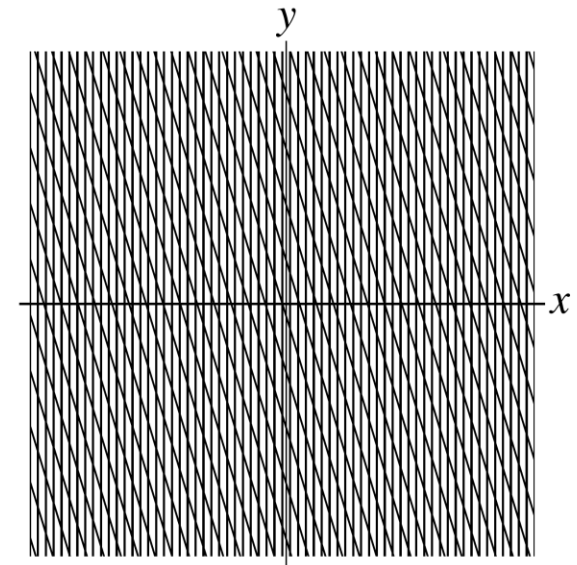
# Superposition of non-harmonic periodic objects



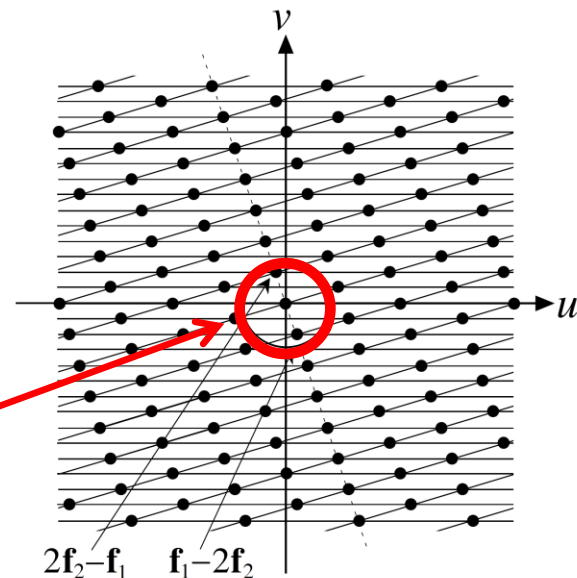
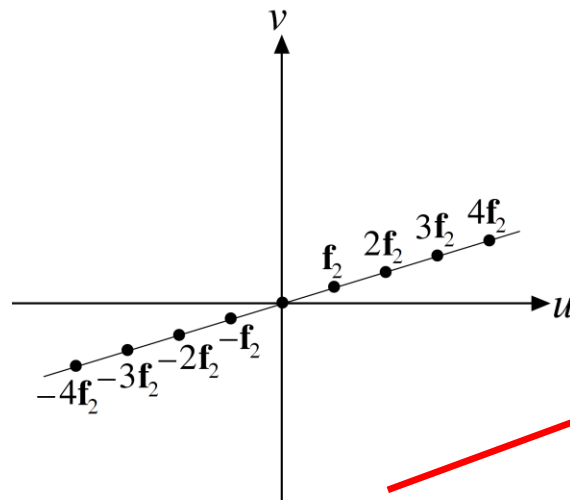
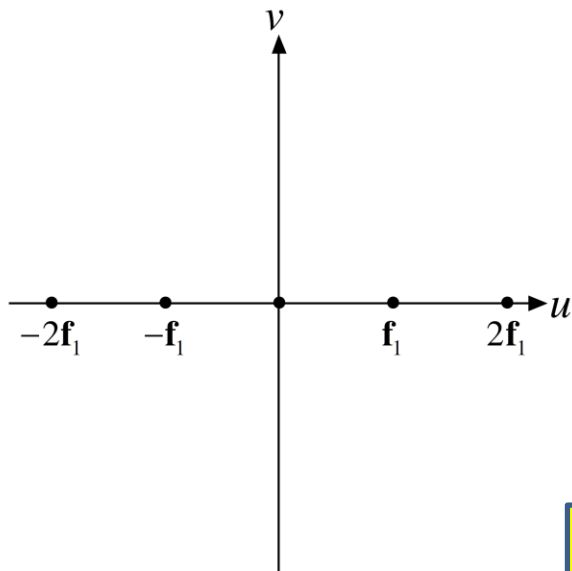
(a)



(b)



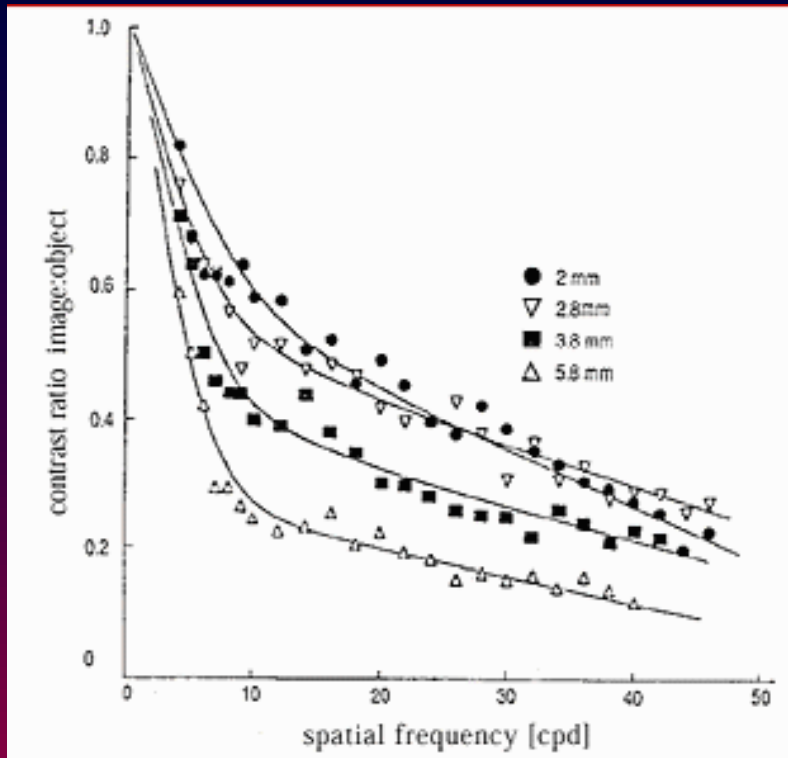
(c)



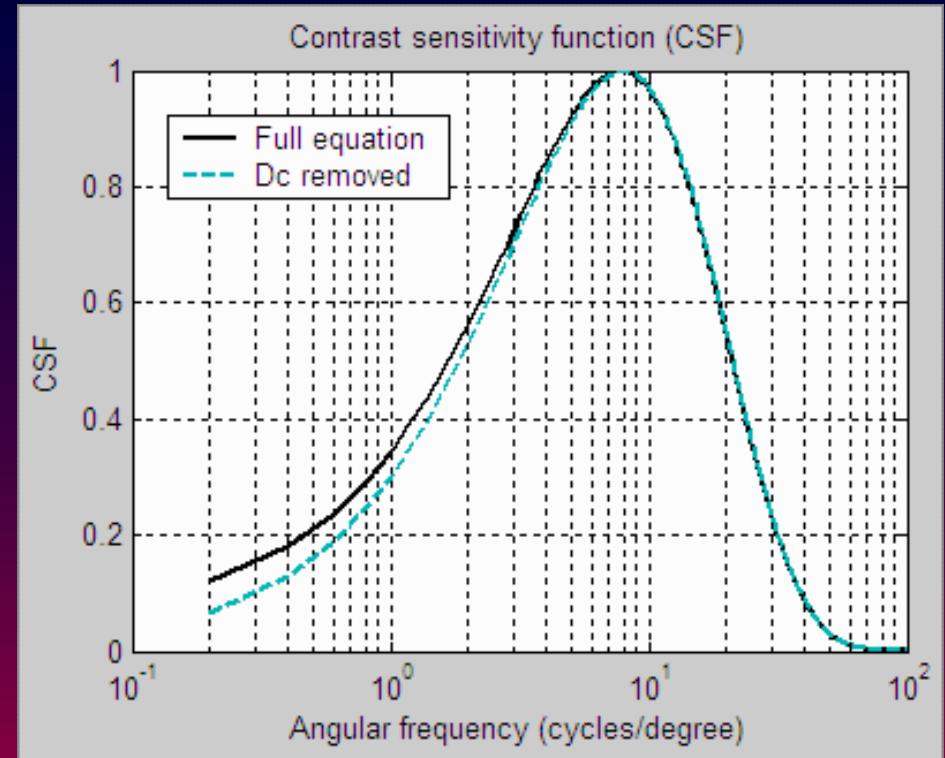
**Visibility circle**

# Visual band

## MTF



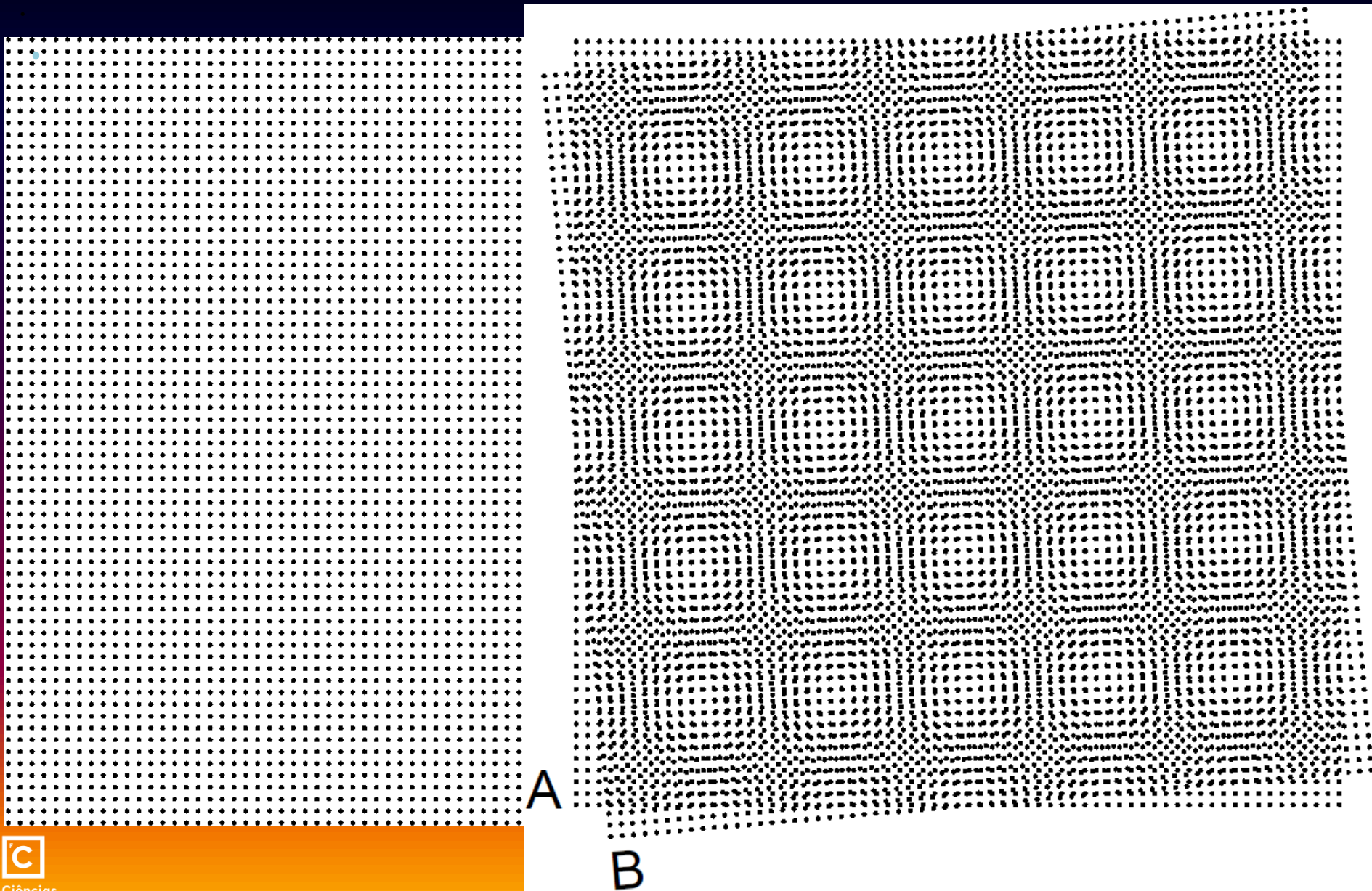
## CSF



**Cutoff frequency: 60 cycles/° (2 mm pupil)**

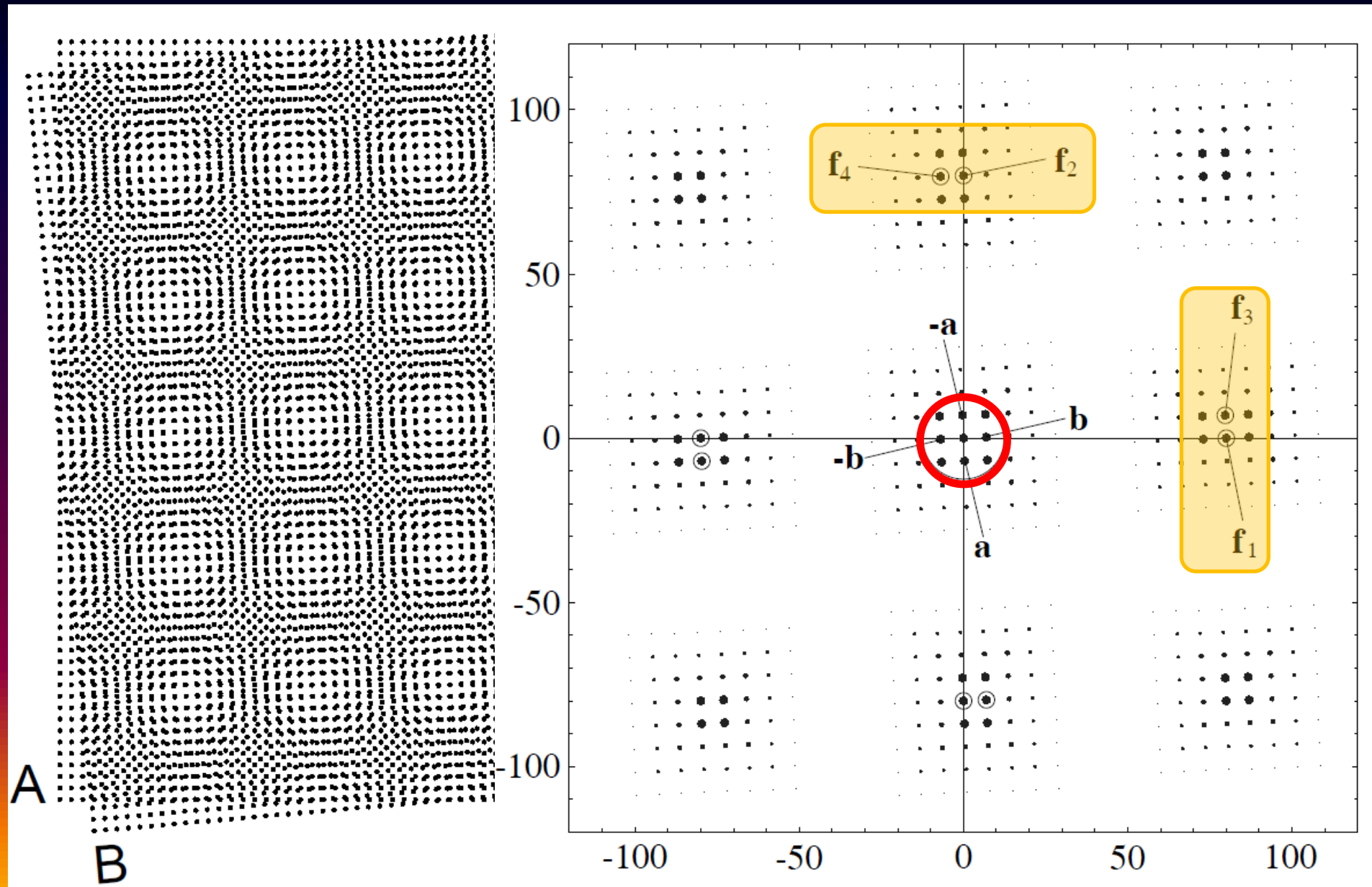
**~ 250 dpi @ 30 cm ( ~ 0.1 mm @ 30 cm)**

# Superposition (X) of periodic 2D objects

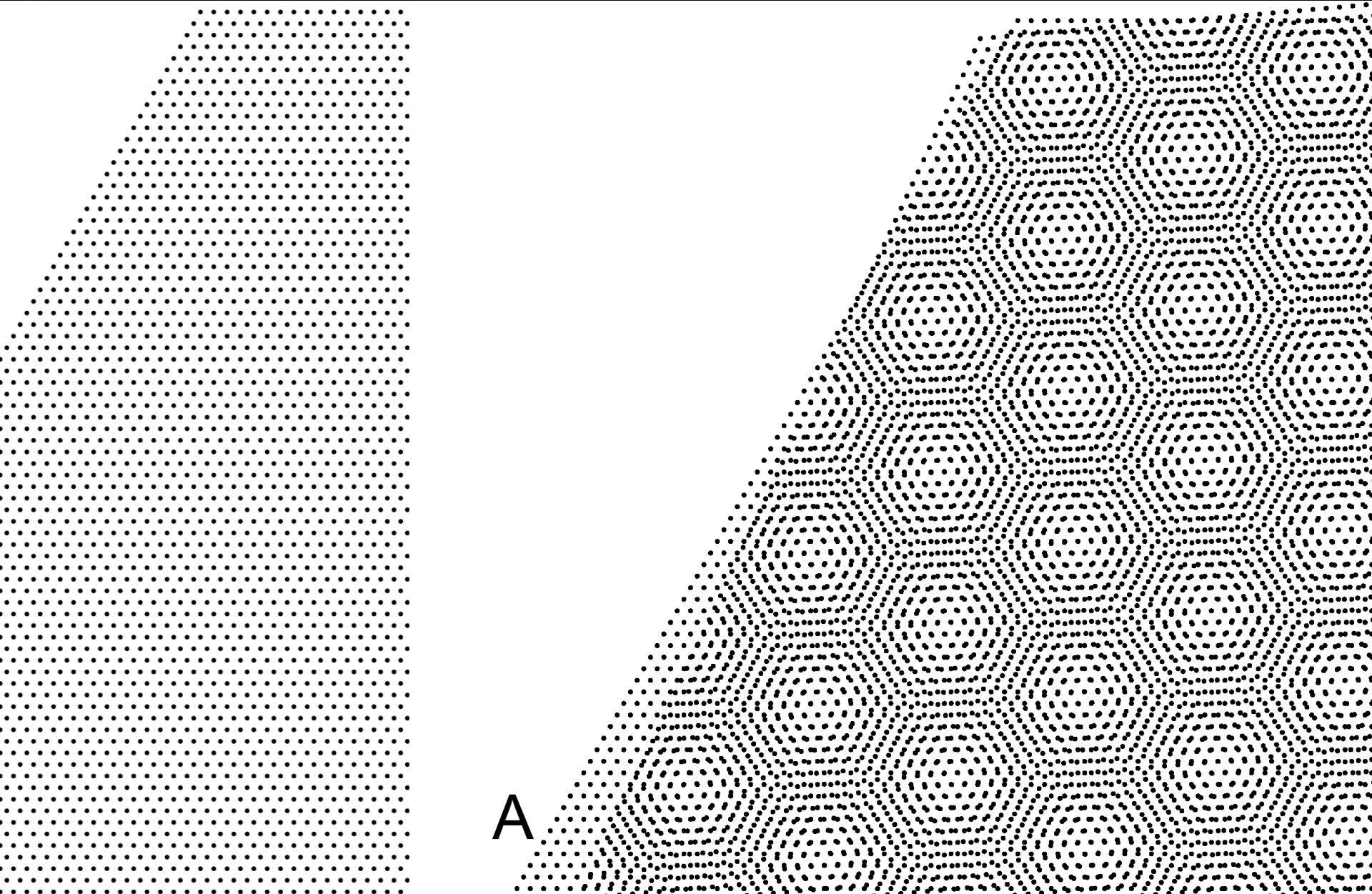




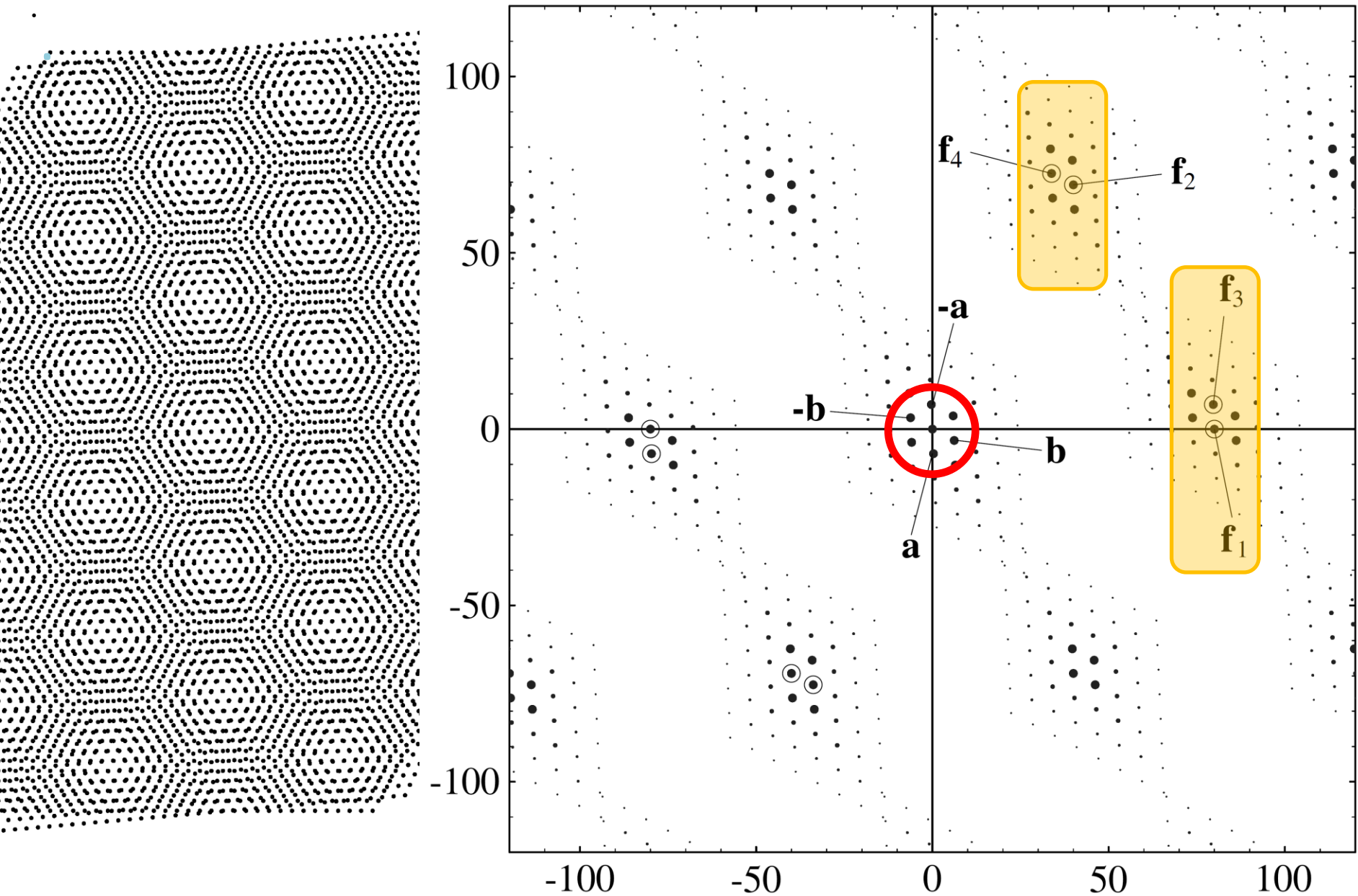
# Superposition (X) of periodic 2D objects



# Superposition (X) of periodic 2D objects (hexagonal)

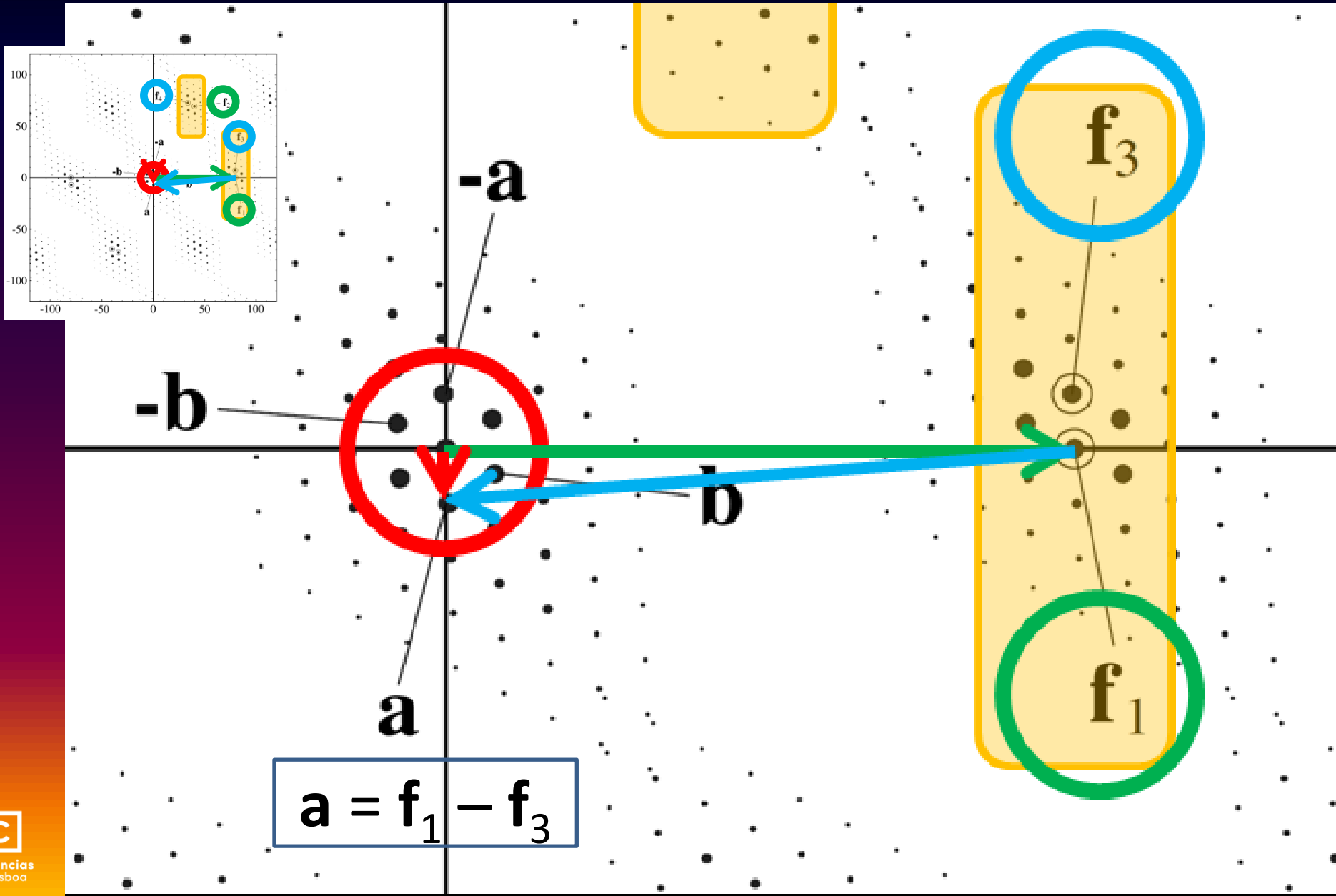


# Superposition (X) of periodic 2D objects





# Superposition (X) of periodic 2D objects



# Very important!

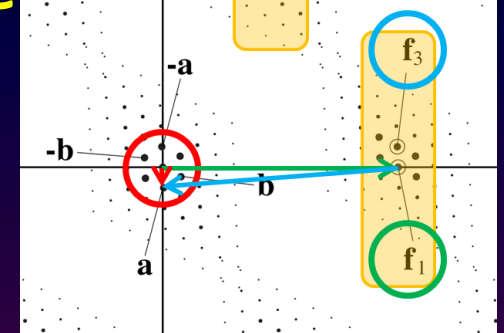
Generating **low frequencies** within the visibility circle, from non-visible **high frequencies** (100,000 dpi  $\rightarrow$  0.25  $\mu\text{m}$ ), enables applications in:

- **In document security**
  - *Scrambled indicia*, hidden images, modulations, digital watermarking, ...
- **In image or video coding**

# In general:

Anywhere – and also within the **visibility circle**:

$$\mathbf{f} = \sum_{i=1}^m k_i \mathbf{f}_i$$



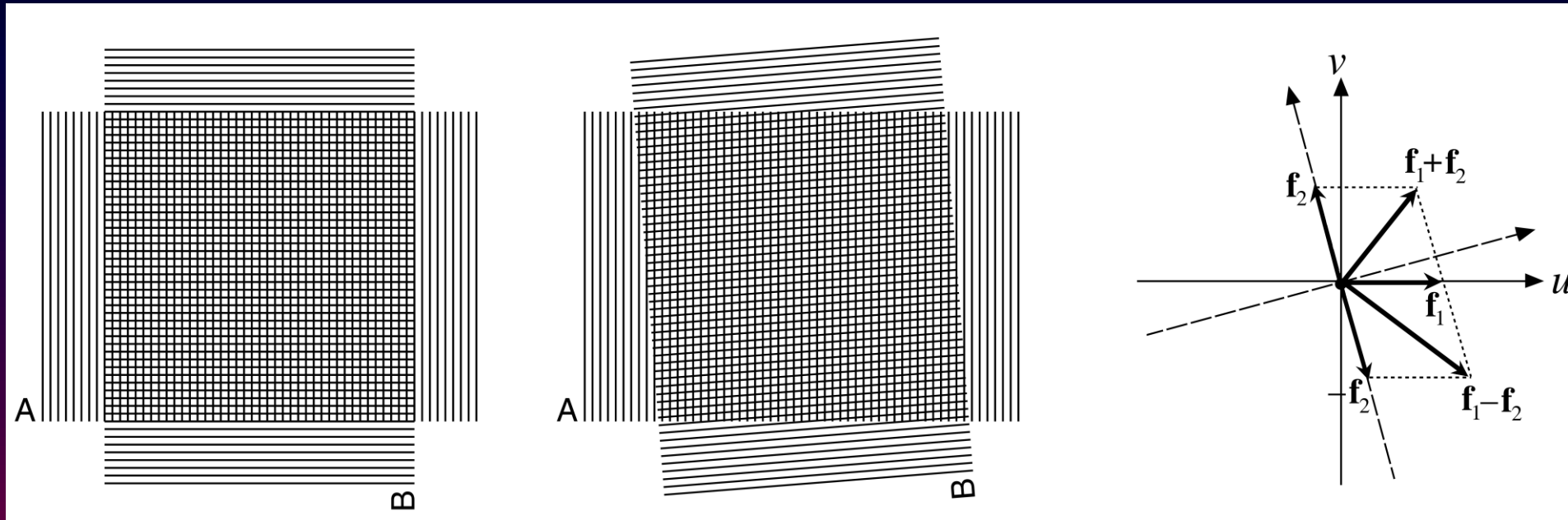
In particular, it may happen that, from the combination of frequencies, a **singular state** appears:

$$\mathbf{f} = \sum_{i=1}^m k_i \mathbf{f}_i = \mathbf{0}$$

Distinguishing stable from unstable or singular states is of utmost importance for Moiré applications or to mitigate Moiré effects.

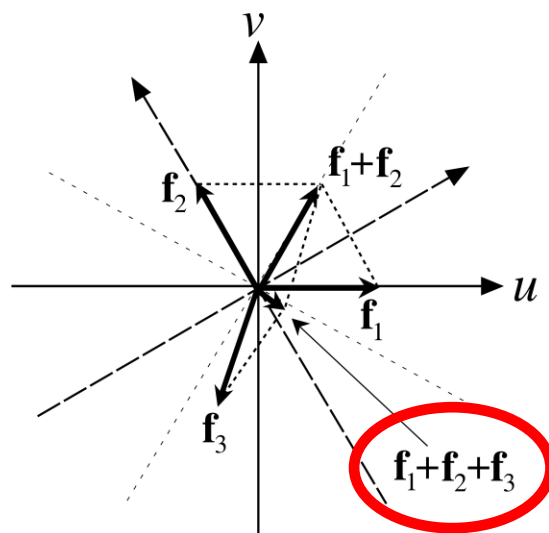
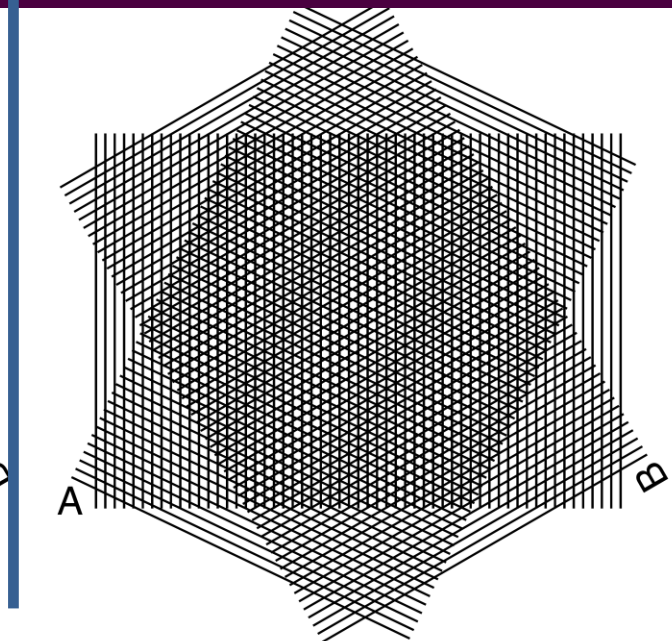
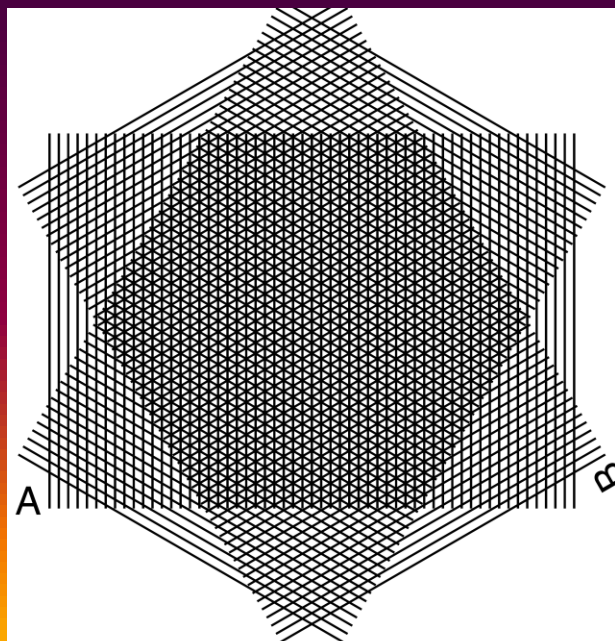
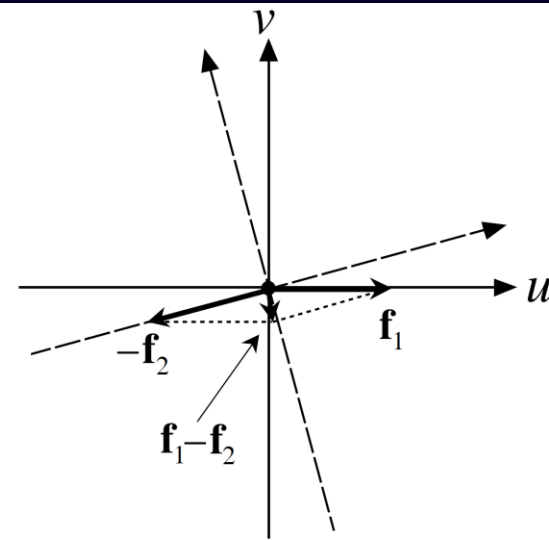
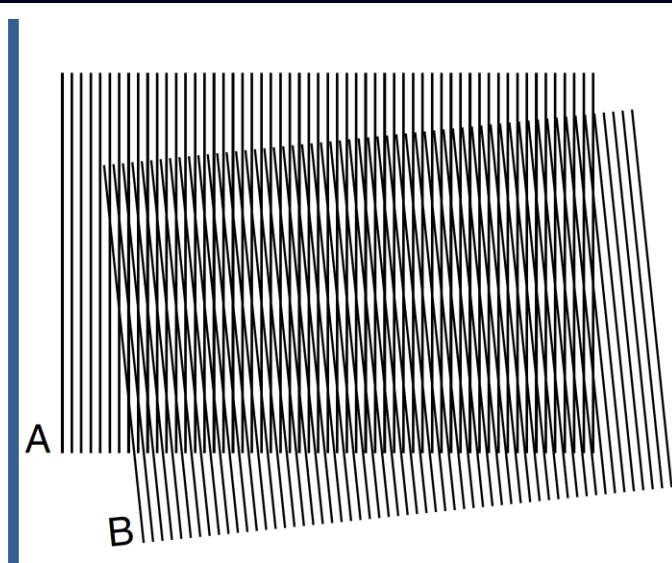
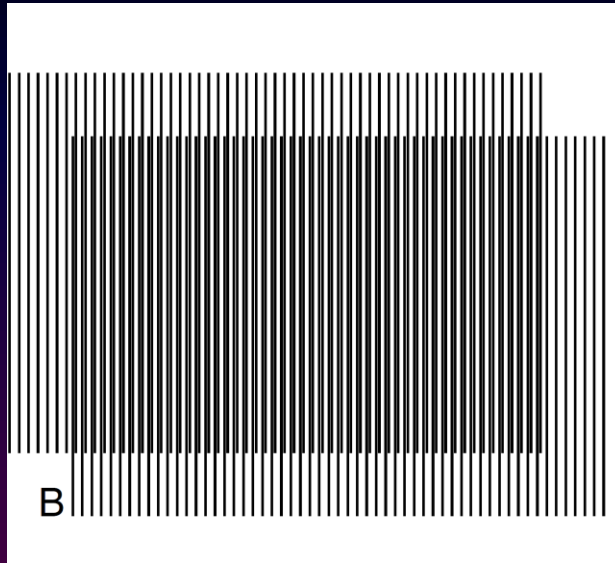
Unstable states ...?

# Stability

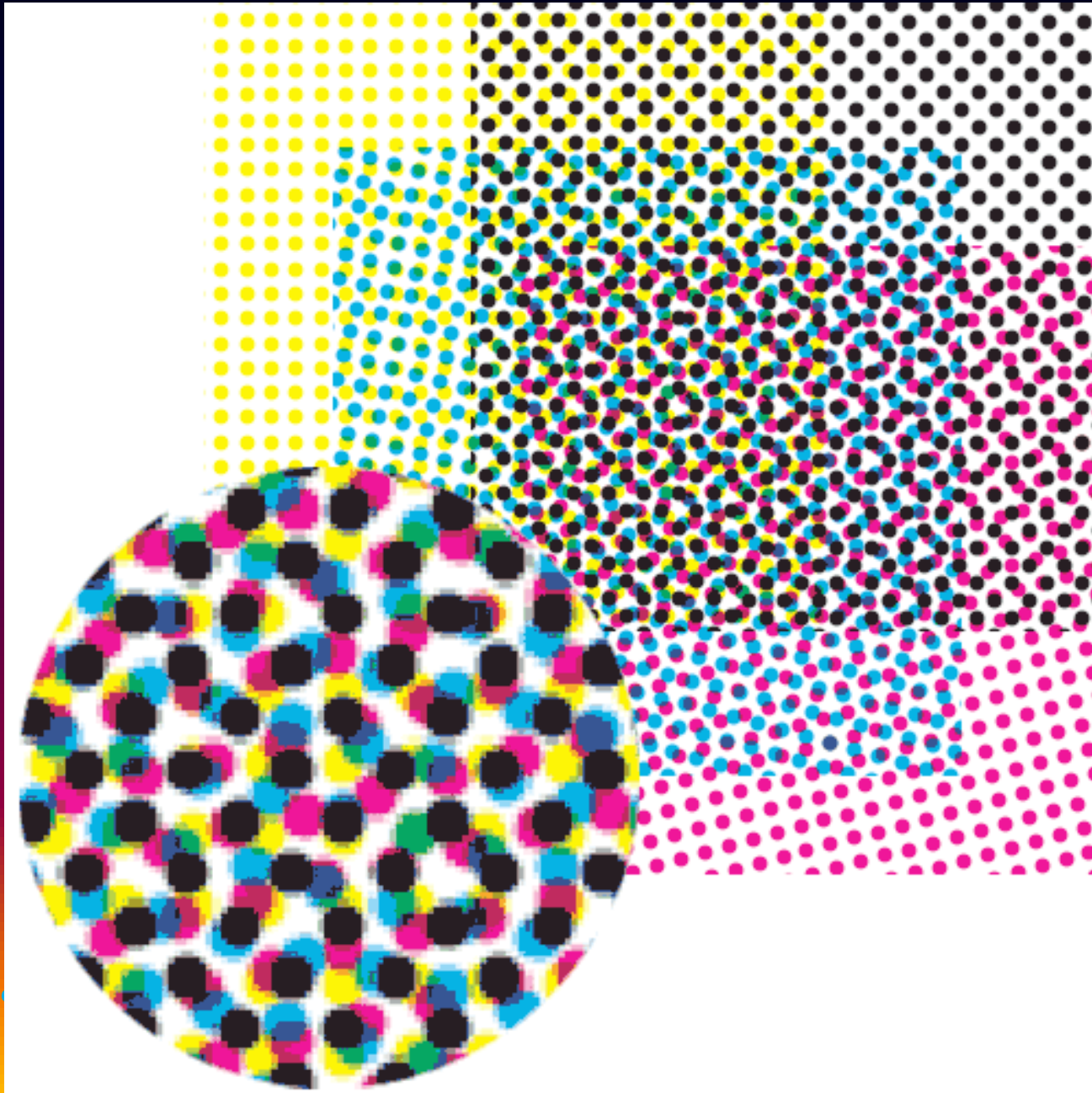




# Instability

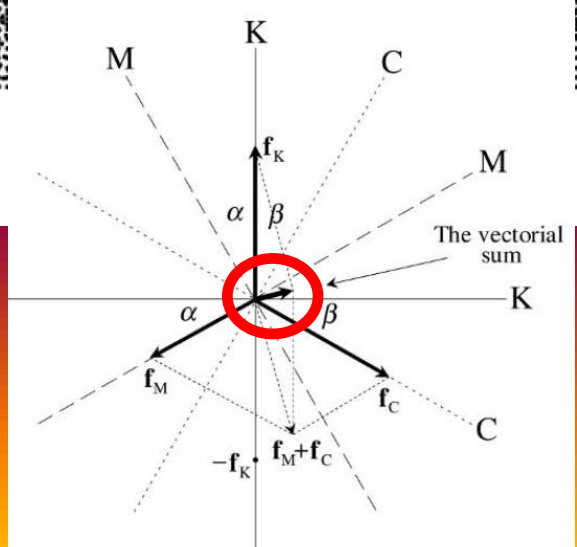
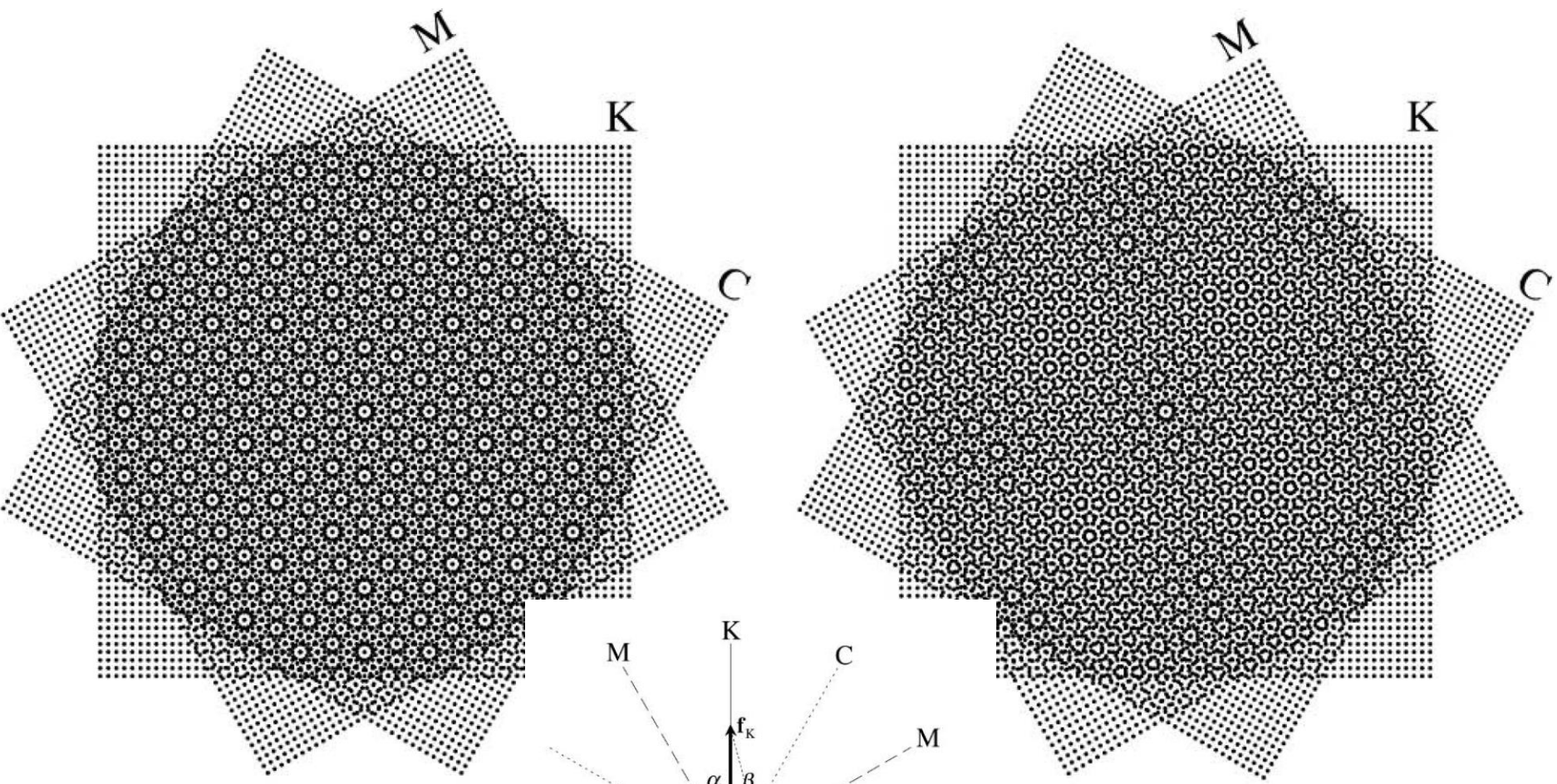


# Printing: 4 meshes, singular state unstable





# Printing: 4 meshes, singular state unstable



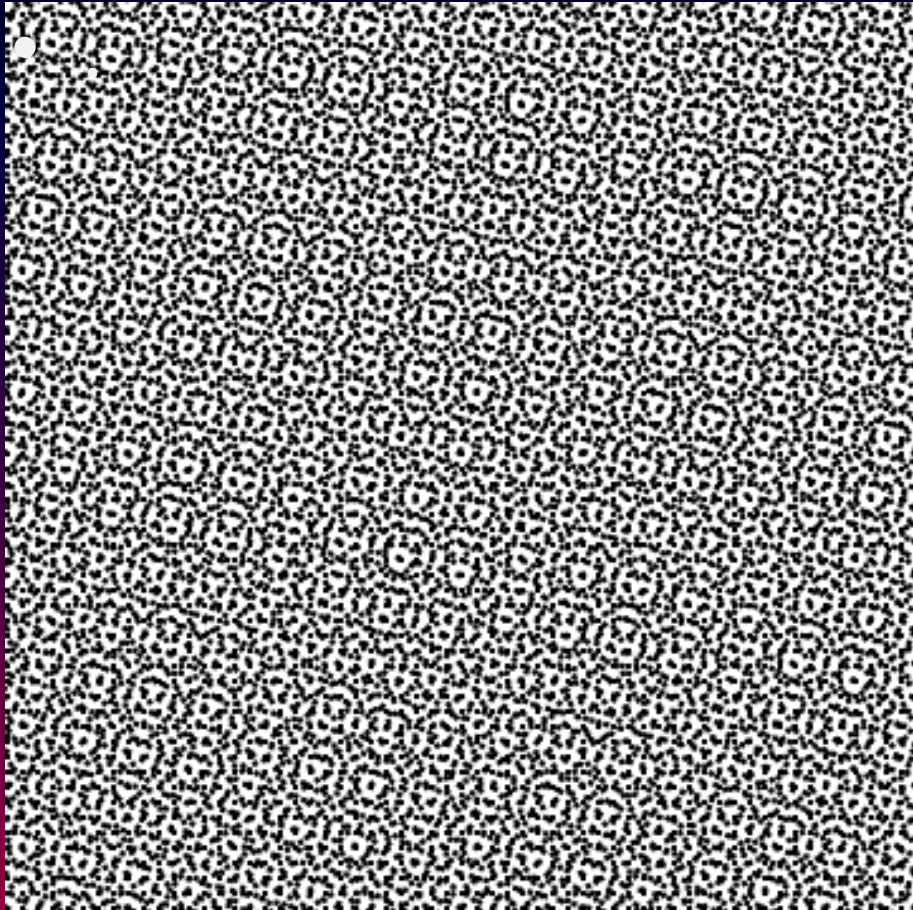
Currently, in industry:  
**M, K, C a 30°**

Other solution →

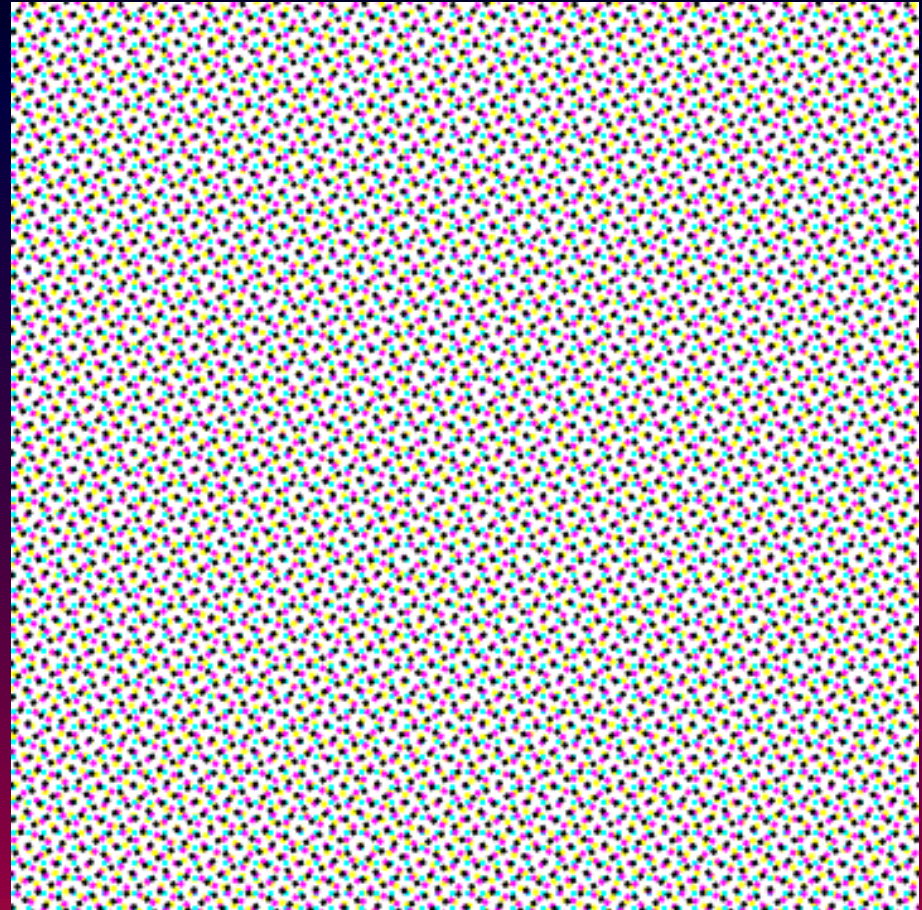


# Printing: 4 meshes, stability point

<http://www.wasatch.com/moire.html>



M, K, C at 30°  
Y at 15°



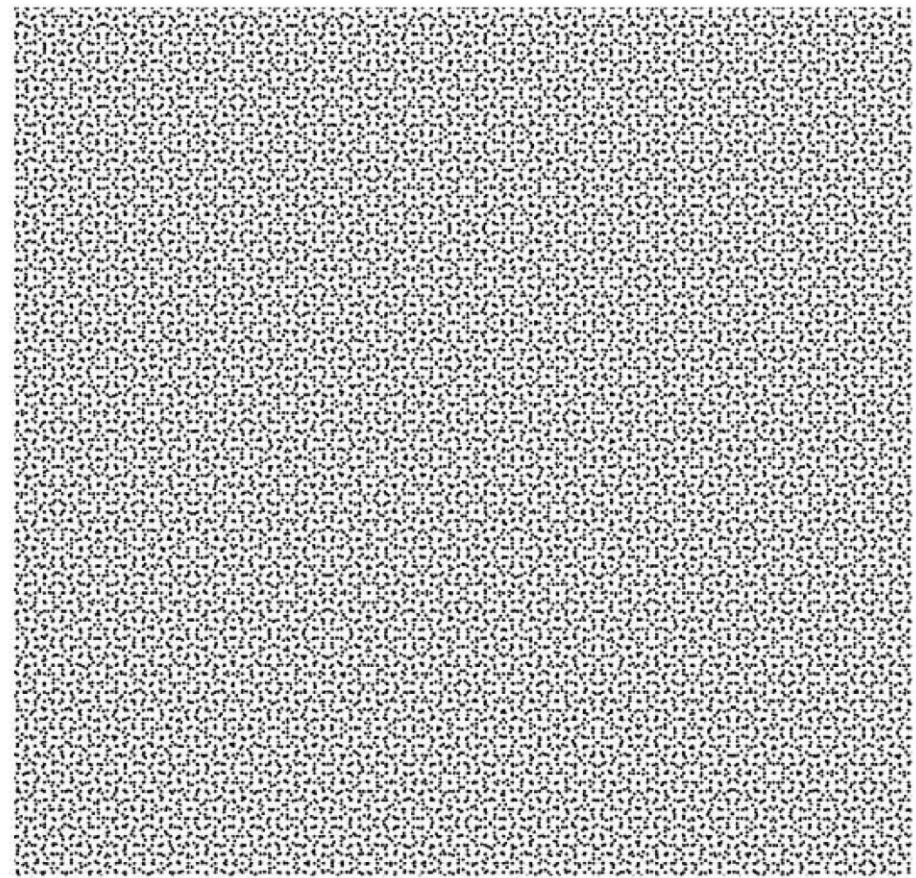
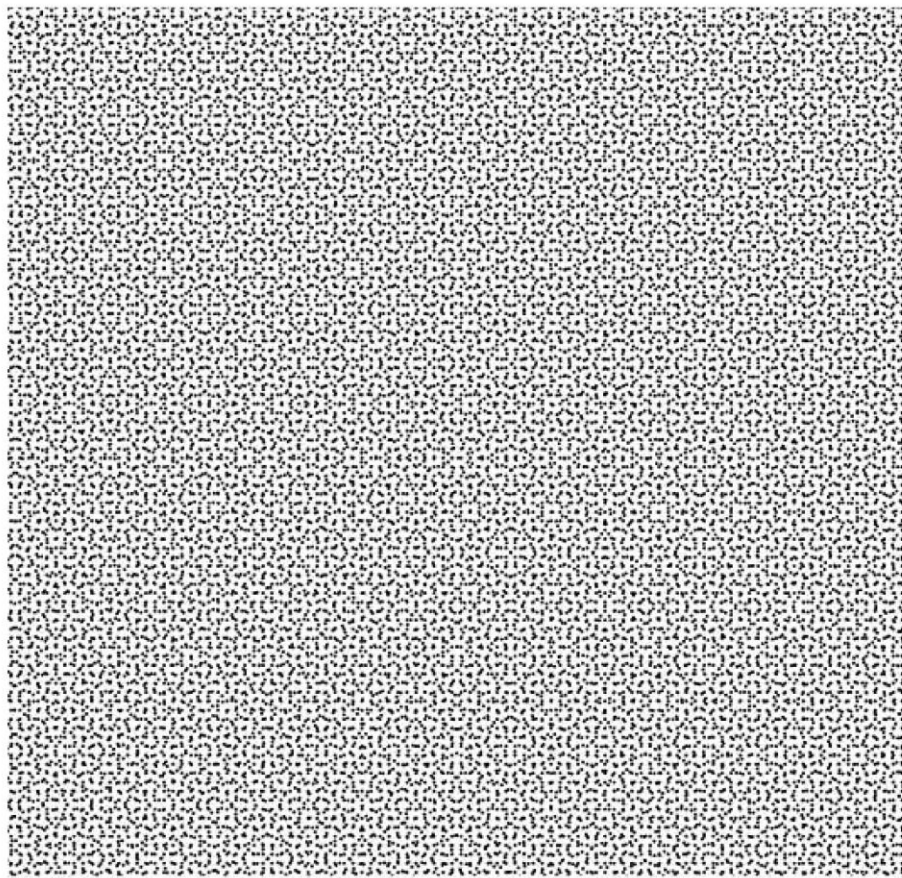
Final result, CMYK

Other solution →





# Printing: 4 meshes, stability point



## Stable point

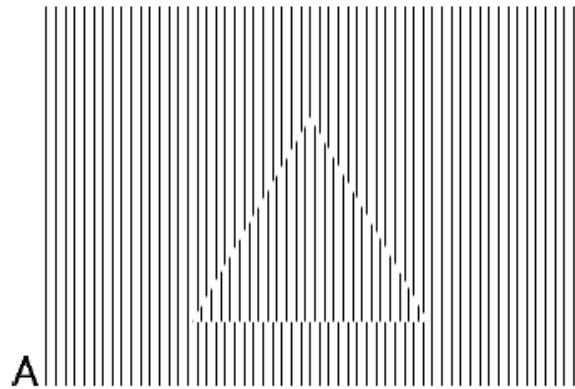
M, K, C at 23.5°, 24°,  
 $q_{MK}=q_{CK}=0.833^\circ$

## Perturbations

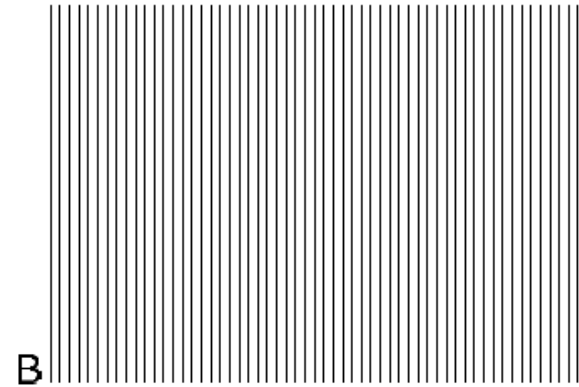
Tiny visual differences

# Security

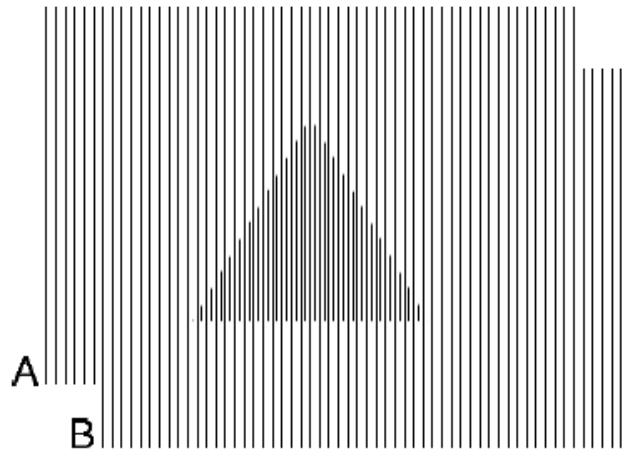
[http://iopscience.iop.org/1742-6596/77/1/012001/pdf/jpconf7\\_77\\_012001.pdf](http://iopscience.iop.org/1742-6596/77/1/012001/pdf/jpconf7_77_012001.pdf)



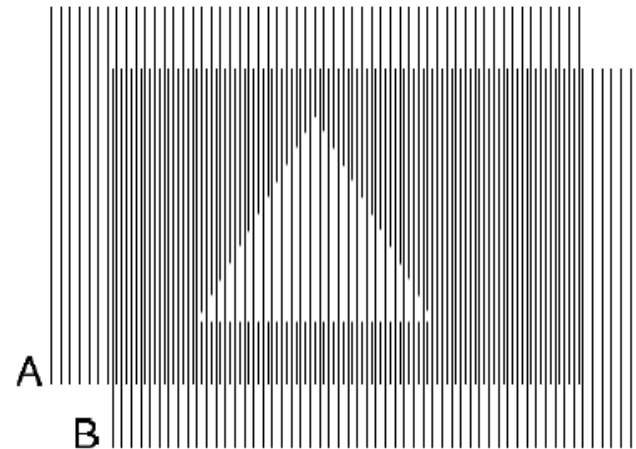
(a)



(b)



(c)



(d)



# Security – Scrambled indicia

<http://sites.google.com/site/stamphiddenimages/Home/stamp-images>



# Security – Scrambled indicia (Estónia)

<http://seguridaddocumental.blogspot.com/2009/10/imagen-encryptada-scrambled-indicia.html>



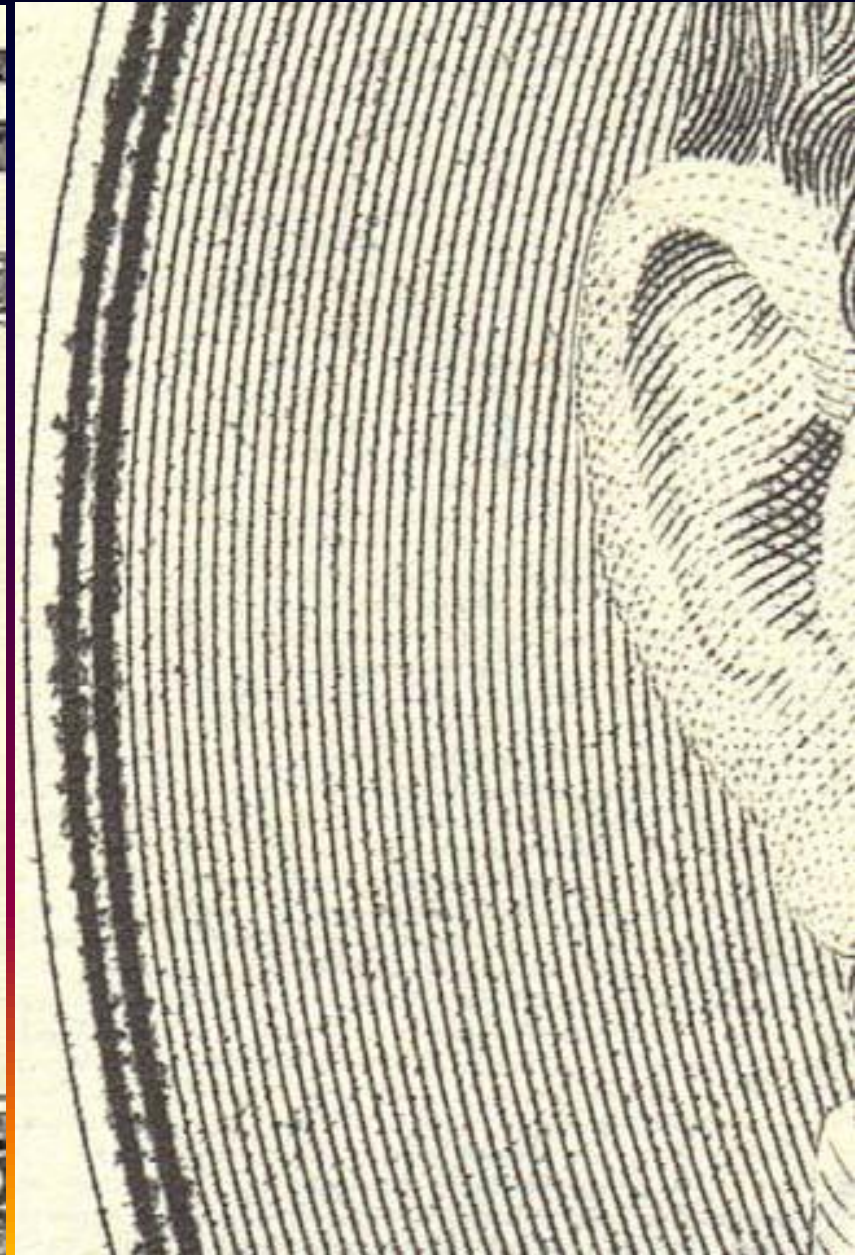
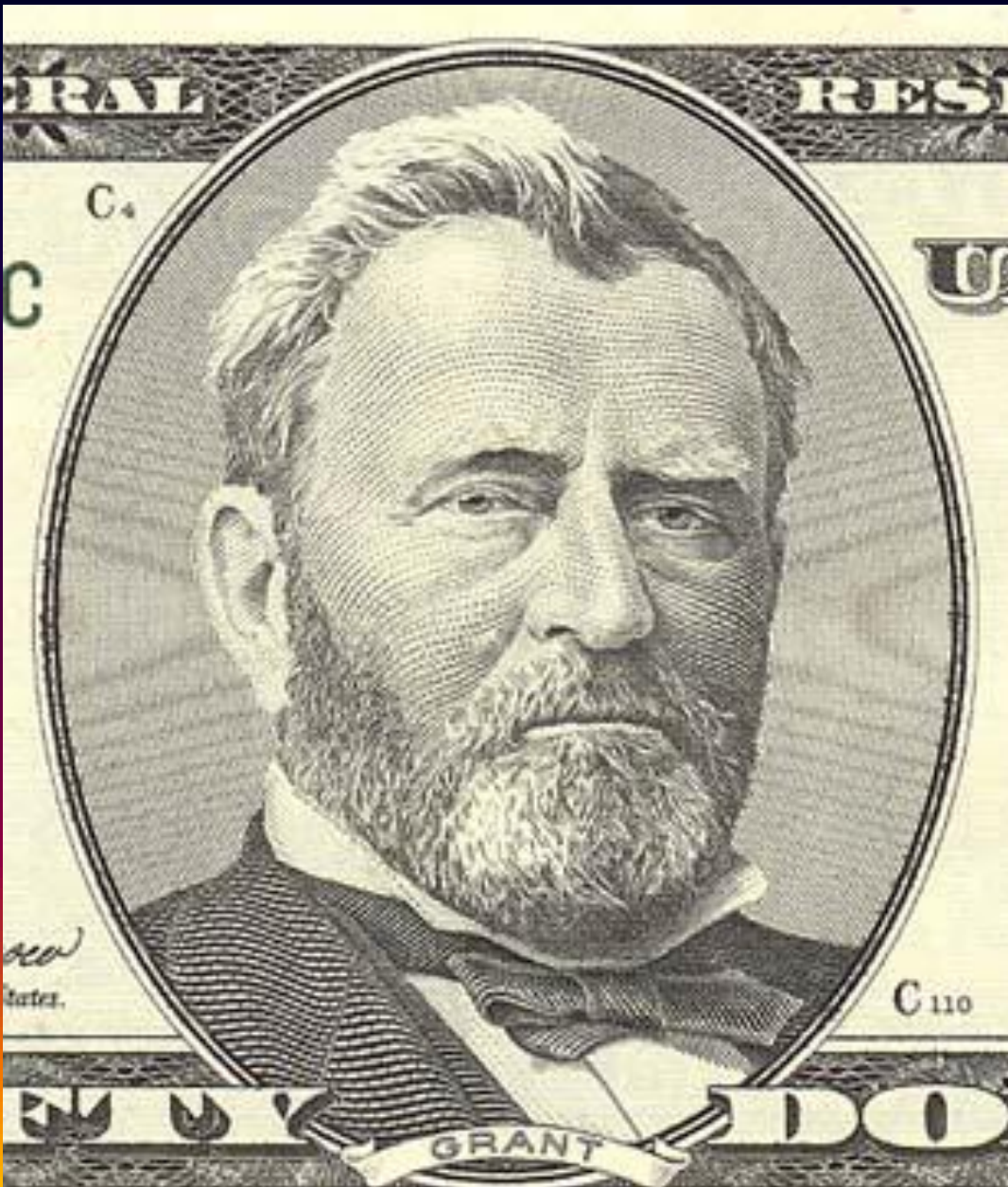




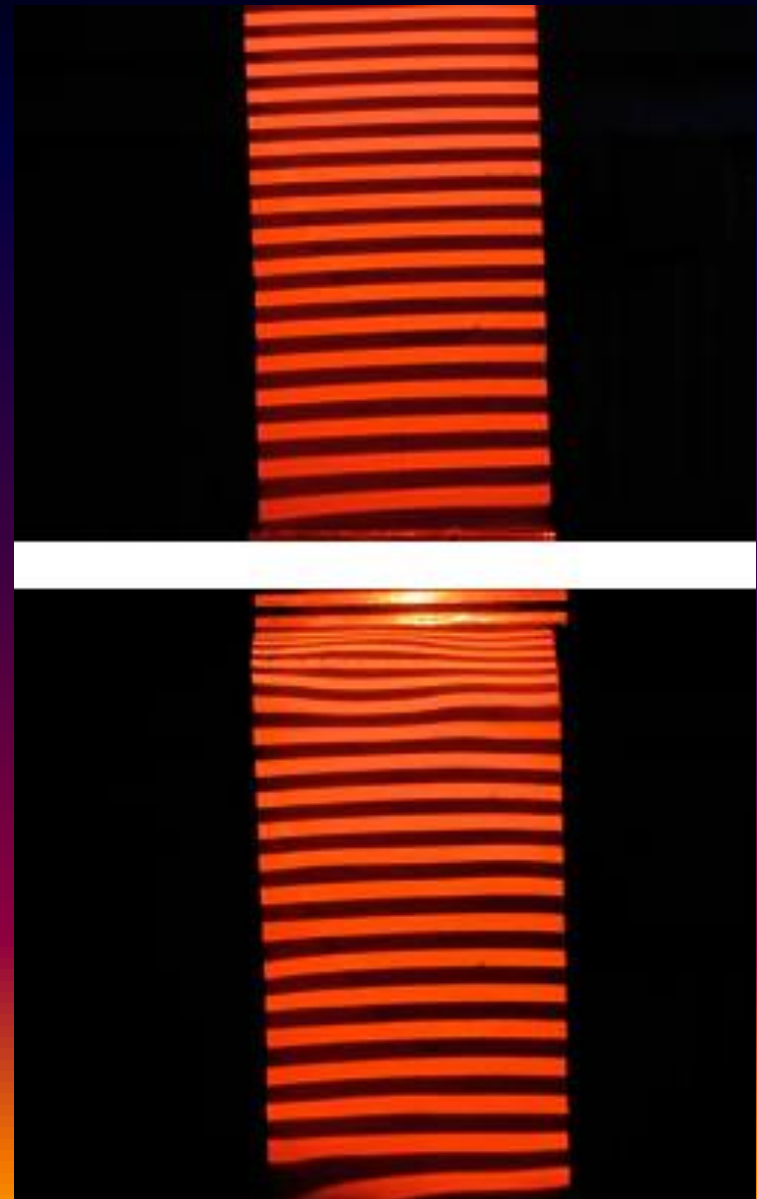
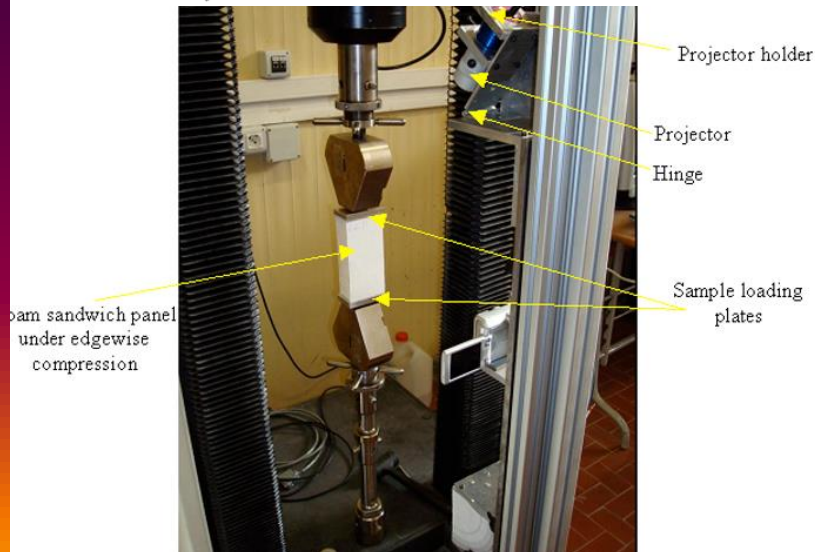
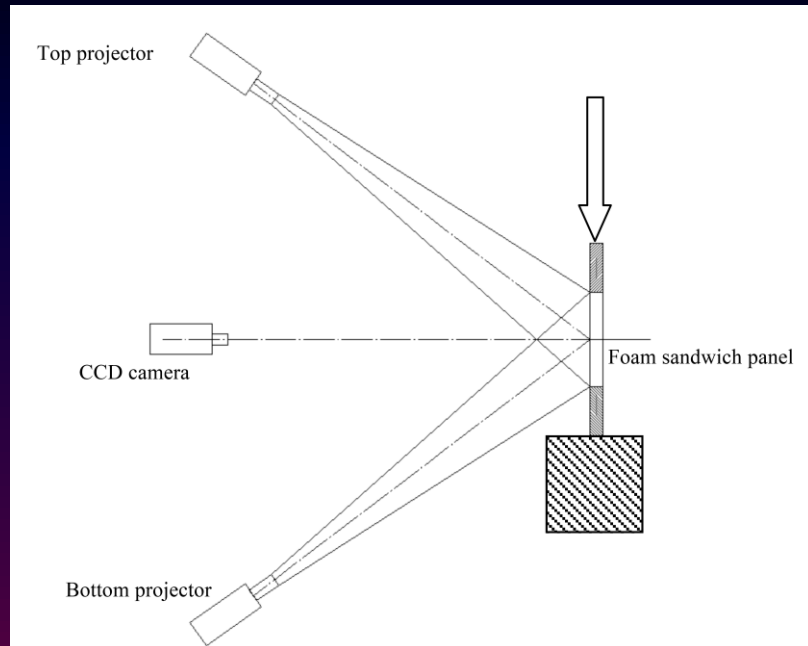


# Security – Screen / scan trap

(USD, President Ulysses S. Grant, 1869-1877)

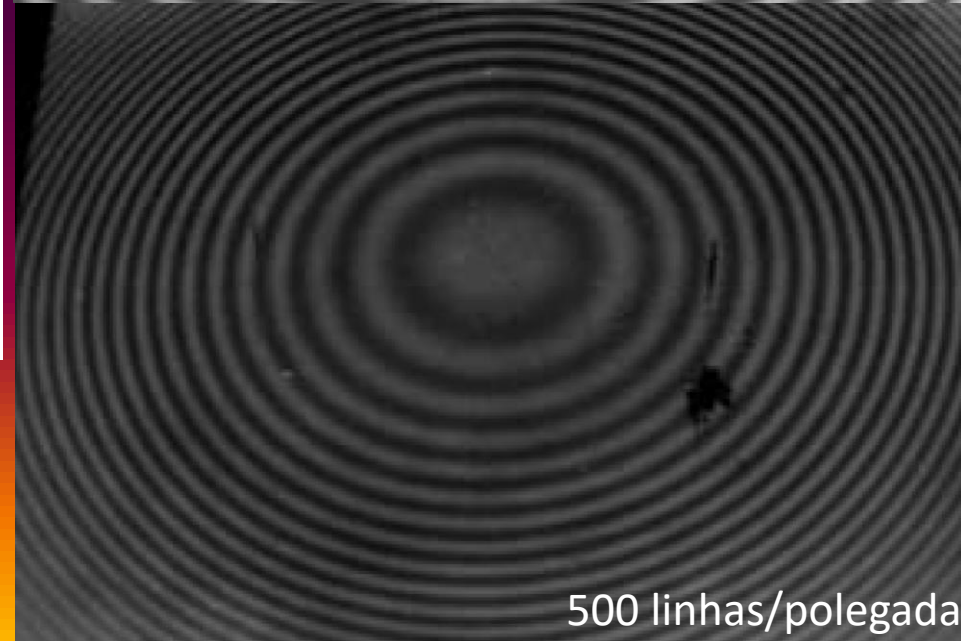
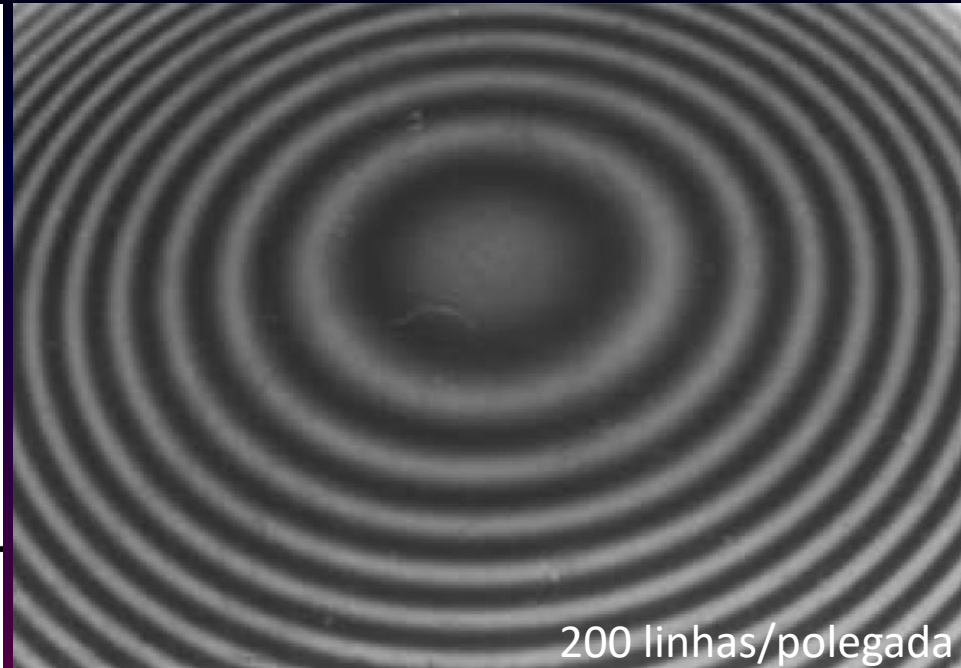
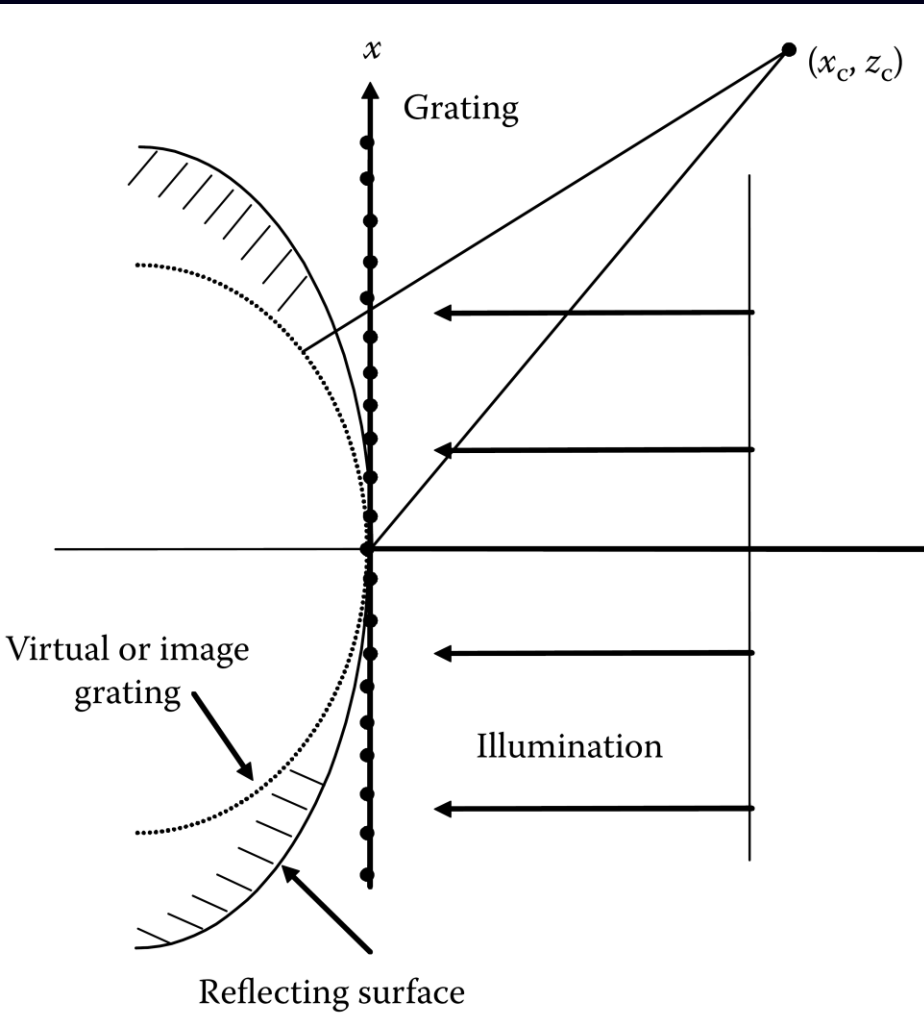


# Moiré – metrology



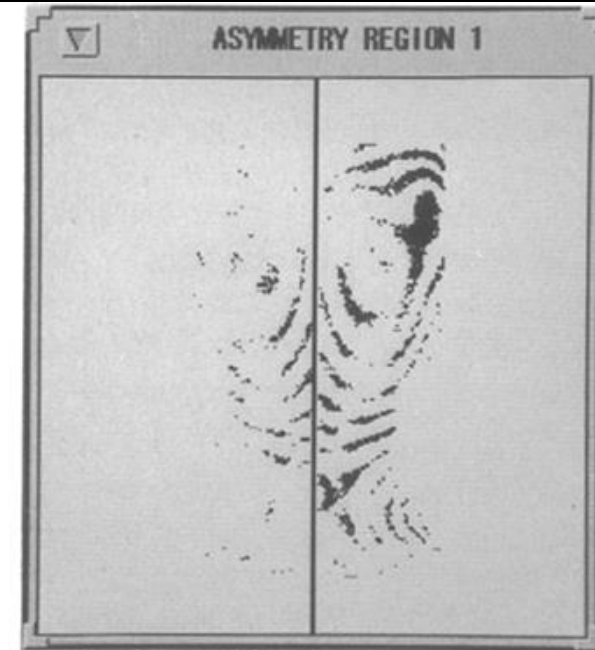
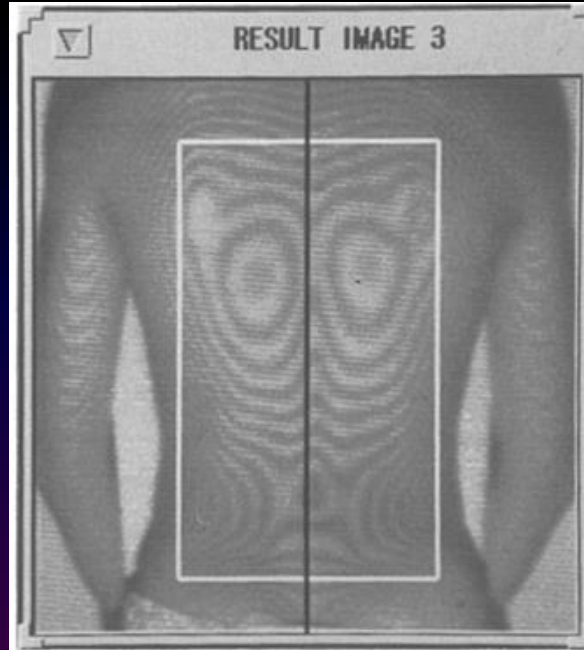


# Moiré – Metrology

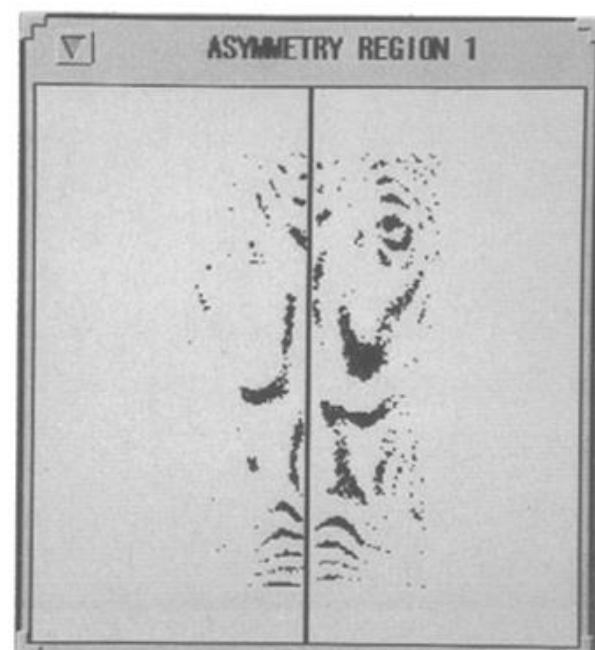
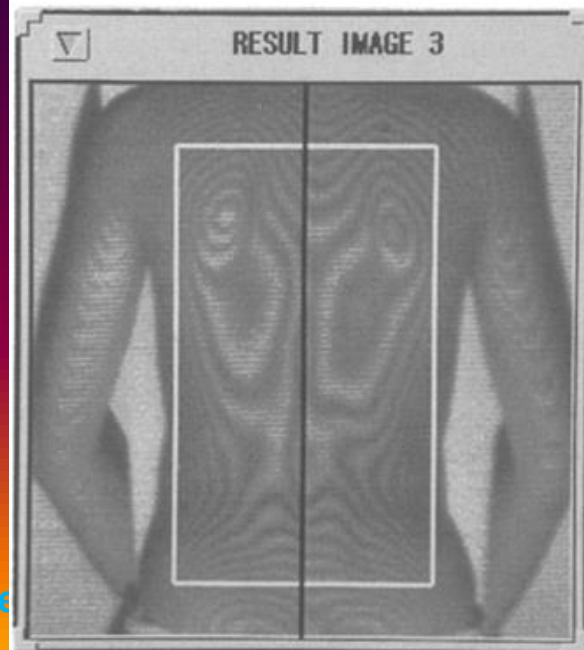




# Moiré - Metrology

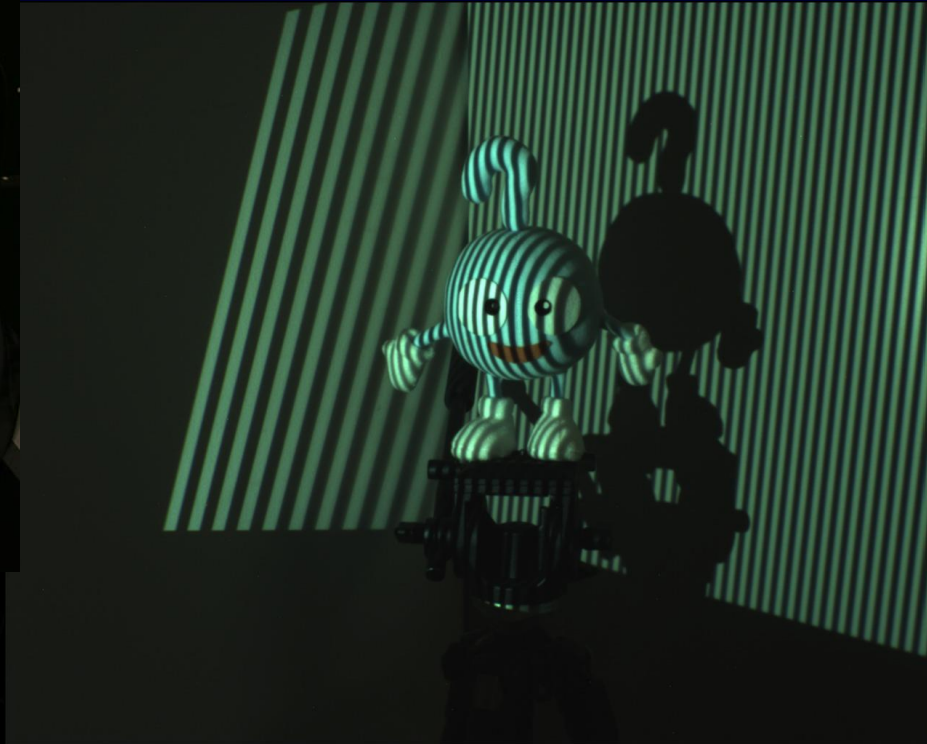
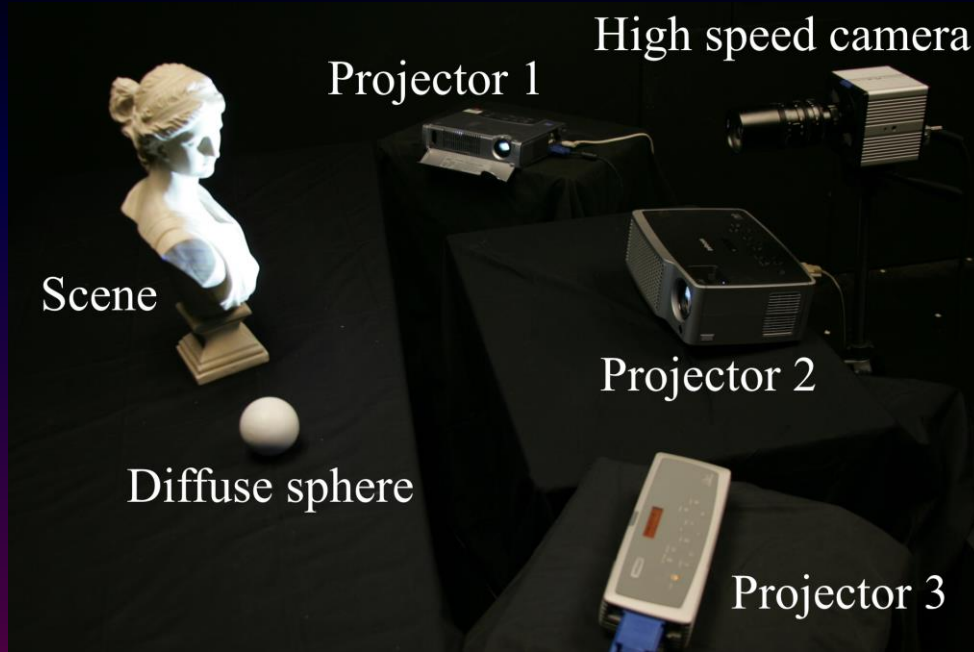


(a)



(b)

# Metrology: structured light

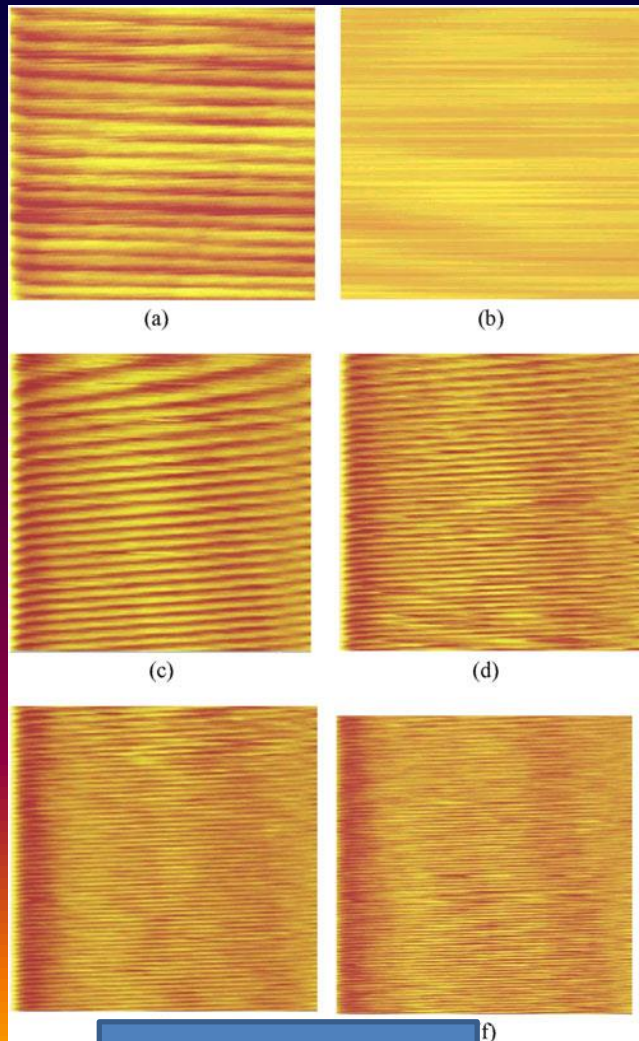


# Materials – surfaces – STM – Pyrolytic Graphite

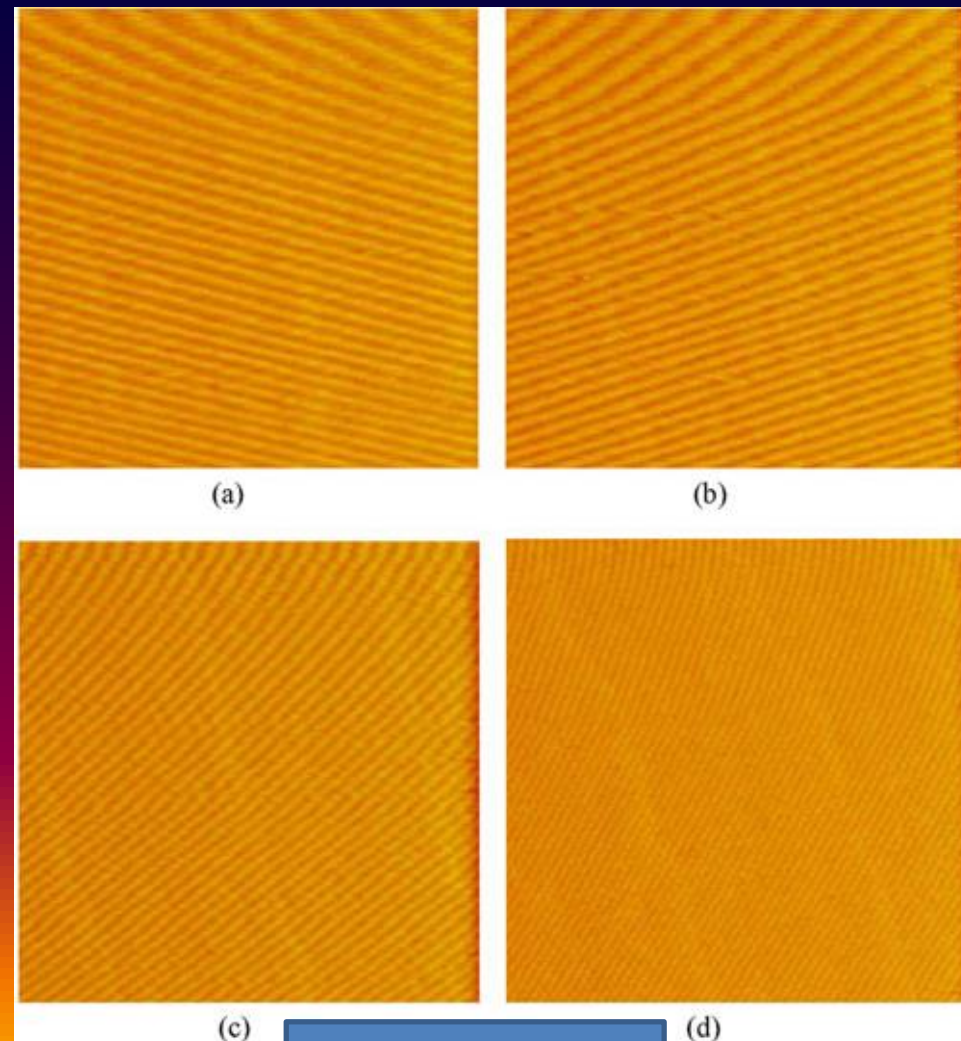
[http://iopscience.iop.org/0957-4484/15/8/022/pdf/nano4\\_8\\_022.pdf](http://iopscience.iop.org/0957-4484/15/8/022/pdf/nano4_8_022.pdf)

Moiré : “interferência” entre a rede atômica e o padrão de varrimento do STM

“Amplifica” as irregularidade da rede comensuráveis com a periodicidade do varrimento



Translations

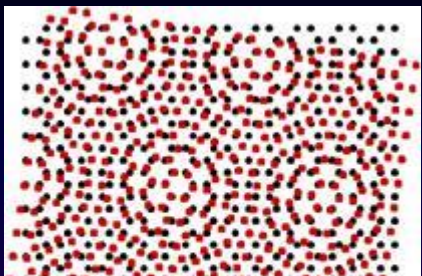


Rotations

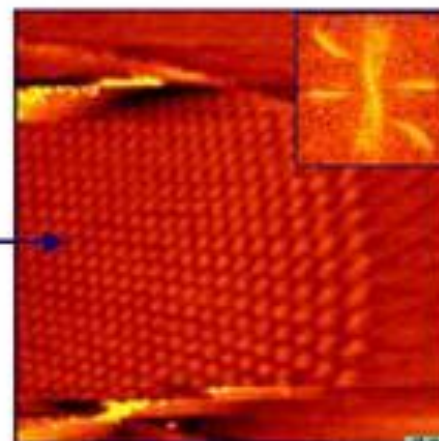
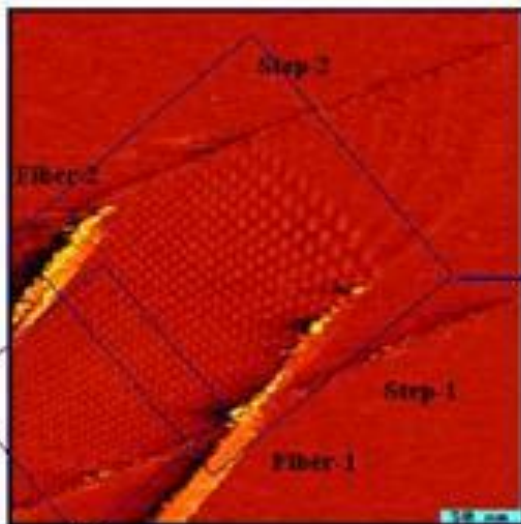
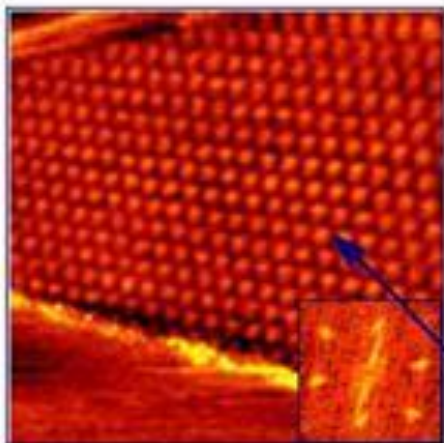


# Materials – surfaces – STM – Pyrolytic Graphite

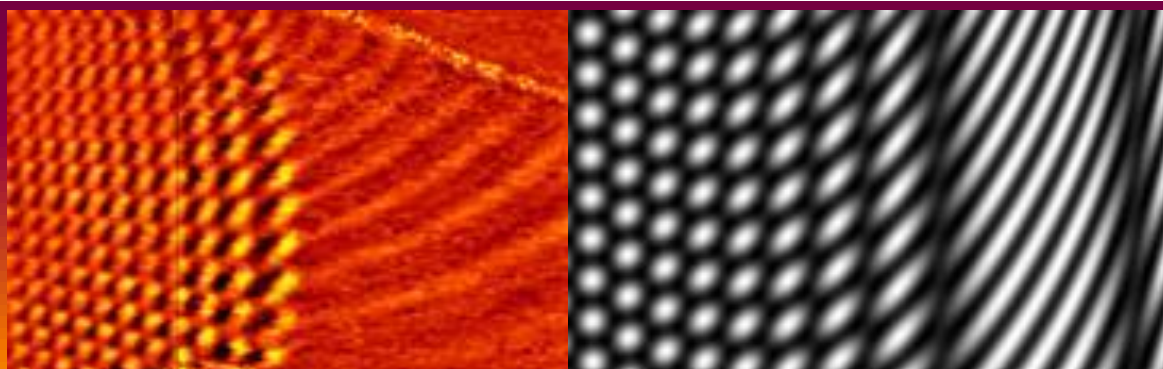
<http://www.iitk.ac.in/infocell/iitk/newhtml/storyoftheweek39.htm>



Padrão gerado por Moiré entre duas redes hexagonais, ligeiramente rodadas: a superficial e outra sub-superficial – período 10-100x superior que a constante de rede



Duas fibras num terraço. Detalhes de duas zonas, com periodicidades variáveis



Observação STM (esquerda), modelo (direita)

As fibras induzem uma pequena rotação de  $2.3^\circ$  no terraço, mas não nas proximidades das fibras



# Conclusions

Physics deals with art of measurement

Measuring means selecting sensors and the sampling strategy

When periodic or completely unknown patterns are at stake ... be careful and try to consider all cases.

Artifacts stemming from measurement processes are needed for industry, commerce and services

**Instabilities** have many applications

**Instabilities** give rise to optical measurement methods

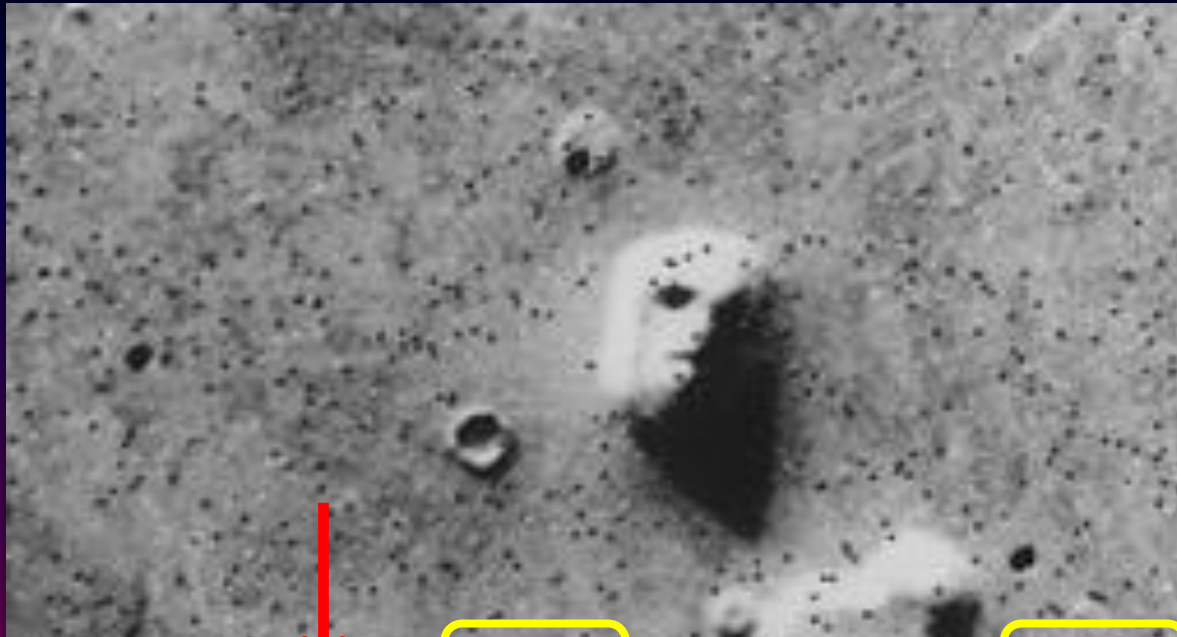
At 1D, engineers call the differences  $f_1 - f_2$  as 'demodulation' and have lots of ways to manipulate them (remember AM e FM modulation in radio...)

Whenever there is a display, a screen, a digital projector, a scanner, a copier, on the imaging chain ... be **CAREFUL!**

**When the object can be anticipated, artefacts are easy to cope with, and the measurement strategy can be fine-tuned**

**If the objects are unknown... Well, nature is often simetric, repetitive... Be careful... Remember the planet Mars in 1976...**

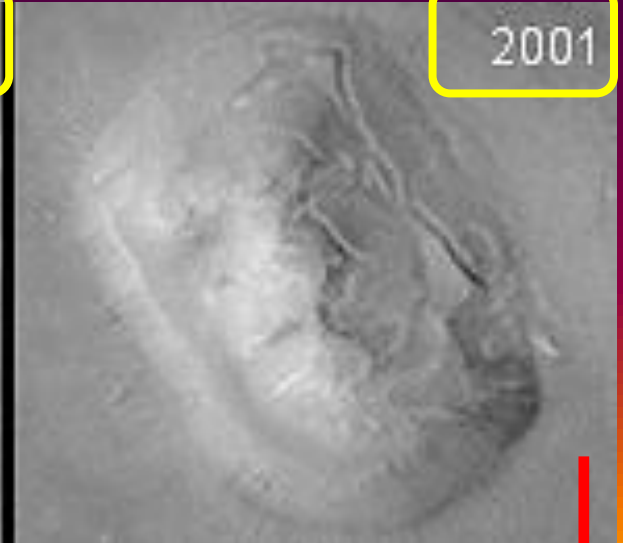
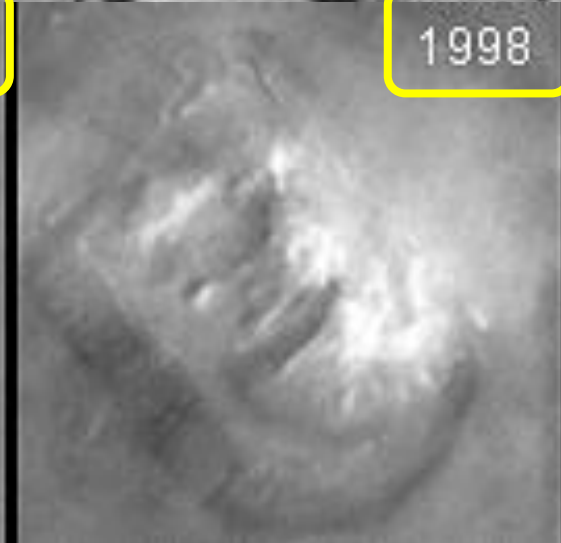
# Face on Mars (1976 → 2001)



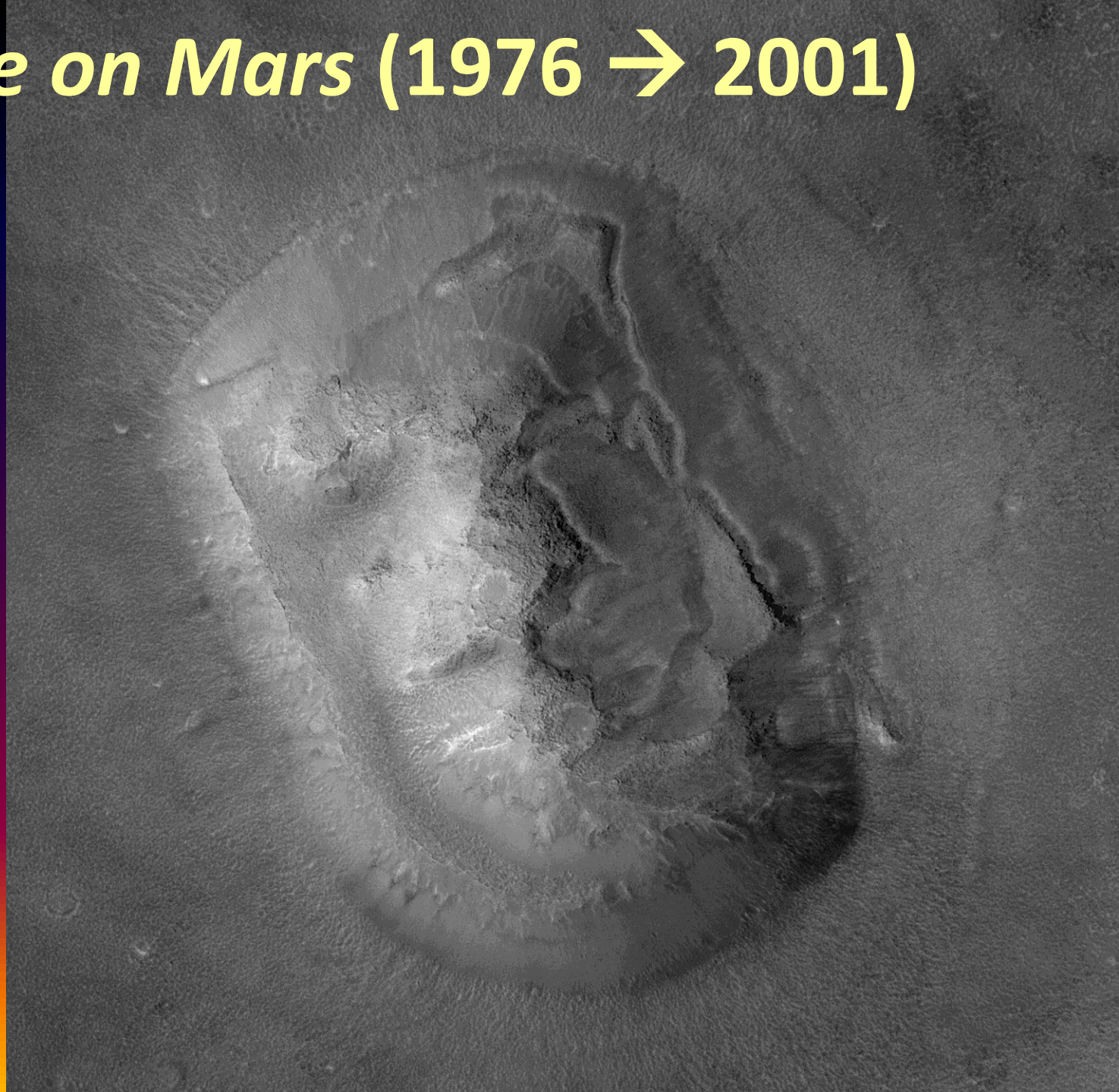
1976

1998

2001



# *Face on Mars (1976 → 2001)*



# The END

Thank you



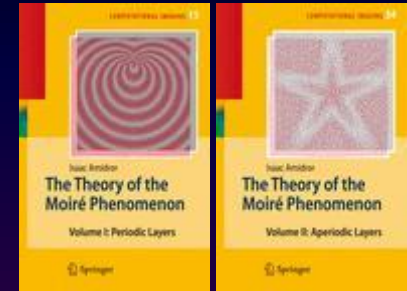
# Bibliography

## **The theory of the Moiré phenomenon: Periodic (I) and Aperiodic (II) layers**

Isaac Amidror

Springer, 2009

<http://diwww.epfl.ch/w3lsp/books//moire>



## **Optical Document Security (2nd ed.)**

Rudolf L. van Renesse (Ed.)

Artech House, 1998

## **Hidden and scrambled images – a review**

Rudolf L. van Renesse

SPIE Vol. 4677, pp. 333-348 (2002)

# Sampling: Moirés & aliasing

- Os problemas de amostragem podem decorrer de:
  - Funções de banda não limitada
    - É o caso, sempre, de funções periódicas...
  - Frequência de amostragem mal escolhida
  - Filtragem passa-baixo do espectro do sinal amostrado incorrecta.
- Estes problemas existem na conversão ADC de
  - Imagens "tramadas" (*halftone screen*) em relação com a
  - Passo de amostragem do sensor (resolução)
- São tipicamente referidos como *aliasing*
- Neste contexto, o aliasing pode ser visto como o caso particular em que
  - $r_1(x,y)$  representa a reflectância da imagem inicial
  - $r_2(x,y)$  representa o pente 2D que descreve o dispositivo de amostragem
- Da convolução entre os espectros decorre a existência de múltiplas réplicas de  $R_1(u,v)$ , cada uma das quais centrada em cada um dos impulsos de  $R_2(u,v)$ .
- Se a frequência de amostragem  $f < 2f_{\max}$ , existe sobreposição entre réplicas de  $R_1(u,v) \rightarrow$  altas frequências das réplicas sobrepõem-se (aditivamente) à réplica central de  $R_1(u,v)$ , aumentando a energia das baixas frequências ou criando artefactos de baixa frequência não existentes em  $r_1(x,y)$ .
- A filtragem passa-baixo não permite a reprodução fiel do sinal

# Sampling: Moirés & aliasing

- If  $R_1(u,v)$  decreases fast (although not being band-limited) aliasing imposes slight degradations: loss of high frequency details, degradation of contours, ...
- If the signal is periodic or if it contains periodic patterns, its spectrum  $R_1(u,v)$  and its replications after convolution, may contain intense pulses, some of them, eventually, within the visibility circle, and generating artifacts which do not exist in the original signal.
- Classical sampling theory addresses
  - Continuous spectra and band-limited images
- Na approach based on Moiré enables sampling of
  - Periodic signals
- ...and frequencies smaller than Nyquist can be used provided unwelcome frequencies are outside the visibility circle.
  - Although spectral superposition forbids the reconstruction of  $r_1(x,y)$ , this does not necessarily create artifacts (moiré)
- Anti-aliasing: removal, by low-pass filtering, of high-frequency details, impossible to resolve by the sampling system.



# http://www.imageprocessingbasics.com/image-sampling-and-aliasing/

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Explains the Rayleigh spatial resolution limit.
- [Sampling and aliasing](#)  
See how different sampling resolutions can cause aliasing, and how to do anti-aliasing.
- [Pixel re-quantization](#)  
Explore in real time the effects of changing the number of pixel quantization levels.
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See the effects of varying the parameters in the affine geometric transform.
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Interactively explore the effect of changing the parameters in graylevel transform functions.
- [Histogram equalization](#)  
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### Sampling and (anti)aliasing

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Show sampling points

Apply anti-aliasing

Adjust sampling resolution:

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#### Short tutorial

A typical approach of storing an image digitally on a computer, is by sampling the image at a rectangular grid. The color, or intensity, at each of these points is converted into a numeric value and stored in the computer. Apart from the color/intensity at those specific points, everything else is discarded when the image is stored in the computer.

When displaying this digital image, we again form a continuous image by interpolating between the stored samples. One way to do the interpolation is to say that for every ('continuous') point, we merely choose the value at the closest sample. This is known as nearest neighbor interpolation and causes each digital image sample to be drawn on screen as a sharply defined pixel. Higher order interpolation cause continuous, smooth, or more 'natural' looking images.

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### Sampling and (anti)aliasing

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Adjust sampling resolution:

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#### Short tutorial

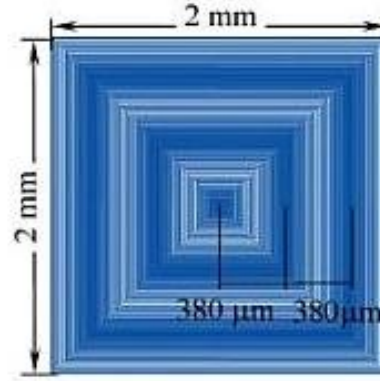
A typical approach of storing an image digitally on a computer, is by sampling the image at a rectangular grid. The color, or intensity, at each of these points is converted into a numeric value and stored in the computer. Apart from the color/intensity at those specific points, everything else is discarded when the image is stored in the computer.

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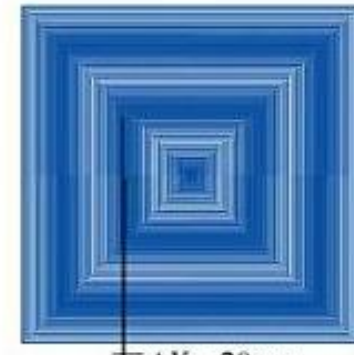
# Alignments

## Masks in integrated circuits

## Offset printing plates

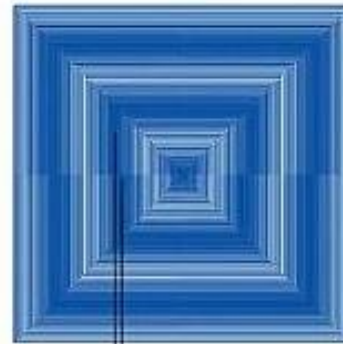


(a)

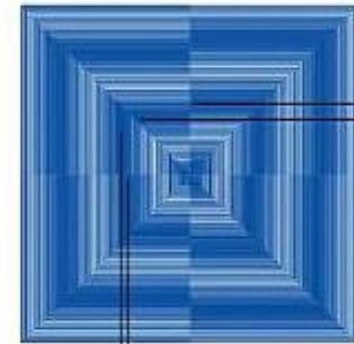


(b)

1 μm



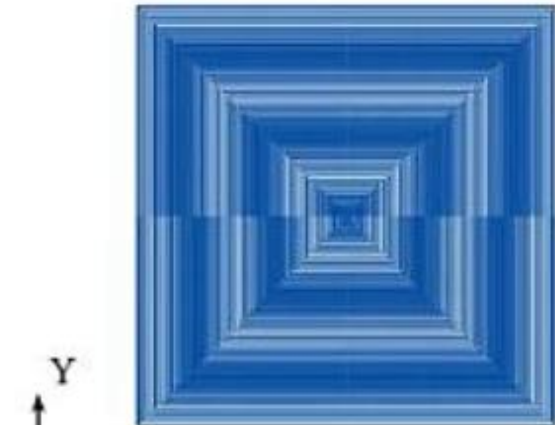
(c)



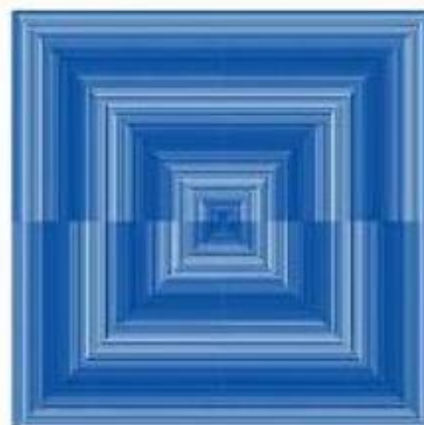
$\Delta x = 1 \mu\text{m}$   
 $\Delta y = 2 \mu\text{m}$

$\Delta x = \pm 2 \mu\text{m}$

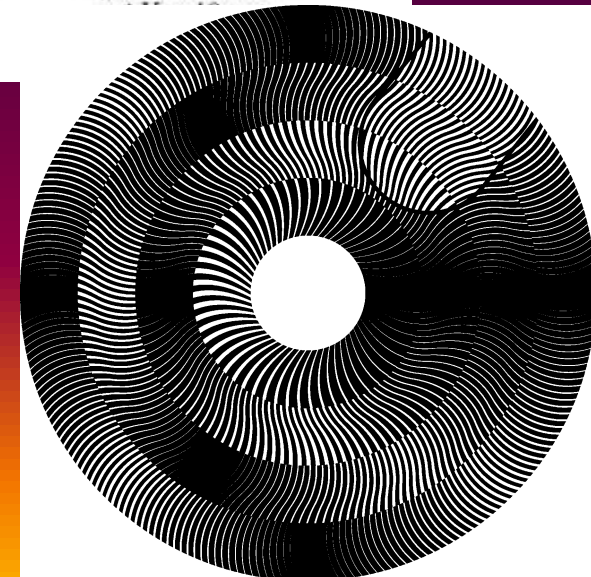
[http://books.google.pt/books?id=n-xkaj7SWD0C&pg=PA539&dq=alignment+moir%C3%A9&hl=pt-PT&ei=W9PLTrakNoGL8gO9oLnKDw&sa=X&oi=book\\_result&ct=result&resnum=1&ved=0CC4Q6AEwAA#v=onepage&q=alignment+moir%C3%A9&f=false](http://books.google.pt/books?id=n-xkaj7SWD0C&pg=PA539&dq=alignment+moir%C3%A9&hl=pt-PT&ei=W9PLTrakNoGL8gO9oLnKDw&sa=X&oi=book_result&ct=result&resnum=1&ved=0CC4Q6AEwAA#v=onepage&q=alignment+moir%C3%A9&f=false)



(a)



(b)





# Test targets or holograms?

Zoneplate Chart 16:9 x1=1920x1080 max.freq., x2, x4

(c) Falk Lumo

